

Simulating highly disturbed vegetation distribution: the case of China's Jing-Jin-Ji region

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Background. Simulating vegetation distribution is an effective method for identifying vegetation distribution patterns and trends. The primary goal of this study was to determine the best simulation method for a vegetation in an area that is heavily affected by human disturbance.

Methods. We used climate, topographic, and spectral data as the input variables for four machine learning models (random forest (RF), decision tree (DT), support vector machine (SVM), and maximum likelihood classification (MLC)) on three vegetation classification units (vegetation group (I), vegetation type (II), and formation and subformation (III)) in Jing-Jin-Ji, one of China's most developed regions. We used a total of 2,789 vegetation points for model training and 974 vegetation points for model assessment.

Results. Our results showed that the RF method was the best of the four models, as it could effectively simulate vegetation distribution in all three classification units. The DT method could only simulate vegetation distribution in units I and II, while the other two models could not simulate vegetation distribution in any of the units. Kappa coefficients indicated that the DT and RF methods had more accurate predictions for units I and II than for unit III. The three vegetation classification units were most affected by six variables: three climate variables (annual mean temperature, mean diurnal range, and annual precipitation), one geospatial variable (slope), and two spectral variables (Mid-infrared ratio of winter vegetation index and brightness index of summer vegetation index). Variables Combination 7, including annual mean temperature, annual precipitation, mean diurnal range and precipitation of driest month, produced the highest simulation accuracy.

Conclusions. We determined that the RF model was the most effective for simulating vegetation distribution in all classification units present in the Jing-Jin-Ji region. The RF model produced high accuracy vegetation distributions in classification units I and II, but relatively low accuracy in classification unit III. Four climate variables were sufficient for vegetation distribution simulation in such region.

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15

16 Abstract

17 **Background.** Simulating vegetation distribution is an effective method for identifying
18 vegetation distribution patterns and trends. The primary goal of this study was to determine the
19 best simulation method for a vegetation in an area that is heavily affected by human disturbance.

20 **Methods.** We used climate, topographic, and spectral data as the input variables for four
21 machine learning models (random forest (RF), decision tree (DT), support vector machine
22 (SVM), and maximum likelihood classification (MLC)) on three vegetation classification units
23 (vegetation group (I), vegetation type (II), and formation and subformation (III)) in Jing-Jin-Ji,
24 one of China's most developed regions. We used a total of 2,789 vegetation points for model
25 training and 974 vegetation points for model assessment.

26 **Results.** Our results showed that the RF method was the best of the four models, as it could
27 effectively simulate vegetation distribution in all three classification units. The DT method could
28 only simulate vegetation distribution in units I and II, while the other two models could not
29 simulate vegetation distribution in any of the units. Kappa coefficients indicated that the DT and
30 RF methods had more accurate predictions for units I and II than for unit III. The three
31 vegetation classification units were most affected by six variables: three climate variables
32 (annual mean temperature, mean diurnal range, and annual precipitation), one geospatial variable
33 (slope), and two spectral variables (Mid-infrared ratio of winter vegetation index and brightness
34 index of summer vegetation index). Variables Combination 7, including annual mean
35 temperature, annual precipitation, mean diurnal range and precipitation of driest month,
36 produced the highest simulation accuracy.

37 **Conclusions.** We determined that the RF model was the most effective for simulating vegetation
38 distribution in all classification units present in the Jing-Jin-Ji region. The RF model produced
39 high accuracy vegetation distributions in classification units I and II, but relatively low accuracy

40 in classification unit III. Four climate variables were sufficient for vegetation distribution
41 simulation in such region.

