

1 Remaining gaps in open source software 2 for Big Spatial Data

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8 **ABSTRACT**

9 The volume and coverage of spatial data has increased dramatically in recent years, with Earth observa-
10 tion programmes producing dozens of GB of data on a daily basis. The term Big Spatial Data is now
11 applied to data sets that impose real challenges to researchers and practitioners alike. As rule, these
12 data are provided in highly irregular geodesic grids, defined along equal intervals of latitude and longitude,
13 a vastly inefficient and burdensome topology. Compounding the problem, users of such data end up
14 taking geodesic coordinates in these grids as a Cartesian system, implicitly applying Marinus of Tyre's
15 projection.

16 A first approach towards the compactness of global geo-spatial data is to work in a Cartesian system
17 produced by an equal-area projection. There are a good number to choose from, but those supported
18 by common GIS software invariably relate to the sinusoidal or pseudo-cylindrical families, that impose
19 important distortions of shape and distance. The land masses of Antarctica, Alaska, Canada, Greenland
20 and Russia are particularly distorted with such projections. A more effective approach is to store and
21 work with data in modern cartographic projections, in particular those defined with the Platonic and
22 Archimedean solids. In spite of various attempts at open source software supporting these projections,
23 in practice they remain today largely out of reach to GIS practitioners. This communication reviews
24 persisting difficulties in working with global big spatial data, current strategies to address such difficulties,
25 the compromises they impose and the remaining gaps in open source software.

26 **1 INTRODUCTION**

27 Raster datasets covering the entire globe are becoming ever more available, not only in the form of remote
28 sensing derived products, but also as time-series of natural variables, such as those reporting to Climate,
29 Geology or Sociology. Researchers in Geo-Informatics and Earth Sciences in general are thus increasingly
30 able of working at the global scale. Remarkably, such datasets are in almost all cases provided in highly
31 irregular global grids, defined along regular intervals of longitude and latitude. Exemplary datasets
32 include:

- 33 • Moderate Resolution Imaging Spectroradiometer (MODIS) - constant intervals of 0.05° latitude
34 and longitude.
- 35 • Shuttle Radar Topography Mission (SRTM) - constant intervals of 1 arc second.
- 36 • Digital Terrain Elevation Data (DTED) - various levels with latitude intervals ranging from 1 to 30
37 arc seconds and longitude ranging from 1 to 180 arc seconds.
- 38 • IPCC climate scenarios - constant intervals of 2° latitude and longitude.

39 Researchers working at the global scale tend to use these data “as is”, skipping any formal cartographic
40 projection. Since any common GIS programme operates on the Cartesian plane, researchers end up
41 tacitly working on the semi-plane created by Marinus of Tyre’s projection (in which the irregular global

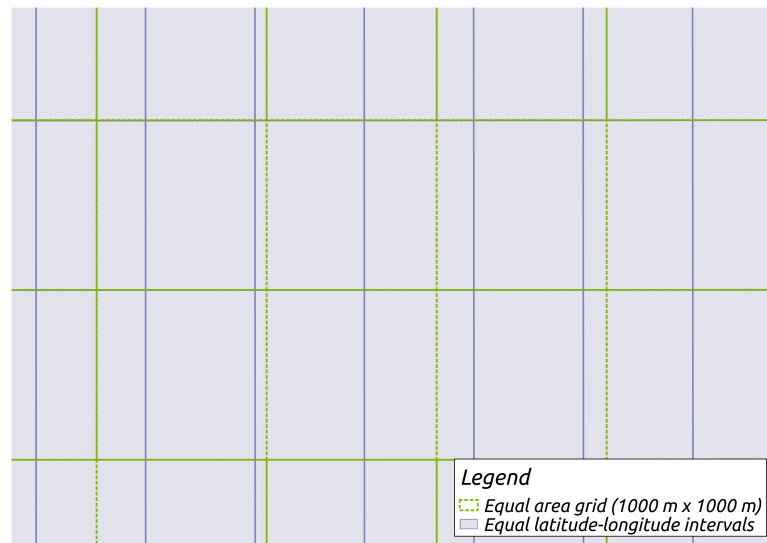


Figure 1. A regular grid defined on an equal-area projection compared with a grid defined on equal intervals of latitude and longitude, at a latitude of 50° .

42 grid becomes a regular quadrangular grid). It is deeply ironic that Earth Sciences continue relying on a
 43 mathematical formulation that is almost 2 000 years old.

