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# A comparison of clustering methods for biogeography with fossil datasets

#### Matthew J Vavrek

Cluster analysis is one of the most commonly used methods in palaeoecological studies, particularly in studies investigating biogeographic patterns. Although a number of different clustering methods are widely used, the approach and underlying assumptions of many of these methods are quite different. For example, methods may be hierarchical or nonhierarchical in their approaches, and may use Euclidean distance or non-Euclidean indices to cluster the data. In order to assess the effectiveness of the different clustering methods as compared to one another, a simulation was designed that could assess each method over a range of both cluster distinctiveness and sampling intensity. Additionally, a nonhierarchical, non-Euclidean, iterative clustering method implemented in the R Statistical Language is described. This method, Non-Euclidean Relational Clustering (NERC), creates distinct clusters by dividing the data set in order to maximize the average similarity within each cluster, identifying clusters in which each data point is on average more similar to those within its own group than to those in any other group. While all the methods performed well with clearly differentiated and well-sampled datasets, when data are less than ideal the linkage methods perform poorly compared to non-Euclidean based k-means and the NERC method. Based on this analysis, Unweighted Pair Group Method with Arithmetic Mean and neighbor joining methods are less reliable with incomplete datasets like those found in palaeobiological analyses, and the k-means and NERC methods should be used in their place.

# A comparison of clustering methods for biogeography with fossil datasets

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## 9 Abstract

10 Cluster analysis is one of the most commonly used methods in palaeoecological studies, 11 particularly in studies investigating biogeographic patterns. Although a number of different 12 clustering methods are widely used, the approach and underlying assumptions of many of these 13 methods are quite different. For example, methods may be hierarchical or non-hierarchical in their approaches, and may use Euclidean distance or non-Euclidean indices to cluster the data. In 14 15 order to assess the effectiveness of the different clustering methods as compared to one another, 16 a simulation was designed that could assess each method over a range of both cluster 17 distinctiveness and sampling intensity. Additionally, a non-hierarchical, non-Euclidean, iterative 18 clustering method implemented in the R Statistical Language is described. This method, Non-19 Euclidean Relational Clustering (NERC), creates distinct clusters by dividing the data set in 20 order to maximize the average similarity within each cluster, identifying clusters in which each 21 data point is on average more similar to those within its own group than to those in any other 22 group. While all the methods performed well with clearly differentiated and well-sampled 23 datasets, when data are less than ideal the linkage methods perform poorly compared to non-24 Euclidean based k-means and the NERC method. Based on this analysis, Unweighted Pair Group 25 Method with Arithmetic Mean and neighbor joining methods are less reliable with incomplete

26 datasets like those found in palaeobiological analyses, and the k-means and NERC methods

27 should be used in their place.

28

29 Keywords: Adjusted Rand Index, biogeography, cluster analysis, ecological similarity,

- 30 palaeoecology
- 31

## 32 Introduction

Clustering, defined as "a classificatory method which optimizes intra-group 33 34 homogeneity" (Lance and Williams, 1967), is one of the most frequently used forms of 35 multivariate analysis in palaeoecology (Hammer et al., 2001). One of the areas in which cluster 36 analysis is commonly used is studying patterns of biogeography amongst species assemblages. 37 Cluster analysis has been used in palaeoecological studies on groups as diverse as vertebrates 38 (Shubin and Sues, 1991; Holtz, Jr. et al., 2004; Fröbisch, 2009; Gates et al., 2010; Noto and 39 Grossman, 2010; Donohue et al., 2013), invertebrates (Schwimmer, 1975; Clapham and James, 40 2008), foraminifera (Collins, 1993) and plants (LePage et al., 2003), and assemblages spanning 41 the Ediacaran (Clapham et al., 2003) to the Pleistocene (Wolfe, 2000). With the rise of large 42 datasets of fossil species occurrences [e.g. Paleobiology Database, MioMAP (Carrasco et al. 43 2005), FAUNMAP (Graham and Lundelius, Jr. 2010), NOW (Fortelius 2015); see Uhen et al., 44 2013 for recent review] with hundreds or thousands of records, semi-automated methods such as 45 clustering are becoming more and more necessary to find underlying patterns in these highly 46 complex collections. As the use of cluster analysis in palaeobiology has steadily expanded, so 47 too have the types of methods used. Although the underlying purpose of these methods is the 48 same (i.e. to delimit different groups from one another), their approaches and assumptions are 49 often quite different. For example, some cluster analysis methods (e.g. Unweighted Pair Group 50 Method with Arithmetic Mean/UPGMA, neighbour-joining) use a hierarchical approach to 51 grouping data (James and McCulloch, 1990; Shi, 1993). 52 Other common methods include partitioning techniques, such as *c*-means or *k*-means,

