

Ulyxes: an open source project for automation in engineering surveying

Ulyxes is an open source project to drive robotic total stations as well as other sensors, collect their measurements in database and finally publish the results for authorized users on the web. On special requests the results are also presented with web based maps in the background. This project is like an instant coffee: three in one (coffee, sugar and milk). The coffee and the strongest part is the research and coding. The sugar is the application of the program in industrial environment and the milk on the top is the educational usage. The software development started in 2008 connected to a monitoring task in the Hungarian Nuclear Power Plant. Since then the development has been extended from total stations to different positioning capable sensors. In 2012 the development of a new Python based object oriented framework started. The code is based on the results of some other open source projects, Python, PySerial, GNUGama, SQLite, OpenCV, etc. After connecting to the international Geo4All network in 2014, Ulyxes became a project of our Geo4All Lab. The project has its own home page (<http://www.agt.bme.hu/ulyxes>) and the source code is available on the GitHub portal (<https://github.com/zsiki/ulyxes>). The code is maintained by the colleagues at the Department of Geodesy and Surveying at the Budapest University of Technology, volunteers from all over the World are welcome. BSc and MSc students are also involved in the development and testing. More theses were connected to this project in the recent five years. In the curriculum of an MSc subject called Surveying Automation, Ulyxes is used to demonstrate automatized tasks in engineering surveying. The system has been applied for several projects during the last 10+ years. Typical applications are the load tests of bridges and other engineering structures and on the other hand Ulyxes can be used to monitor the movements of buildings in the nearby of constructional works, like metro stations, underground garage and other buildings as well. Raspberry Pi small, single board computers are used with Raspbian operating system during on-site works.

The source code is divided into three parts. The first one is the Ulyxes API which is the core of the system. The second one, Ulyxes Apps is a collection of applications based upon the API. Some of them were developed by our students. The third part is the server side scripts to publish observation results through the Internet. Moreover it is also planned to implement SOS standard using IstSOS. Our Geo4All Lab maintains another open source software, called GeoEasy to process observation data in engineering and land surveying. A closer cooperation is also planned between our two open source projects. In this paper the most important features of Ulyxes will be presented with examples, an actual monitoring project in Budapest and test loads of bridges and overpasses.

1 Ulyxes: an open source project for 2 automation in engineering surveying

3 Zoltán Siki¹, Bence Takács², and Csaba Égető³

4 ¹Department of Geodesy and Surveying, Budapest University of Technology and
5 Economics, Hungary

6 ²Department of Geodesy and Surveying, Budapest University of Technology and
7 Economics, Hungary

8 ³Department of Geodesy and Surveying, Budapest University of Technology and
9 Economics, Hungary

10 Corresponding author:

11 Zoltán Siki¹

12 Email address: siki.zoltan@epito.bme.hu

13 ABSTRACT

14 Ulyxes is an open source project (<http://www.agt.bme.hu/ulyxes/>) to drive robotic total stations as well as
15 other sensors, collect their measurements in database and finally publish the results for authorized users
16 on the web. On special requests the results are also presented with web based maps in the background.
17 This project is like an instant coffee: three in one (coffee, sugar and milk). The coffee and the strongest
18 part is the research and coding. The sugar is the application of the program in industrial environment and
19 the milk on the top is the educational usage.

20 The software development started in 2008 connected to a monitoring task in the Hungarian Nuclear
21 Power Plant. Since then the development has been extended from total stations to different positioning
22 capable sensors. In 2012 the development of a new Python based object oriented framework started.
23 The code is based on the results of some other open source projects, Python, PySerial, GNUGama,
24 SQLite, OpenCV, etc. After connecting to the international Geo4All network in 2014, Ulyxes became a
25 project of our Geo4All Lab (<http://www.agt.bme.hu/osgeolab/index.php?page=start&lang=en>).

26 The project has its own home page (<http://www.agt.bme.hu/ulyxes>) and the source code is available
27 on the GitHub portal (<https://github.com/zsiki/ulyxes>). The code is maintained by the colleagues at the
28 Department of Geodesy and Surveying at the Budapest University of Technology, volunteers from all over
29 the World are welcome. BSc and MSc students are also involved in the development and testing. More
30 diploma works were connected to this project in the recent five years. In the curricula an MSc subject
31 called Surveying Automation, Ulyxes is used to demonstrate automatized tasks in engineering surveying.
32 The system has been applied for several projects during the last 10+ years. Typical applications are
33 the load tests of bridges and other engineering structures and on the other hand Ulyxes can be used to
34 monitor the movements of buildings in the nearby of constructional works, like metro stations, underground
35 garage and other buildings as well. Raspberry Pi Grimmert (2014) small, single board computers are
36 used with Raspbian operating system during on-site works.