42

43 **Introduction**

44 Vegetation is an essential component of terrestrial ecosystems and landscapes (Editorial
45 Committee of Vegetation Map of China, Chinese Academy of Science, 2007). Environmental
46 research, resource management, and conservation planning require vegetation distribution maps
47 (Franklin, 2010) to better understand, use, and monitor vegetation. Vegetation patterns and
48 distributions are affected by the climate (Chen et al., 2015; Zhang et al., 2018) and other
49 disturbances, particularly those caused by changes in land use (Hansen et al., 2013; Wehkamp et
50 al., 2018). Human disturbances, such as industrialization, urbanization, population growth, land
51 use change for agricultural use, etc., strongly influence the environment by greatly altering
52 vegetation patterns, making exact mapping a significant challenge (Xie, Sha, & Yu, 2008; Zhou
53 et al., 2016).

54 Field surveys, the traditional method used to map vegetation, are costly and labor-intensive
55 (Newell & Leathwick, 2005; Zhou et al., 2016). Mapping using remote sensing data is also a
56 popular method that has been used over the last 30 years (Xie, Sha, & Yu, 2008). This method
57 makes it possible to obtain a wide range of reliable data from remote sensing images, and it
58 updates vegetation boundaries by visually interpreting images and field surveys (Zhang et al.,
59 2008). However, determining vegetation units and their boundaries by visual interpretation can
60 produce inaccurate results. Researchers may get different results from the same images for the
61 same study areas (Bie & Beckett, 1973; Pfeffer, Pebesma, & Burrough, 2003). Furthermore, field
62 survey and remote sensing methods manually draw vegetation unit boundaries based on climate,
63 elevation, and soil type information, which can be inaccurate in transition areas (Zhang et al.,
64 2008). Using simulation models in combination with field and remote sensing data may be an
65 effective alternative for mapping vegetation.

66 Changes in the environment can affect vegetation composition, structure, function, and spatial
67 distribution. Environmental variables have been used to simulate the global distribution of
68 vegetation (Dilts et al., 2015; Mod et al., 2016). Simulation models are usually developed to test
69 how environmental variables control vegetation distribution (Guisan & Zimmermann, 2000).
70 Modern remote sensing data and software make it more convenient than ever before to produce
71 predictive vegetation maps (Franklin, 1995).

72 Predictive vegetation mapping uses environmental variables and various models based on
73 niche theory and gradient analysis to visualize communities in geographic space (Dilts et al.,
74 2015, Lany et al., 2019). Other methods based on statistics and machine learning have also been
75 used to simulate vegetation distribution. Predictive vegetation mapping includes various
76 statistical methods such as the generalized linear model, the generalized additive model, and
77 multivariate statistical approaches (Lany et al., 2019; Prasad, Iverson, & Liaw, 2006). Recently,
78 machine learning modeling methods have been used to map the distribution of both vegetation
79 communities and individual species. These methods include the support vector machine (SVM),

80 decision tree (DT), and artificial neural network (Guisan & Zimmermann, 2000; Hastie,
81 Tibshirani, & Friedman, 2009; Zhou et al., 2016). These machine learning models have fewer
82 limitations and can produce more reliable results than traditional vegetation modeling methods
83 (Hastie, Tibshirani, & Friedman, 2009). Advanced machine learning techniques can integrate
84 spectral and spatial predictors and improve classification accuracy by retaining important
85 information about vegetation composition and structural differences (Sesnie et al., 2010).
86 Machine learning models efficiently and cost-effectively produce vegetation maps without the
87 general inaccuracies caused by visual interpretation (Franklin, 2010).

88 The Jing-Jin-Ji region, also known as the Beijing-Tianjin-Hebei urban agglomeration, is the
89 center of northern Chinese politics, culture, and economy. Because of its extension, it faces
90 significant problems such as unbalanced regional development and the struggle between
91 economic growth and limited resources. The region's larger cities, including Beijing and Tianjin,
92 have large populations, developed economies, and abundant educational resources. However,
93 these big cities face issues of limited natural resources and serious ecological and environmental
94 pollution. In particular, Beijing's large population requires limited resources such as water, land,
95 and vegetation (Wang & Gong, 2018). Breaking up administrative divisions may be the best
96 method to coordinate regional development (Wang et al., 2019). The new Xiong'an area located
97 in Hebei province is being constructed to relocate some of Beijing's population. The
98 development of areas like Xiong'an is affected by the surrounding natural environment. To better
99 integrate the environmental carrying capacity and socioeconomic development of the Jing-Jin-Ji
100 region, including the new Xiong'an area, accurate vegetation maps with temporal resolution are
101 necessary. The most updated vegetation map of the Jing-Jin-Ji region is the Vegetation Map of
102 the People's Republic of China (VMC), with a scale of 1:1,000,000 (Editorial Committee of
103 Vegetation Map of China, Chinese Academy of Science, 2007). Most of its data come from a
104 field survey conducted between 1980 and 1990, meaning its temporal and spatial scales are both
105 outdated.