53 which may try to optimize groups by minimizing relative distances based on a chosen index

54 (Hartigan and Wong, 1979). Although clustering methods may be widely used, their

55 effectiveness relative to one another is less well known, in particular with the often sparse

56 datasets used in palaeobiological studies. In order to examine the relative efficacy of these 57 different clustering methods with species occurrence data, a dataset where the "true" clustering 58 relationship is known is required. To generate multiple simulated datasets with established 59 clustering relationships, I created an R function which could create a species occurrence database 60 that could then be used to test the efficiency of the methods over a large number of trials. 61 In addition to the analysis of the various clustering methods commonly used, I also 62 describe here an R function for a non-Euclidean, non-hierarchical clustering method termed here Non-Euclidean Relational Clustering (NERC), an iterative method that uses agglomerative 63 clustering with post-clustering optimization. The efficacy of this function is tested in comparison 64 65 to the more traditional methods.

66

## 67 Materials and Methods

#### 68 The NERC Function

69 The NERC Function The algorithm's execution can be broken down into three distinct 70 steps [after Lance and Williams (1967)]: the initialization of clusters; the allocation of new 71 elements to a cluster; and finally an iterative reallocation process whereby the clusters are 72 optimized. The first step, initialization of the clusters, begins by sampling a number of elements 73 equal to the requested number of final clusters. Each of these selected samples is assigned 74 randomly to a different initial cluster. In the second step, the function searches for the greatest 75 similarity (smallest value in a dissimilarity matrix) between any unassigned sample and any 76 assigned sample. The unassigned sample with the highest similarity is assigned to the same 77 group as that which it shares the greatest similarity, similar to Single Linkage Clustering 78 Analysis (Gower and Ross, 1969). This process then repeats, until all samples are assigned to a 79 cluster. At the end of the second step, if any group has only one member the process restarts 80 from the first step.

As a final step, an optimization of the clusters is performed. To begin, each individual sample within the entire set is assessed for its average similarity to every cluster. The similarity is based on the average pairwise distance from a sample to every member of a cluster (excluding the sample itself in the case of the cluster it had been assigned to). If a sample has a greater 85 similarity to another cluster other than the one it has been assigned to, the optimization routine 86 will reassign the sample to the cluster that it had the most similarity to. If more than one sample 87 is in a suboptimal cluster, only one sample, chosen at random, will be reassigned at a time. After 88 a sample has been reassigned, the average pairwise distances will be calculated again before 89 another sample is reassigned (if necessary). If all the samples are in the cluster with which they have the greatest average similarity then the cycle is complete. At present, an upper limit of 1000 90 91 reassignments has been set so as to avoid an infinite loop if there is no solution where every 92 sample is in its optimal grouping. The process will find a local, but not necessarily global, 93 optimum by minimizing the overall dissimilarity within clusters. Because the method is heuristic 94 in nature, it is best to repeat the clustering process many times.

95

### 96 Implementation of NERC

97 The R Statistical Language (R Development Core Team, 2012) was used to implement the

98 NERC function. The R Language is cross platform, Open Source and free to use, and is widely

99 used in statistical research, making it easy to extend with new functions and packages. The

100 package fossil (Vavrek, 2011) with all of the functions discussed in this paper is available

101 through the Comprehensive R Archive Network (CRAN) at http://cran.r-

102 project.org/web/packages/fossil/. All data analysis and figure creation was done using R v3.2.1

103 on a Mac OS X 10.10 system. For a full copy of the R code used in the calculations and figures,

104 please consult the Supplementary Materials.