37 The source code is divided into three parts. The first one is the Ulyxes API which is the core of the system.
38 The second one, Ulyxes Apps is a collection of applications based upon the API. Some of them were
39 developed by our students. The third part is the server side scripts to publish observation results through
40 the Internet. This part is unfortunately the weakest one of the project. Most of the new developments
41 should be carried on here. Moreover it is also planned to implement SOS standard using IstSOS. Our
42 Geo4All Lab maintains another open source software, called GeoEasy (<https://github.com/zsiki/GeoEasy>)
43 to process observation data in engineering and land surveying. A closer cooperation is also planned
44 between our two open source projects.

45 In this paper the most important features of Ulyxes will be presented with examples, an actual monitoring
46 project in Budapest and test loads of bridges and overpasses.

47 INTRODUCTION TO ULYXES

48 Ulyxes is an open source project (<http://www.agt.bme.hu/ulyxes/>) to drive robotic total stations as well as
49 other sensors, collect their measurements in database and finally publish the results for authorized users
50 on the web. On special requests the results are also presented with web based maps in the background.

51 This project is like an instant coffee: three in one (coffee, sugar and milk). The coffee (the strongest
52 part) is the research and coding. The sugar is the application of the program in industrial environment and
53 the milk on the top is the educational usage.

54 The software development started in 2008 connected to a monitoring task in the Hungarian Nuclear
55 Power Plant. Since then the development has been extended from total stations to different positioning
56 capable sensors (Hillar, 2016). In 2012 the development of a new Python based object oriented framework
57 started. The code is based on the results of some other open source projects, Python, PySerial, GNUGama,
58 SQLite, OpenCV, etc. After connecting to the international Geo4All network in 2014, Ulyxes became a
59 project of our Geo4All Lab (<http://www.agt.bme.hu/osgeolab/index.php?page=start&lang=en>).

60 The project has its own home page (<http://www.agt.bme.hu/ulyxes>) and the source code is available
61 on the GitHub portal (<https://github.com/zsiki/ulyxes>). The code is maintained by the colleagues at
62 the Department of Geodesy and Surveying at the Budapest University of Technology and Economics,
63 volunteers from all over the World are welcome.

64 METHODS

65 The source code is divided into three parts. The first one is the Ulyxes API which is the core object library
66 of the system. This is useful only for programmers. The second one, Ulyxes Applications is a collection
67 of useful standalone applications based upon the API. Some of them were developed by our students. The
68 third part is the server and client side scripts to publish observation results through the Internet. There
69 is a sample web application on the Ulyxes home page to demonstrate the publication of the coordinate
70 data stored in relational database. The backend is a PostgreSQL/PostGIS database, the middleware is
71 written in PHP, on the client side JavaScript functions are running based on jQuery and jQueryUI. AJAX
72 technology is used to connect the middleware to the client side. Data are sent from the server to the clients
73 in JSON format.

74 The API is a collection of Python classes, on the top there are the sensor classes, each sensor class
75 contains a communication interface, a measure unit and an optional writer instance (Figure 1). The task
76 of the communication interface is to send commands to the physical sensor and to receive the answer.
77 Different interface classes can be plugged into a sensor object, e.g. serial communication or i2c. The
78 measure unit is responsible to build the sensor specific native command and to parse and interpret the
79 answer from the sensor (Figure 2).

80 The Ulyxes Applications demonstrate the usage of the API. Most of them are useful for end users. The
81 most complex application is called RobotPlus, it realizes the on-site part of a monitoring system based
82 on robotic total stations. It integrates four other Ulyxes applications/classes (FileGen, BlindOrientation,
83 Robot and FreeStation) and an external open source application, called GNU Gama (Cepek, 2002). The
84 monitoring process is driven by a JSON configuration file where several parameters can be set. The
85 RobotPlus application is started as a cron job and the configuration file is loaded before each observation
86 circle. It makes easy to change the configuration on a running system. The application can handle control
87 points and monitoring points. The control points are supposed not moving and are used to check the
88 stability of the station position. The monitoring points are on the structures to check. Points are marked
89 by prisms.