106 In this study, we integrated geospatial, climate, and spectral data to simulate vegetation
107 distribution through four different models across three vegetation classification units. This
108 research was different from the research of Zhou et al. (2016). Firstly, the research area of this
109 research was the Jing-Jin-Ji region located in the North China Plain and affected by high social-
110 economic disturbance, while the Qilian Mountain in the research of Zhou et al. is characterized
111 by complex terrain, but without high social-economic disturbance. Secondly, the predictive
112 variables as well as the combinations of these variables were different from the research of Zhou
113 et al. (2016). Thirdly, we compared four model methods for simulating distribution of vegetation
114 in three vegetation classification levels, while only three models were used for simulation in two
115 vegetation classification levels in the research of Zhou et al. (2016). Our primary objectives were
116 to: (1) determine the best modeling method for vegetation affected by high socioeconomic
117 disturbance, (2) create an improved vegetation map of the Jing-Jin-Ji region, (3) determine the
118 predictive abilities of different models across different vegetation classification units, and (4)
119 determine which variables enhanced the classification accuracy for vegetation mapping.

120

121 **Materials & Methods**

122 **Study area**

123 The Jing-Jin-Ji region is located in the northern part of the North China Plain. Its location ranges
124 from 113°04' to 119°53'E and 36°01' to 42°37'N and is bordered by Taihang Mountain in the
125 west, Yanshan Mountain in the north, and the Bohai Sea in the east. The region includes the
126 Beijing, Tianjin, and Hebei provinces (Fig. 1). Jing-Jin-Ji has a population of approximately 110
127 million people and covers an area of approximately 216,000 km² (Wang et al., 2019). The region
128 is a temperate monsoon climate zone with an elevation range of -14 to 2,837 m (Fig. 1). The
129 annual precipitation ranges from 305 to 711 mm, with increased precipitation at lower altitudes.
130 The annual mean temperature ranges from -3 to 14°C, with colder averages at higher elevations.
131 The amount of precipitation in the region gradually decreases moving from the southeast to the
132 northwest, while temperature changes show the reverse pattern.

133

134 **Vegetation and training data**

135 The VMC, completed in 2007 based on field survey data, included eight vegetation groups (I),
136 15 vegetation types (II), and 75 formations and subformations (III) from the Jing-Jin-Ji region.
137 However, some of the map's vegetation unit areas are very small and difficult to distinguish. To
138 ensure that enough training and assessment point data can be randomly selected in units II and
139 III, we selected eight units I, 12 units II, and 39 units III from the study area (Table 1).
140 Cultivated vegetation are mainly distributed in low areas with an altitude range of -14 to 254 m
141 and an annual mean temperature range of 7 to 14°C. Major cultivated plants include winter wheat
142 and coarse grains. Scrub and grass-forb communities are mainly distributed in the north, in
143 elevations ranging from 254 to 1,440 m.

144 We obtained model training and assessment data on vegetation composition from field surveys
145 and other publications. We collected a total of 3,763 vegetation points, with 2,789 of those used
146 for model training and 974 used for model assessment. Each unit III had at least 80 vegetation
147 points, with at least 60 of those used for model training and 20 used for model assessment. The
148 model training and assessment data were randomly selected for each unit III. Additionally, we
149 increased the credibility of the model assessment by first rasterizing the vector VMC onto the
150 same grid as the modeled data, and then assessing the data using the Kappa coefficient (Landis &
151 Koch, 1977; Weng & Zhou, 2006; Zhou et al., 2016).