44 While the area of the Earth's surface is in the order of 510 Mm^2 , the total area of Marinus of
 45 Tyre's projection counter-domain is over 800 Mm^2 , a difference of 60%. This also means that a global
 46 dataset sampling the Earth at regular angular intervals, contains 60% more samples than one defined to
 47 favour regularity of sampling areas (Figure 1 exemplifies this difference). This is not only a problem
 48 for storage space, but much more so to Geo-computation with big data, demanding more memory and
 49 computing cycles. When employing modern techniques such as Neuronal Networks or Machine Learning,
 50 researchers can easily be facing computation constrains with Marinus of Tyre's projection that in an equal
 51 area projection would be less restrictive or altogether non existent.

52 A number of reasons collude to deter researchers from working with alternative cartographic projec-
 53 tions:

- 54 • Other datasets are also provided in similar constant latitude-longitude global grids.
- 55 • Re-projecting original data with an alternative cartographic projection can be computationally
 56 expensive.
- 57 • Re-projection may lead to data loss.
- 58 • It is not easy to identify the most appropriate cartographic projection.

59 The last item is itself rooted in another issue: support for modern equal-area cartographic projections
 60 remains scant in free and open source software for Geo-Informatics (FOSS4G). Only those equal-area
 61 projections yielding higher shape distortions are readily usable in stock open-source GIS programmes,
 62 which naturally plays against their adoption.

63 This article starts with a brief review of the issues with popular equal-area projections (Section 2);
 64 it then reviews current support to modern projections of this class in FOSS4G (Section 3); Section 4
 65 concludes by identifying the development avenues in FOSS4G software enabling work with appropriate
 66 equal-area projections.

67 2 POPULAR EQUAL-AREA PROJECTIONS

68 The gains in storage space and the consequent reduction in computation demands more than justify
 69 working with global rasters on equal-area projections. The options for the purpose are many, however,
 70 only a few of these projections are actually operational in an open source software stack. Figure 2

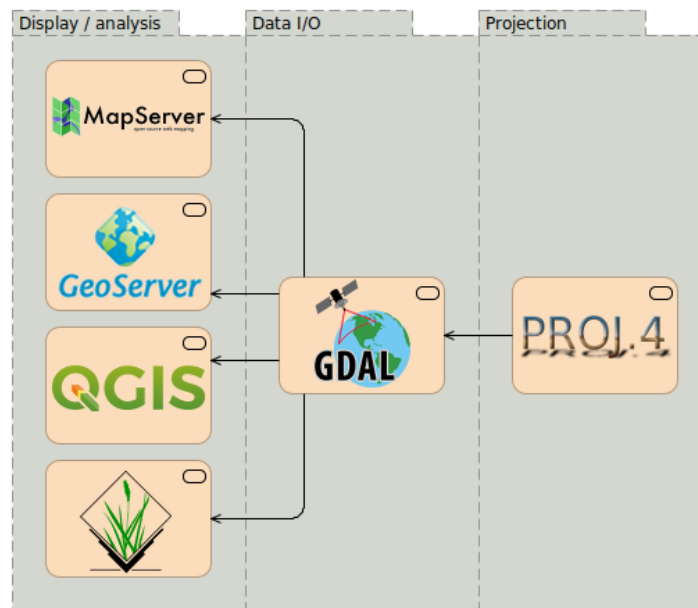


Figure 2. Dependencies of staple FOSS4G programmes.

71 portraits schematically the dependencies of various off-the-shelf geo-spatial open source programmes.
 72 Essentially, any cartographic projection must be supported by both Proj (PROJ contributors, 2018) and
 73 GDAL (GDAL/OGR contributors, 2018) to be fully usable in an open source environment. Unfortunately,
 74 the slim number of supported equal-area projections are mostly part of the sinusoidal or pseudo-cylindrical
 75 families, inducing deep shape distortions. In large measure this is due to GDAL, that to support any
 76 projection strictly requires its inverse too.

77 Figure 3 provides a practical example with the portrayal of New Zealand in a projection centred on 0°
 78 E, 0° N. The islands composing this country turn out deeply warped, particularly so with the classical
 79 Sinusoidal projection. This is significant, given how popular this last projection is (Seong et al., 2002),
 80 used even by institutions like NASA (possibly because it preserves distances along parallels and the
 81 central meridian). Such distortions are particularly critical for datasets that while produced on a global
 82 scale, are relevant to local analysis process, e.g. climate, environment.