90 The monitoring process has the following sequence of operations:

- 91 ● load JSON configuration,
- 92 ● get meteorological data for EDM corrections,
- 93 ● load coordinates of the points (both control and monitoring points and the station),
- 94 ● generate direction (bearing and zenith angle) and distance to the points from the station,
- 95 ● orient the station (preliminary orientation is made),
- 96 ● make observations for the control points,
- 97 ● calculate free station from the observation with blunder detection using GNU Gama,
- 98 ● set station coordinates and orientation,
- 99 ● make observations for the monitoring points,

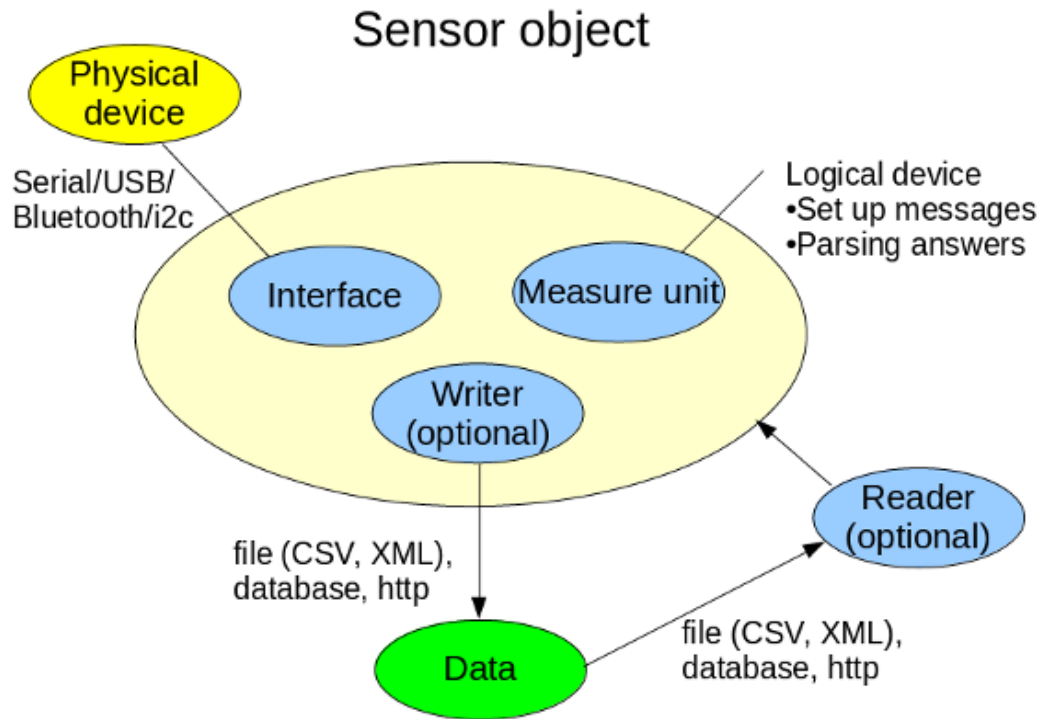


Figure 1. Logical components of an Ulyxes sensor object

100 • save observations/coordinates.

101 During the process a log file is written, the log level (DEBUG, INFO, WARNING, ERROR) can be
102 set in the configuration.

103 RESULTS

104 The system has been applied to several projects during the last 10+ years. Typical applications are the load
105 tests of bridges and other engineering structures (Berberan et al., 2007) and on the other hand Ulyxes can
106 be used to monitor the movements of buildings in the nearby of constructional works, like metro stations,
107 underground garage and other buildings as well. A monitoring process was made more than ten months
108 long during the building of an underground garage in Budapest. Two Leica TCA 1800 instruments were
109 set up with Raspberry Pi 3 computers (Raspbian operating system) and mobile internet (Figure 3). The
110 observations were made in every two hour from 2017 September to 2018. Our department worked in a
111 consortium with Hungeod Ltd.

112 Meteorological sensors were not installed on the field, instead the API of openweathermap.org was
113 used to get temperature, air pressure and humidity for Budapest. As the measured distances were below
114 100 meters the small differences between the real and the openweathermap.org data cause few tenth of
115 millimeters differences in the meteorological corrections of the distances.

116 The collected data were stored in an SQLite database on the Raspberry Pi, separately for the two sta-
117 tions and were uploaded to the common central database through the mobile Internet connection. Besides
118 the coordinates, angle and distance observations, the meteorological data and some other information are
119 stored in the database, e.g. the mean error of the free station calculations and maximal inclination angle
120 of the standing axis of the instrument. Charts are generated from the data in the database (Figure 4).