152

153 **Geospatial, climate, and spectral data**

154 We derived geospatial variables, including elevation, slope, and aspect, from the 30 m resolution
155 Shuttle Radar Topography Mission (SRTM) digital elevation model (DEM; Zhao et al., 2018).
156 We then resampled these data to a 500×500 m grid cell size using the cubic technique in ArcGIS
157 10.3 (Wu et al., 2019).

158 We downloaded the climate data, including 19 bioclimatic variables, at ~1 km resolution from
159 WorldClim (Fick & Hijmans, 2017) at <http://worldclim.org/>. These climate data were also

160 resampled to a 500×500 m grid cell size using the cubic technique in ArcGIS 10.3 (Wu et al.,
161 2019). Climatic variables are important for plant ecophysiology (Mod et al., 2016) and are
162 commonly used as bioclimatic limits in vegetation models (Sitch et al., 2003).

163 We acquired the MYD09A1500M product data (sinusoidal projection, path 4 and row 26, path
164 4 and row 27, path 5 and row 26, path 5 and row 27) from summer (July 20, 2013) and winter
165 (January 17, 2013) as Modis images from the Geospatial Data Cloud at <http://www.gscloud.cn/>.
166 Our image pre-processing included image subset mosaicking and clipping in ENVI 5.2 (Deng,
167 2010). We obtained the land surface albedo in bands 1-7 directly from the MYD09A1500M
168 product, and calculated the indices' effectiveness at reflecting vegetation information (Price,
169 Guo, & Stiles, 2002; Zhou et al., 2016).

170 Since vegetation indices can provide information on both vegetation and environment
171 (Bannari, Morin, & Bonn, 1995), these indices are more sensitive than single spectral bands at
172 detecting green vegetation (Bannari, Morin, & Bonn, 1995; Cohen & Goward, 2004). Therefore,
173 vegetation indices can be used for image interpretation, vegetation discrimination and prediction,
174 and land use change detection (Bannari, Morin, & Bonn, 1995; Cohen & Goward, 2004; Zhou et
175 al., 2016). We tested the vegetation discrimination of 14 vegetation indices (Table 2).

176 To determine the distribution predictive ability of different variables, we grouped the variables
177 into different combinations based on the results of the Pearson correlation. We only used less
178 correlated variables ($R < |0.7|$, Pearson correlation) (Chala et al., 2017) in Combinations 1-9
179 (Table 3), then used variable combinations as input predictor variables to simulate vegetation
180 distribution. Combination 1 included the less correlated variables of the summer land surface
181 albedos from bands 1 to 7. Combination 2 included the less correlated variables of the winter
182 land surface albedos from bands 1 to 7. Combination 3 included the less correlated variables in
183 Combinations 1 and 2. Combination 4 included the less correlated variables of the summer
184 vegetation indices. Combination 5 included the less correlated variables of the winter vegetation
185 indices. Combination 6 included the less correlated variables in Combinations 4 and 5.
186 Combination 7 included the less correlated variables from the 19 bioclimatic variables.
187 Combination 8 included the less correlated variables from the 19 bioclimatic variables and three
188 geospatial variables. Combination 9 included the less correlated variables in Combinations 3, 6,
189 and 8. Combinations 10 and 11 represented the top 10 most important variables of the DT and
190 RF methods, with Combination 9 in vegetation unit I, respectively (Table 3). The SVM and
191 maximum likelihood classification (MLC) methods only output the simulation results of variable
192 Combinations 1 to 6, likely due to the training samples' weak separability (Deng, 2010).