83 A detailed analysis of these distortions can be obtained using Tissot's Indicatrix (Goldberg and Gott III,
 84 2007). However, Figure 3 is enough to show the distortions imposed by these popular projections. And it
 85 is not only a visual accuracy problem, shapes warped this much also imply higher information loss during
 86 re-projection to alternative CRSs, e.g. in local or regional analysis exercises. The need for alternative
 87 equal-projections is therefore well patent, so that space and computation economy does not come at the
 88 expense of cartographic quality.

89 A further alternative is to use multi-projection systems, usually one per continent, such as the
 90 Equi7 Bauer-Marschallinger et al. (2014), but these create problems of their own. There is an overhead in
 91 managing different projections in parallel, and overlaps between the various Cartesian counter-domains
 92 in the system can create problems of their own. They also make the publication of data to third parties
 93 cumbersome, since standards like WMS or WCS do not consider multi-projection systems.

94 **3 MODERN EQUAL-AREA PROJECTIONS**

95 Throughout the past century several mathematicians and cartographers produced novel equal-area projec-
 96 tions that considerably ameliorate shape distortion. However, for one reason or other, none of them is
 97 fully supported in a FOSS4G stack. This section explores a few of them¹.

¹The software stack used in these tests comprised: Ubuntu 18.04, Proj 4.9.3, GDAL 2.2.3.