105 The R implementation of the NERC function has one required and three optional106 arguments, and takes the form:

107

```
108 rclust(dist, clusters = 2, rand = 1000, counter = FALSE)
```

109

The only required argument is a distance or dissimilarity matrix (the dist argument), either as a full matrix or lower triangle. The first optional argument (clusters) is the number of groups to be created. The number of groups used must be a positive integer equal to or greater than 2 but no greater than 1/2 the total number of samples. The minimum value represents the smallest number of clusters without placing all samples within one group, and the maximum value prevents

115 clusters of one. The default value for the number of clusters is set to 2. The second optional

116 argument gives the number of times the clustering process should be run. Because the method

117 should be run many times to have a better chance of finding the global optimal solution, this

118 option has a default value of 1000. The last optional argument (counter) specifies whether to

119 print the current run. Note that at this point the R function returns only the result with the

- 120 smallest average within group distances overall.
- 121

### 122 Data Simulation and Comparisons

123 In order to test the efficacy of NERC in comparison to several other cluster methods, I 124 also created a simple function to simulate a species abundance data set. This function, called 125 sim.occ(), creates a matrix of sites (columns) and species (rows) with a known clustering 126 solution. The number of species, localities, regions (clusters), sample size and proportion of 127 regional endemicity can all be adjusted. Each specific 'region' in the simulated set contains a 128 number of 'cosmopolitan' species that are found in every region, as well as 'endemic' species 129 that are found in only that particular region. To obtain a sample for a single locality, a 130 randomized log-normal distribution is applied to the total possible species pool for a given region; the parameters are set so that any given locality will have several abundant species, a 131 132 large number of less common species, and some species which are not present. A log-normal 133 distribution was used as it is one of the most common species abundance distributions found in 134 empirical samples of modern habitats (Preston 1962; Gaston and Blackburn 2000; Magurran 135 2004). For every sample a new randomized log-normal distribution was created from the parent 136 region species pool. The average number of specimens can be varied to simulate different 137 sampling intensities. The full R code for the function can be found within the fossil package. 138 The simulated data was clustered using 6 different combinations of methods and input 139 matrices: single linkage, complete linkage, UPGMA, k-means on a db-RDA ordination using 140 both Euclidean and a non-Euclidean distance measure, and NERC. For those methods that provide hierarchical clusters, discrete clusters were made using the cutree function. The db-RDA 141 142 ordination was performed using the capscale function in the vegan (Oksanen et al., 2011) 143 package.

144 Most functions used require a distance matrix as input, rather than raw species values. In

145 order to convert the occurrence matrices to dissimilarity matrices, the ecol.dist() function was used, with the Sørensen (sometimes called Dice) dissimilarity index used to calculate pairwise 146 147 dissimilarities. The Sørensen dissimilarity index was used because it is one of the most commonly used indicices, and is regarded as one of the most effective presence/absence 148 149 dissimilarity measures (Southwood and Henderson 2000; Magurran 2004). Although the 150 sim.occ() function did create abundance-based occurrence matrices, the use of the Sørensen 151 dissimilarity index is presence/absence based, in effect converting the data. Although discarding 152 abundance data is not generally recommended in actual analyses, presence/absence data is typically more common in palaeontological datasets, so using the Sorenson dissimilarity index 153 created a more realistic scenario. 154

155 The six methods were tested to see how well they performed both with varying levels of endemicity (or differentiation between clusters; Fig. 1) as well as with varying levels of sampling 156 157 intensity. A simulated occurrence matrix was created 1000 times for each level of differentiation 158 or sampling intensity, and then clustered to obtain averaged performance values for all five 159 clustering methods. Each of the simulations consisted of 30 samples from 3 different endemic 160 regions, for a total of 90 samples to be used in the cluster analysis. Because of the parallel nature 161 of this simulation, the multicore (Urbanek, 2011), foreach (Revolution Analytics, 2011b), and 162 doMC (Revolution Analytics, 2011a) parallel computing packages for R were also used. The 163 visualization of cluster distinctiveness in Fig. 1 was created using the NMDS function provided 164 by the ecodist package (Goslee and Urban, 2007).