193

194 **Vegetation distribution models**

195 We used DT, RF, MLC, and SVM vegetation distribution models in this study. The DT model is
196 a divisive, monothetic, and supervised classifier often used for species distribution modeling and
197 related applications (Franklin, 2010). It is computationally fast and easy to understand and
198 implement. It uses classification or regression algorithms to generate classification rules, and
199 then visualizes those rules into simple tree graphics (Hastie, Tibshirani, & Friedman, 2009; Zhou

200 et al., 2016). The DT model calculates the most significant variables contributing to the model
201 (Deng, 2010). We used a DT with five layers, 40 samples in the smallest parent node, and 10
202 samples in the smallest child node.

203 The RF model is an ensemble method that has been applied in risk assessment and species
204 distribution modeling studies (Cutler et al., 2007; Zhang & Dong, 2017). The RF model creates
205 and combines different DTs to produce considerably more accurate classifications that are
206 unaffected by noise or overtraining (Burai et al., 2015; Cutler et al., 2007; Gislason,
207 Benediktsson, & Sveinsson, 2006). The RF model also calculates the most significant variables
208 that contribute to the model (Cutler et al., 2007). Running an RF model requires defined
209 parameters, including tree number, number of randomly selected features, and node impurity
210 function. We generated the RF model in EnMAP-Box, a license-free and platform-independent
211 software interface designed to process hyperspectral remote sensing data, which was developed
212 by the Humboldt University of Berlin. There are in-built applications aimed at the processing of
213 hyperspectral data, such as SVM and RF for classification of image data in the EnMAP-Box
214 (Held et al., 2014). We used the default settings in EnMAP-Box with 100 trees. The number of
215 randomly selected features was equal to the square root of the number of all features, and we
216 used a Gini coefficient for the node impurity function (Jakimow et al., 2014; Ma, Gao, & Gu,
217 2019; van der Linden et al., 2015; Zhou et al., 2016).

218 The MLC model is one of the most commonly used supervised image classification methods.
219 MLC's classification rules use the statistics of the Gaussian probability density function to assign
220 each pixel to the class with the highest probability. Although the MLC method usually generates
221 similar or more accurate classifications than other methods, it is not applicable when there are
222 fewer training samples than input predictors (Burai et al., 2015; Zhou et al., 2016).

223 The SVM model is a supervised machine learning model used for classification and
224 regression. It is a complex and widely used method that can output more accurate predictions
225 (Burai et al., 2015) than other methods. The SVM model searches for an optimal plane in a
226 multidimensional space to divide all sample elements into two categories, making the distance
227 between the closest points in the two classes as large as possible (Kabacoff, 2016). Running an
228 SVM model requires a defined kernel parameter g and regularization parameter c . In this study,
229 we generated the SVM model in the EnMAP-Box. The default settings in EnMAP-Box to the
230 SVM model was applied, where the parameter g was 0.01 to 1,000, and the parameter c was 0.1
231 to 1,000. Parameters g and c were tested using a grid search with internal performance
232 estimation, and we used those with the best performance for data training (Lin et al., 2014; van
233 der Linden et al., 2014; van der Linden et al., 2015).

234 We generated the predicted vegetation maps of the three classification units using the DT, RF,
235 MLC, and SVM methods with a resolution of 500 m. We selected all 11 variable combinations
236 as the input variables for each method. The DT and RF method results indicated which variables
237 were most important for vegetation discrimination.

238

239 **Model assessment**

240 We used the VMC and a total of 974 vegetation points to assess the overall accuracy and Kappa
241 coefficient of every predicted vegetation map. Kappa coefficient values ranging from 0.4 to 0.55
242 indicated moderate agreement, from 0.56 to 0.8 indicated substantial agreement, and from 0.81
243 to 1 indicated almost perfect agreement (Landis & Koch, 1977; Weng & Zhou, 2006; Zhou et al.,
244 2016). When the Kappa coefficient value was greater than 0.4, the assessed predicted map was
245 considered acceptable.