121 For the static part of test loads of bridges and overpasses Ulyxes is used in a similar way as in
122 building monitoring (Lienhart, 2017), but the period is much shorter. In this case the advantages of
123 the automation are the shorter observation time and the faster on site result generalization using few
124 SQL scripts. In case of dynamic test loads the observed movement lasts few seconds, therefore Ulyxes

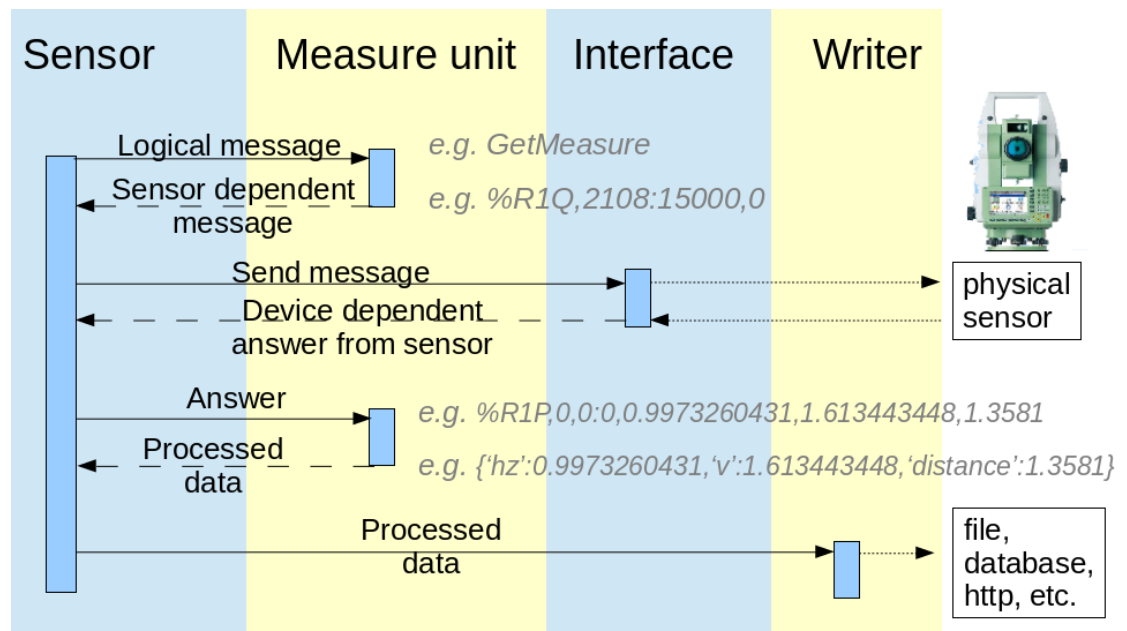


Figure 2. UML sequence diagram of command processing

125 supported digital cameras are preferred (e.g. Raspberry Pi Camera Module), usually attached to the
 126 telescope of an instrument to increase resolution.

127 Another interesting application of Ulyxes is to collect data for indoor navigation. The Wi-Fi fingerprint
 128 method needs a map of the strengths of the signals of the wireless access points. By the combination of
 129 two Ulyxes applications (MeasureToPrism and WifiCollector) the signal strengths and positions can be
 130 collected. A robotic total station, driven by MeasureToPrism application, follows a 360 degree prism
 131 and measures the distance as often as possible (1-2 seconds in fast distance measurement mode), while a
 132 Raspberry Pi 3, running the WifiCollector application, is moved along the prism and collects the Wi-Fi
 133 data. It is a one man measuring system, no operator is necessary at the robotic total station. The instrument
 134 is locked on the prism at the beginning. The MeasureToPrism application stores point coordinates with a
 135 timestamp, the WifiCollector stores SSID, address, signal quality, signal strength and timestamp. The
 136 two data sets are connected by the observation timestamps, so clocks have to be synchronised before the
 137 observations. The positions are interpolated to each second, if the observations are rarer and the signal
 138 strengths are aggregated to seconds as these data can be collected more often than one second, depending
 139 on the available Wi-Fi access points.

140 **Server and client side scripts**

141 This is the part of the project that still needs improvement. There is a simple AJAX based web application
 142 written in JavaScript and PHP, data are stored in PostgreSQL/PostGIS database. A PHP script is
 143 responsible for answering HTTP GET/POST requests, the responses are sent in JSON format, which is
 144 a native format for JavaScript and ES6. We have just started to upgrade our scripts to support different
 145 databases and not only to display elevation change trends but horizontal ones, too.