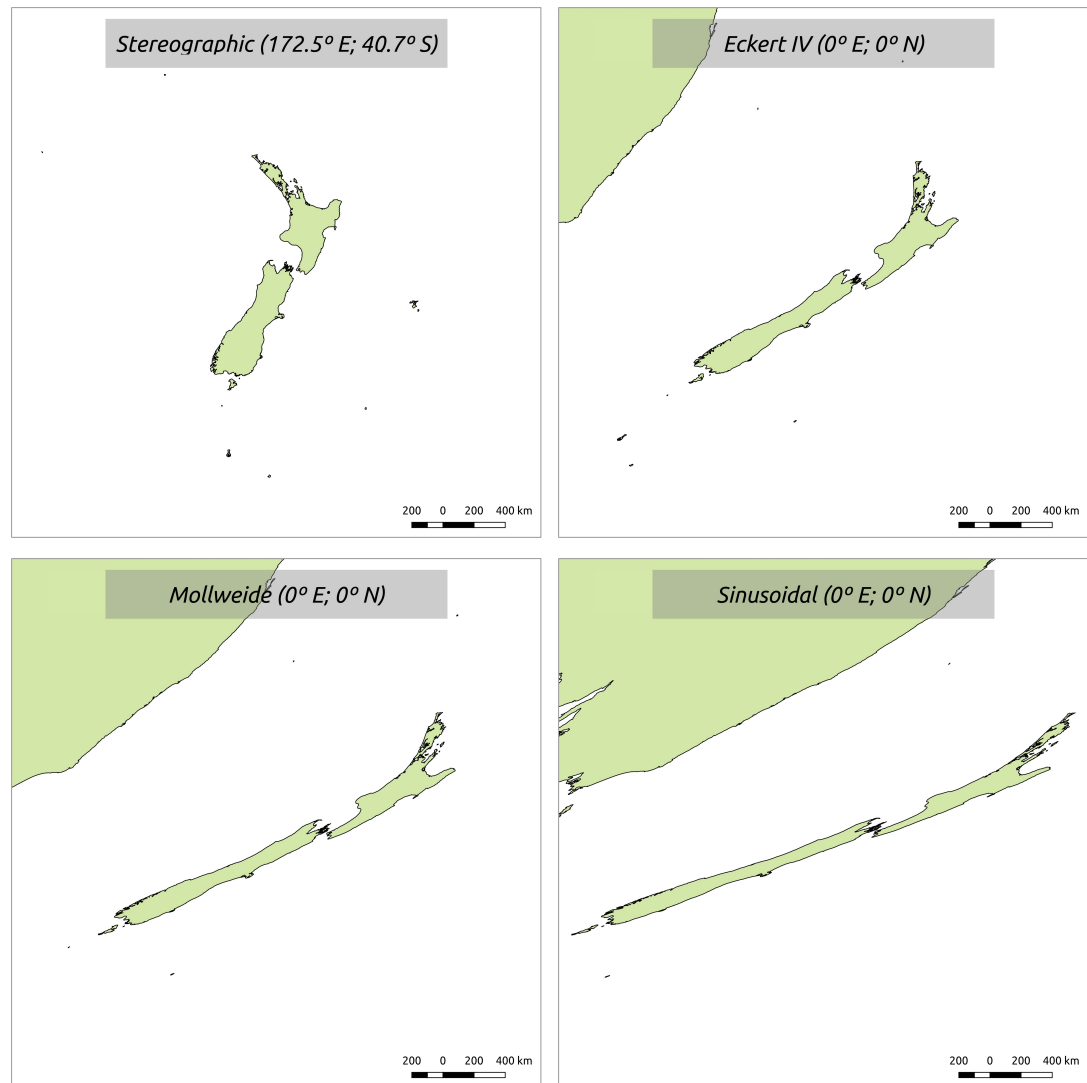


Figure 3. The distortions produced on New Zealand by three popular equal-area map projections when applied on the point with coordinates (0° E, 0° N).

98 3.1 Hammer's

99 This projection was developed in the last decade of the XIX century, with the goal of ameliorating
100 the distortions produced by Mollweide's projection at high longitudes (Snyder, 1997). Hammer drew
101 inspiration from Aitoff's projection, using an elliptical counter-domain where all parallels are curved
102 (apart from the one passing in the central point, usually the Equator).

103 In spite of its improvements over Mollweide's, Hammer's projection never found the popularity of the
104 former. Perhaps for that reason, Hammer's projection is scantily supported by FOSS4G, only by Proj, in
105 its direct form.

Listing 1. Hammer's projection with Proj and GDAL

```
106 $ cs2cs +init=epsg:4326 +to +proj=hammer +lat_0=0 +lon_0=0 +datum=WGS84
107 +units=m +no_defs <<EOF
108 > 15 -15
109 > EOF
110 1625591.45 -1668538.36 0.00
111
112 $ gdaltransform -s_srs "+init=epsg:4326" -t_srs "+proj=hammer_+lat_0=0
113 +lon_0=0_+datum=WGS84_+units=m_+no_defs" <<EOF
114 > 15 -15
115 > EOF
116 ERROR 1: Translating source or target SRS failed:
117 +proj=hammer +lat_0=0 +lon_0=0 +datum=WGS84 +units=m +no_defs
118
```

120 3.2 Goode's Homolosine

121 John P. Goode (1925) developed his Homolosine projection in the 1920s, while attempting to interrupt
122 Mollweide's projection. The end result was a major improvement over the then equal-area state-of-the-art,
123 with serious shape distortions only present at latitudes over 60°. This projection would gain popularity in
124 the following decades, often used to convey socio-economic information; it is easy to find in didactic and
125 technical publications of the second half of the XX century. However, with the advent of web mapping,
126 this projection has almost disappeared from general interest publications.

127 Interestingly, Goode's Homolosine is in fact reasonably supported by FOSS4G. Both Proj and GDAL
128 fully support it, while analysis programmes like QGIS or GRASS are able to intake Homolosine rasters.
129 Unfortunately, the analysis programmes are not able to correctly use and portray vector data encoded with
130 this projection, greatly limiting analysis and cartography. Figure 4 presents raster and vector maps as
131 portrayed by QGIS with the Homolosine projection; at least the vector rendering library as it a loss with
132 the projection counter-domain. Even so, Goode's Homolosine is the closest it gets to a proper equal-area
133 projection suitable for modern day big geo-spatial data processing.

134 3.3 Bogg's Eumorphic

135 Just a few years after Goode, Samuel W. Bogg developed a projection that produces a similarly shaped
136 world map (Snyder, 1997). Bogg used an average of the Sinusoidal and Mollweide's projections to
137 obtain easting coordinates and a pseudo-cylindrical to obtain the northing. A map produced with Bogg's
138 Eumorphic projection can be easily mistaken by Goode's Homolosine. Perhaps for coming later, the
139 Eumorphic never became as popular as the Homolosine.

140 Bogg's Eumorphic projection is supported by Proj, but not by GDAL, meaning it is in practice largely
141 unusable with a FOSS4G stack. Rending it operational would require at least the implementation of
142 its inverse in Proj, so that GDAL can accept it. Beyond that, the same issues with vector data in the
143 Homolosine are to be expected with the Eumorphic.