165 For the simulated biogeographic datasets, the "true" clustering was known, and so the 166 results of each clustering method could be compared to this *a priori* grouping. The Rand Index (Rand, 1971; Hubert and Arabie, 1985) is method to compare two clustering outcomes and 167 168 calculates an index of similarity, with a value of 1 being a perfect match. The original formula 169 for this index, however, had a lower bound that fluctuated, depending on group sizes and 170 numbers (Hubert and Arabie, 1985). A modification of this original formula, given by Hubert and Arabie (1985), scaled the value so that the greatest mathematically possible difference would 171 172 always be 0, with the upper bound still set to 1. This modification is referred to as the Adjusted 173 Rand Index (ARI). In the fossil package, both functions are provided, although only the ARI is used to calculate the effectiveness of the clustering methods in this paper. 174

175

#### 176 **Results**

177 Overall, the NERC and non-Euclidean k-means methods were the most effective at recovering the original groupings across the different levels of regional endemicity (Fig. 2), with 178 179 the NERC slightly outperforming the non-Euclidean k-means. Using a Euclidean distance metric 180 for the k-means method, even when the rest of the method and dataset are kept the same, led to a 181 notable reduction in performance. Complete linkage and UPGMA were readily able to recover 182 the correct clusters when the groups were relatively distinct. However, when the simulated 183 clusters were less distinct their effectiveness quickly declined. Single linkage clustering was least 184 effective and, produced unreliable results even at levels where all the other methods easily found 185 the proper clustering arrangement. 186 For the differing levels of sampling intensity (Fig. 3), the NERC method and non-187 Euclidean k-means methods were again the most effective at recovering an accurate signal, 188 although in this instance the k-means was slightly more effective. Overall, complete linkage and 189 UPGMA gave accurate results when sampling intensity was high, but their performance was 190 very poor with sparsely sampled data. Single linkage was again the least effective of all the 191 methods tested.

192

## 193 Discussion

194 All cluster methods performed well when clusters were very distinct and sampling 195 intensity was high. However, in cases where biogeographic clusters were less distinct or 196 sampling was poor, the db-RDA/k-means and the NERC methods were best able to recover the 197 original clusters compared to the other tested clustering methods. Among the other clustering 198 methods, single linkage performed the poorest of any of the methods. The notably poor 199 performance of the single linkage method was likely the result of individual samples that were 200 extremely distant from all others placed at the base of the tree, and because I applied a strict tree 201 cutting method with the hierarchical methods to obtain discrete clusters, the tree cutting method 202 then identified this single distant sample as an individual cluster. However, the treatment of 203 outliers is challenging in all clustering approaches, and their exclusion may not be possible or 204 desirable. A similar situation, where outliers have an undue influence on group composition, is

205 likely why complete linkage and UPGMA are also less effective than *k*-means or NERC.

206 These hierarchical methods are well suited to applications such as phenetic analyses or 207 phylogenetics, where a single ancestor (theoretically) gives rise to multiple descendants. 208 However, this one-to-many structure often translates poorly to species occurrence data sets like 209 those commonly used in biogeographic studies, where individual lineages may be operating in 210 parallel and independently (Brown, 1999). Individual species may originate in different locations 211 and disperse by various methods to new regions (Brown, 1999), leading to a more reticulate, 212 many-to-many relationship. In this case, a method that does not enforce a hierarchy may better 213 represent the relationships present.