246

247 **Results**

248 **Unit I modeling and assessment**

249 The RF model's results were better than the results of the DT, MLC, and SVM models (Table 4).
250 The RF model had a Kappa coefficient larger than 0.4 when using variable Combinations 6 to 11
251 assessed by field point data, with an overall accuracy of 50% to 72%. The RF model had a
252 Kappa coefficient larger than 0.56 when using variable Combinations 7 to 11 assessed by field
253 data, with an overall accuracy of 68% to 72%. The RF model had the highest Kappa coefficient
254 of 0.66 and the highest overall accuracy of 72% when using variable Combination 7. The DT
255 model had a Kappa coefficient larger than 0.4 when using variable Combinations 7 to 11
256 assessed by field point data, with an overall accuracy of 54% to 56%. The DT model had no
257 Kappa coefficient larger than 0.56 when using all variable combinations. After VMC assessment,
258 we found the highest Kappa coefficient was 0.38 with an overall accuracy of 57% in the RF
259 model using variable Combinations 9 to 11 (Table 4; Fig. 2).

260

261 **Unit II modeling and assessment**

262 The RF model results were better than the results of the other three models. The RF model using
263 variable Combinations 7 to 11 had a Kappa coefficient larger than 0.4, with overall accuracies of
264 66%-70% and 54%-55% for field point data and VMC assessments, respectively. The RF model
265 using Combinations 7 to 11 had a Kappa coefficient larger than 0.56 and an overall accuracy of
266 66%-70% when assessed by field point data. The RF model had the highest Kappa coefficient of
267 0.65 and the highest overall accuracy of 70% when using variable Combination 7. The DT model
268 using variable Combinations 7 to 11 had a Kappa coefficient larger than 0.4, with overall
269 accuracies of 53%-55% and 65%-72% for field point data and VMC assessments, respectively.
270 The DT model had the highest Kappa coefficient of 0.54 and overall accuracy of 72% when
271 using variable Combination 7. The DT model had a larger Kappa coefficient and greater overall
272 accuracy when assessed by VMC rather than the RF model (Table 5; Fig. 3).

273

274 **Unit III modeling and assessment**

275 Only the RF model could simulate vegetation distribution in unit III. The RF model using
276 variable Combinations 7 to 11 had a Kappa coefficient larger than 0.4 and an overall accuracy of
277 55%-58% assessed by field point data. The RF model using variable Combination 7 had the
278 highest Kappa coefficient of 0.57 (the only model with a Kappa coefficient larger than 0.56) and

279 the highest overall accuracy of 58% assessed by field point data. The Kappa coefficients in all
280 models were less than 0.4 when assessed by the VMC (Table 6; Fig. 4).

281

282 **Important variables**

283 For the RF model, eight of the top 10 most important variables were the same across the different
284 vegetation units: three climate variables (annual mean temperature, mean diurnal range, and
285 annual precipitation), one geospatial variable (slope), and four spectral variables (Mid-infrared
286 ratio and NDVI of winter vegetation index, brightness index and NDVI of summer vegetation
287 index). For the DT model, nine of the top 10 most important variables were the same across the
288 different vegetation units: four climate variables (annual mean temperature, mean diurnal range,
289 precipitation of the driest month, and annual precipitation), one geospatial variable (slope), and 4
290 spectral variables (Mid-infrared ratio of winter vegetation index, brightness index of summer
291 vegetation index, summer surface albedo of band 1, winter surface albedo of band 6) (Table 7).

292

293 **Discussion**

294 **Vegetation classification units**

295 Vegetation classification is an important and complex system with multiple levels. Higher level
296 classification methods not only accurately classify vegetation, but they can also describe
297 ecosystem diversity, even during global changes (Faber-Langendoen et al., 2014). Plants in
298 different vegetation classification units have different spectral characteristics and climatic
299 conditions that are the basis for vegetation distribution simulation. Thus, models using the same
300 variables to simulate the vegetation distribution of different classification units may produce
301 different classification accuracies (Dobrowski et al., 2008; Prasad, Iverson, & Liaw, 2006). Map
302 accuracy has been found to be a function of which classification system and categories are used
303 (Muchoney et al., 2000).