Listing 2. Bogg's projection with Proj and GDAL

```
144 $ cs2cs +init=epsg:4326 +to +proj=boggs +lat_0=0 +lon_0=0 +datum=WGS84
145 +units=m +no_defs <<EOF
146 > 15 -15
147 > EOF
148 1541082.76 -1755739.47 0.00
149
150 $ gdaltransform -s_srs "+init=epsg:4326" -t_srs "+proj=boggs_+lat_0=0
151 +lon_0=0_+datum=WGS84_+units=m_+no_defs" <<EOF
152 > 15 -15
153
```

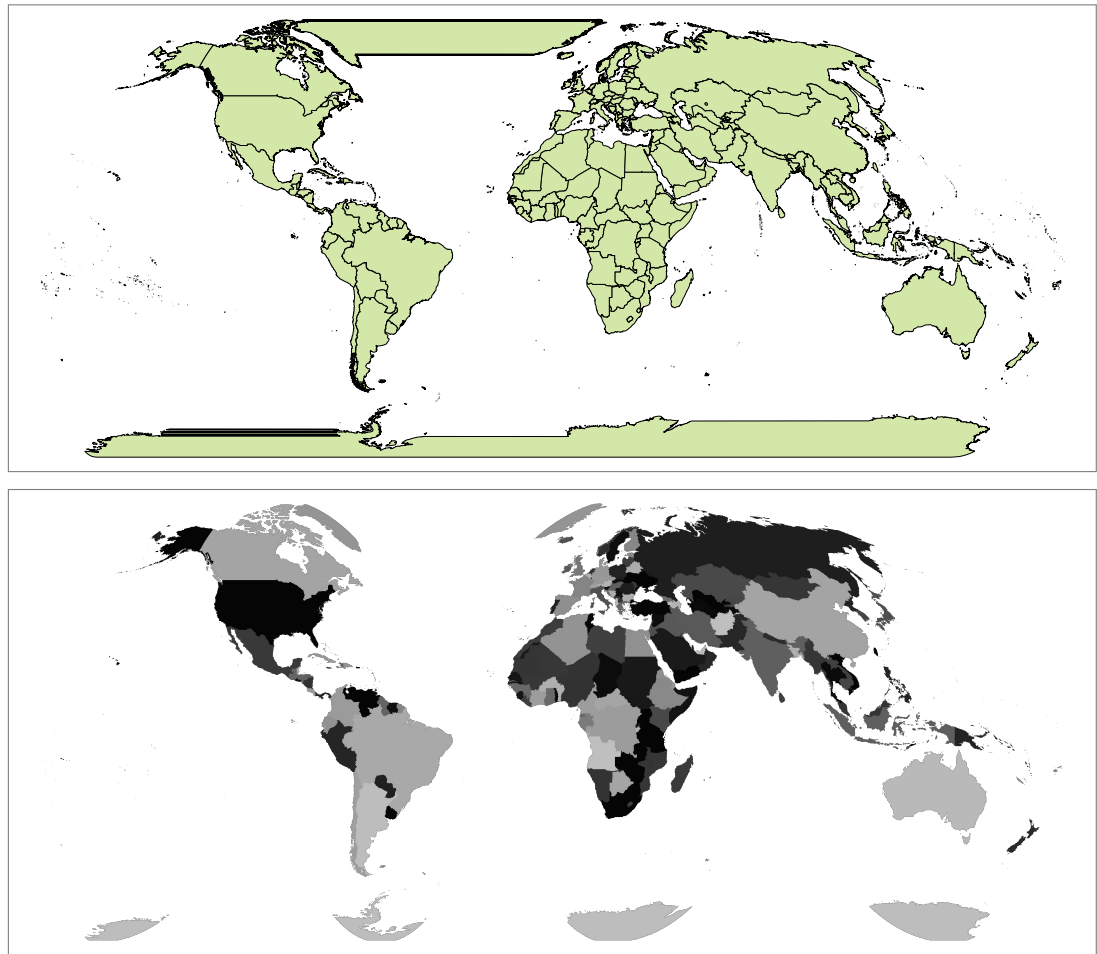


Figure 4. World maps portrayed by QGis with Goode's projection, vector top, raster bottom.

```

154 > EOF
155 ERROR 1: Translating source or target SRS failed:
159 +proj=boggs +lat_0=0 +lon_0=0 +datum=WGS84 +units=m +no_defs

```

158 3.4 Snyder's Icosahedral

159 John P. Snyder (1992) produced a number of reference scholarly works on Cartography in the last
 160 decades of the XX century and eventually developed various projections himself. Most notable is the
 161 equal-area projection Snyder developed for Archimedian and Platonic solids. Fuller (1943) had earlier
 162 used the icosahedron in his somewhat famous Dymaxion projection, but this last author employed rather
 163 a conformal projection. Snyder went further, with an equal-area formulation, that is extendable to the
 164 dodecahedron and truncated icosahedron.