214 Further, species occurrence data is typically non-Euclidean in nature. Whereas all the cells in a phylogenetic data matrix represent a directly observed value, in a species occurrence 215 216 matrix any cell that has a zero value may be due to either the species not occurring in that area or 217 incomplete sampling, two possibilities that may be indistinguishable from one another. To deal 218 with incomplete sampling, most species occurrence data sets are converted into a distance 219 matrix, where the species composition of each sample is compared to every other sample using 220 an index of similarity (or dissimilarity); yet, while most of these measures provide some measure 221 of distance, these distances are not necessarily Euclidean (Gower and Legendre, 1986). The 222 benefit of using non-Euclidean measures over Euclidean distances is readily observable in this 223 study, with the non-Euclidean based k-means outperforming the Euclidean based k-means.

224 Although for this study, the Sørensen dissimilarity index was used, the choice of which 225 non-Euclidean dissimilarity index to use is not necessarily straightforward (e.g. Shi 1993; 226 Magurran 2004; Alroy 2015). By some counts, dozens of different dissimilarity indices have 227 been proposed in the literature (Hubálek 1982; Pielou 1984; Shi 1993), although only a handful 228 of these have entered into common use (Magurran 2004). While alternative methods, such as a 229 recent modification to the Forbes metric (Alroy 2015), have been proposed as replacements to 230 more traditional dissimilarity metrics, the choice of measure is a separate question to the issue in 231 the present study. Although using other dissimilarity measures may have changed the individual 232 effectiveness of the different clustering methods, the relative performance of the clustering 233 methods to each other is unlikely to change, as even with different measures the problems of 234 outliers and hierarchical/non-hierarchical methods would persist.

Both poor differentiation between clusters and inadequate sampling are common

problems with palaeobiological data. No method is entirely immune to either of these issues, but

- 237 overall, based on these simulations, *k*-means and NERC give more reliable and accurate results
- when data are less than robust. Using these methods still does make one strong assumption about
- the underlying data namely, that true divisions within the data exist. Unfortunately, with the
- 240 often muddled and noisy nature of biogeographic data, this assumption is also the hardest to
- 241 objectively determine.

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246

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336	

## 337 Figure captions

338 Figure 1. Visualization of the changing endemicity of clusters (i.e. distinctiveness) and how it 339 alters the clustering of sites in an NMDS plot for the simulated biogeographic data sets. 'e' is the proportion of all species that are endemic to only one biogeographic region. A higher proportion 340 of endemics results in more distinctive clusters, while a lower proportion of endemics results in 341 342 less distinctive clusters. 343 344 Figure 2. Response of various clustering methods to the distinctiveness of clusters as given by 345 the proportion of endemics (i.e. a higher endemicity creates more highly differentiated clusters). 346 The values for each method at any given level of endemicity is the average Adjusted Rand Index 347 comparing the known solution and the calculated solution over 1000 simulations. 348 349 Figure 3. Accuracy of various clustering methods in response to changing levels of sampling 350 intensity (coverage). Overall, as sampling intensity decreases (to the right), clustering becomes

- 351 less reliable. The values for each method at any given level of sampling is the average Adjusted
- 352 Rand Index comparing the known solution and the calculated solution over 1000 simulations.

## Figure 1(on next page)

Variation in group distinctiveness for simulated data.

Visualization of the changing endemicity of clusters (i.e. distinctiveness) and how it alters the clustering of sites in an NMDS plot for the simulated biogeographic data sets. 'e' is the proportion of all species that are endemic to only one biogeographic region. A higher proportion of endemics results in more distinctive clusters, while a lower proportion of endemics results in less distinctive clusters.



## Figure 2(on next page)

Comparison of cluster methods with varying group distinctiveness.

Response of various clustering methods to the distinctiveness of clusters as given by the proportion of endemics (i.e. a higher endemicity creates more highly differentiated clusters). The values for each method at any given level of endemicity is the average Adjusted Rand Index comparing the known solution and the calculated solution over 1000 simulations.



Relative Endemicity
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## Figure 3(on next page)

Comparison of cluster methods with varying sampling intensity.

Accuracy of various clustering methods in response to changing levels of sampling intensity (coverage). Overall, as sampling intensity decreases (to the right), clustering becomes less reliable. The values for each method at any given level of sampling is the average Adjusted Rand Index comparing the known solution and the calculated solution over 1000 simulations.



 Sampling Intensity

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