146 **Educational usage**

147 The aim of the educational usage is to introduce open source software development and some automation
 148 case studies to the students. BSc and MSc students are also involved in the use cases, development
 149 and testing. More theses were connected to this project in the recent five years. In the curriculum
 150 of an MSc subject called Surveying Automation, Ulyxes is used to demonstrate automatized tasks in
 151 engineering surveying. Some sample applications were developed by students (HorizontalSection, Section,
 152 MeasureMatrix), which are also available on GitHub.



Figure 3. Instrument on site

153 **FUTURE OF THE PROJECT**

154 The redesign of the server and client side scripts is in progress. We hope those will be ready by the time of
155 the OGRS 2018. Moreover it is also planned to implement SOS standard using IstSOS. Our Geo4All Lab
156 maintains another open source software, called GeoEasy (<https://github.com/zsiki/GeoEasy>) to process
157 observation data in engineering and land surveying. A closer cooperation is also planned between our two
158 open source projects.

159 **ACKNOWLEDGMENTS**

160 Many thanks to the developers of the open source projects which were applied in our work.

161 **REFERENCES**

- 162 Berberan, A., Machado, M., and Batista, S. (2007). Automatic multi total station monitoring of a tunnel.
163 *Survey Review*, 39(305):203–211.
- 164 Cepek, A. (2002). The gnu gama project - adjustment of geodetic networks. *Acta Polytechnica*, 42(3):26–
165 30.
- 166 Grimmitt, R. (2014). *Raspberry Pi Robotic Projects*. Packt Publishing.
- 167 Hillar, G. (2016). *Internet of Things with Python*. Packt Publishing.
- 168 Lienhart, W. (2017). Geotechnical monitoring using total stations and laser scanners: critical aspects and
169 solutions. *Journal of Civil Structural Health Monitoring*, 7(3):315–324.

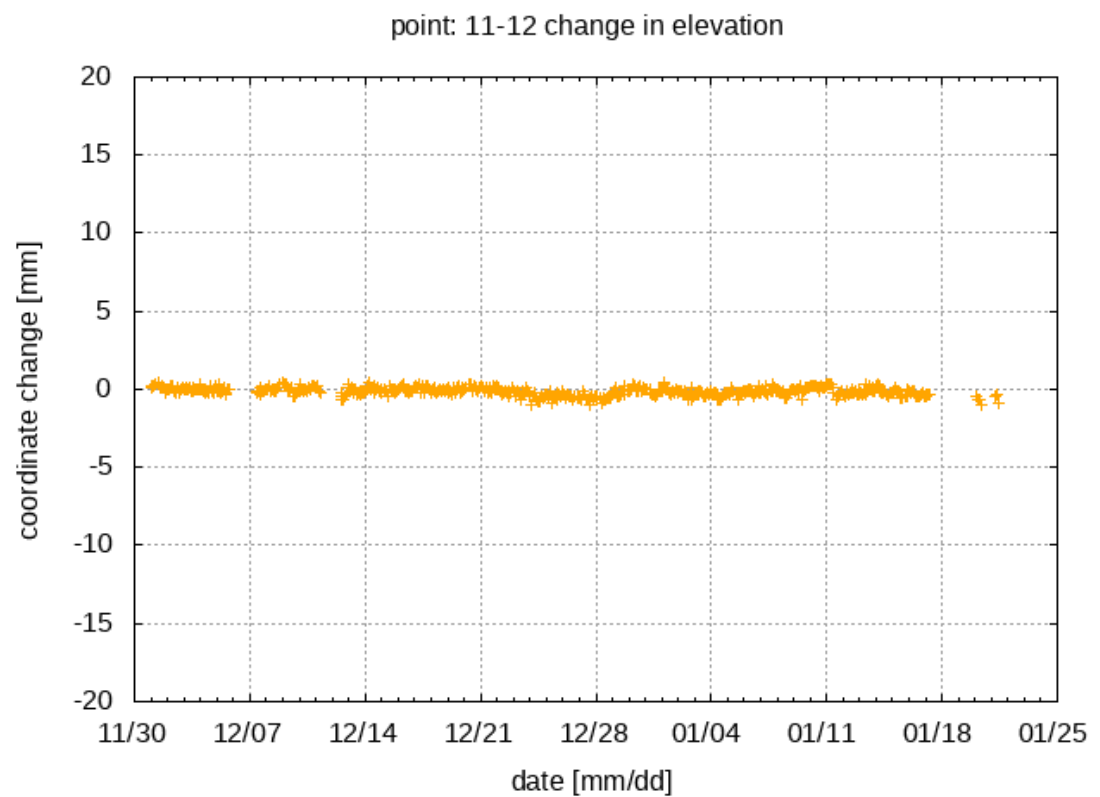


Figure 4. Change of elevation chart