165 Snyder's Icosahedral projection was immediately picked up by researchers working with the Envi-
 166 ronmental Protection Agency of US, whom at the time were developing global sampling grids on the
 167 geodetical domain. Kevin Sahr would produce an open source programme that creates global geodetical
 168 grids, in the process implementing Snyder's Icosahedral projection (Sahr et al., 2003). This programme
 169 was left dusting for decades until recently, when Barnes et al. (2017) created a binding software package
 170 that allows the usage of Sahr's software with the R programming language.

171 The Icosahedral equal-area projection is partially supported by Proj, limited to two pre-defined
 172 orientations of the icosahedron relative to the globe. No other FOSS4G supports this projection, making
 173 it impractical for off-the-shelf spatial analysis.

Listing 3. Snyder's Icosahedral projection with Proj and GDAL

```

174 $ cs2cs +init=epsg:4326 +to +proj=isea +lat_0=0 +lon_0=0 +datum=WGS84
175 +units=m +no_defs <<EOF
176 > 15 -15
177 > EOF
178 6659048.10      7609090.35 0.00
179
180 $ gdaltransform -s_srs "+init=epsg:4326" -t_srs "+proj=isea_+lat_0=0
181 +lon_0=0_+datum=WGS84_+units=m_+no_defs" <<EOF
182 > 15 -15
183 > EOF
184 ERROR 1: Translating source or target SRS failed:
185 +proj=isea +lat_0=0 +lon_0=0 +datum=WGS84 +units=m +no_defs
189

```

188 3.5 Snyder's Dodecahedral and Truncated-Icosahedral

189 Snyder's projection for the icosahedron is directly applicable to the dodecahedron and the truncated-
 190 icosahedron. This last solid is built from the icosahedron, adding a pentagonal face in place of each of
 191 its twelve vertices; the result is a solid with 32 faces, 20 hexagonal and 12 pentagonal. The Truncated-
 192 Icosahedral is actually a composite, with two different projections, at two different scales, one for the
 193 hexagonal faces and another for the pentagonal.

194 According to Snyder's calculations, both the Dodecahedral and the Truncated-Icosahedral projections
 195 yield lower shape distortions rates than the Icosahedral and the author himself appeared to favour these.
 196 Moreover, the representation of continents in the Dodecahedral projection is visually more palatable with
 197 its fewer interruptions. However, no practical open source implementations of these projections could be
 198 identified.

199 4 SUMMARY AND CONCLUSIONS

200 This article reviewed the inadequacy of popular cartographic projections for the analysis of big spatial
 201 data, particularly in the raster form. The most popular of all, Marinus of Tyre's equirectangular projection,
 202 induces irregular grids that needlessly expand the number of cells in rasters, with penalties in storage
 203 space and computation load. Equal-area projections address this; however, those supported by FOSS4G
 204 are scant and invariably impose deep shape distortions that lead to problems of their own.

205 Support for modern equal-area projections is thus an obvious necessity for the FOSS4G community.
 206 Only Goode's Homolosine projection is presently an option, and strictly regarding raster data. Considering
 207 the tests reported above, four different development pathways can be devised in this field:

- 208 a) reconsider the requirement for inverse projections, wherever practical;
- 209 b) develop missing inverse projections in the Proj package;
- 210 c) implement further polyhedral projections in Proj;
- 211 d) enforce the counter-domain of equal-area projections in vector portrayal and processing libraries.

212 One wonders what Marinus of Tyre would think, were he to know how popular his projection remains
213 in the computer age. The father of mathematical cartography might ask himself why map projections in
214 general are still so much in use, when parchments are no longer necessary to store and present geo-spatial
215 data. In effect, modern equal-area projections play a capital role in upgrading geo-computation to the
216 Geodetical domain (Sahr et al., 2003), justifying in a further way the investment from the community.

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