304 Previous studies have explored vegetation distribution simulation using different vegetation
305 classification systems. Plant functional types (PFTs), defined as plant sets sharing similar
306 perturbation response effects on dominant ecosystem processes, have been used to simulate
307 vegetation distribution, as seen in the Biome and Box system models (Box, 1981; Box, 1996;
308 Dormann & Woodin, 2002) with positive simulation results (Box, 1981; Song, Zhou & Ouyang,
309 2005; Weng & Zhou, 2006). The Mapped Atmosphere-Plant-Soil System (MAPSS) model was
310 also used to simulate vegetation distribution using vegetation life forms, leaf area index, leaf
311 morphology, and leaf longevity (Zhao et al., 2002). Other researchers studied potential
312 vegetation distribution using the Holdridge life zone model, with positive vegetation pattern
313 results (Zheng et al., 2006). When the IGBP classification system was applied to simulate
314 vegetation distribution at a regional scale, the map estimate accuracy was upwards of 80%
315 (Muchoney et al., 2000). In this study, we used machine learning models and a hierarchical
316 classification system from the VMC to determine the best modeling method for vegetation
317 affected by high socioeconomic disturbance at various classification levels. In the VMC, unit I
318 was the highest classification level, mainly based upon community appearance; unit II was the

319 second highest level, mainly based upon community and climate appearance; and unit III was the
320 medium classification level, based upon the dominant species. The accuracy of the vegetation
321 distribution simulations in units I and II was similar to each other and higher than unit III's
322 simulation (Tables 4-6).

323

324 **Different model performances**

325 We were interested in vegetation distribution modeling's ability to forecast and respond to
326 environmental changes and vegetation pattern management at local to global scales. Vegetation
327 distribution predictions can help explain the relationship between plants and their abiotic and
328 biotic environments (Franklin, 2010). To benefit from ecosystem service functions, people can
329 design vegetation distributions according to distribution and abundance patterns and trends
330 (Hastie, Tibshirani, & Friedman, 2009). Vegetation classification has become a widely used
331 ecological method due to a number of new statistical and machine learning methods used
332 alongside mapped biological and environmental data to model vegetation distributions over large
333 spatial scales at higher resolutions (Cutler et al., 2007). Different image classification methods
334 are rarely used together in the same classification research, especially when combined with
335 environmental variables (Li et al., 2014).

336 In this study, the RF model performed better than the DT, SVM, and MLC models across the
337 three classification levels. This finding was consistent with the results of other studies that found
338 that the RF method modeled vegetation distribution better than other methods (Prasad, Iverson,
339 & Liaw, 2006). The DT model divided the data into homogenous subgroups according to the
340 range of predictor variable values. The DT model was generally able to handle a large number of
341 independent variables and could build a tree model faster than the other methods. However, the
342 DT model was somewhat unstable for vegetation distribution modeling and had lower
343 classification accuracy (Zhou et al., 2016). The RF model generated a large number of
344 independent trees through data subsets and developed a split in every tree model using a random
345 subset of predictor variables. Therefore, we concluded that the RF model was generally better
346 than the DT model. The SVM model was developed from statistical learning methods and
347 discriminated class samples by locating potentially nonlinear or multiple linear boundaries
348 between individual training points (Burai et al., 2015). The aim of the MLC model was to
349 maximize the overall probability that a pixel is correctly assigned to a class. However, the MLC
350 model requires a large number of training samples that limits its application (Sesnie et al., 2010).
351 Previous research has shown that classification accuracies when using the SVM classifier were
352 higher than the MLC model (Pal & Mather, 2005; Boyd, Sanchez-Hernandez, & Foody, 2006;
353 Sanchez-Hernandez, Boyd, & Foody, 2007; Sesnie et al., 2010). Because the model had fewer
354 requirements, the DT method provided significantly more accurate classifications than those of
355 the MLC model (Boyd, Sanchez-Hernandez, & Foody, 2006). Other studies found that the RF
356 and SVM models were similarly accurate (65.3% and 66.6%, respectively) (Sesnie et al., 2010),
357 and that the RF, MLC, DT, and SVM models performed similarly and reasonably well when
358 simulating land use classification (Li et al., 2014). In addition to the methods mentioned above,

359 an artificial neural network implemented at a regional scale produced classification accuracies of
360 60%-80% (Muchoney et al., 2000; Haslem et al., 2010). In the Arctic, this method provided the
361 most accurate vegetation mapping (Langford et al., 2019). The reasons for the similarly positive
362 results of these models may be due to the relatively large differences between classification
363 objects, and their use of sufficiently representative training samples and appropriate input
364 variables. In our study, only the SVM and MLC models' output simulated the results of variable
365 Combinations 1 to 6. This may be due to the poor separability of the training samples, as the
366 models could not recognize the training points or their vegetation categories (Jarnevich et al.,
367 2015). The Jing-Jin-Ji region has many types of vegetation with very small distribution areas, so
368 the selected training points may have been insufficient. Future training points for these
369 vegetation types should be selected using field surveys, and more suitable models for modeling
370 global vegetation distribution should be developed and tested (Jiang et al., 2012).

371

372 **Important variables in vegetation classification models**

373 Variable selection is directly related to the vegetation distribution model's ability to capture
374 important environmental factors (Mod et al., 2016). Models predict the important variables that
375 drive the distribution of vegetation (Prasad, Iverson, & Liaw, 2006). Vegetation distribution is
376 predominantly driven by temperature, precipitation, and topographical variables (Franklin, 1995;
377 Mod et al., 2016; Prasad, Iverson, & Liaw, 2006), specifically those related to physiological
378 tolerance, site energy, and moisture balance (Franklin, 1995). In addition to environmental
379 variables, some spectral variables are used as input variables. However, the overuse of spectral
380 variables can actually decrease discrimination accuracy, meaning that only spectral variables
381 reflecting vegetation information should be selected, such as those related to the visible
382 spectrum, infrared spectrum, and vegetation indices (Price, Guo, & Stiles, 2002, Zhou et al.,
383 2016). Different variables respond to different information. Spectral variables directly reflect
384 land surface object information, while geospatial and climatic variables reveal information about
385 the vegetative environment.

386 Terrain, an important variable in vegetation distribution models, has long been used to
387 improve map accuracy, especially for regions with large elevation differences (Dobrowski et al.
388 2008; Oke & Thompson, 2015). Sesnie et al. (2010) found that adding elevation as a predictive
389 variable dramatically improved the accuracies of the SVM and RF models >80% for most forest
390 types. Slopes with similar elevations but different aspects have very different soil and vegetation
391 temperatures (Gunton, Polce, & Kunin, 2015; Mod et al., 2016). Dobrowski et al. (2008)
392 highlighted the importance of slope and aspect when mapping vegetation communities in the
393 Sierra Nevada. Slope was also an important variable in this study (Table 7) since different types
394 of vegetation require different precipitation and temperature levels and have different tolerances
395 to extreme heat and cold. The significance of these climate variables (annual mean temperature,
396 temperature range, and annual precipitation) has been validated in other studies (Prasad, Iverson
397 & Liaw, 2006; Sesnie et al., 2008). We looked at two surface albedo indices (the summer surface
398 albedo of band 1 and the winter surface albedo of band 6). Sesnie et al. (2010) combined

399 elevation and spectral band data to increase the classification accuracy to a satisfactory level for
400 most forest types. De Colstoun et al. (2003) obtained high accuracies (80%) when classifying
401 coniferous, temperate broad-leaf, and mixed forest types using Landsat ETM+ bands. Other
402 studies have used different vegetation index variables (Price, Guo & Stiles, 2002; Zhou et al.,
403 2016) specific to their study areas and data.

404 The input variables used in our vegetation distribution model are not exhaustive.
405 Ecophysiological meaningful predictors such as soil moisture, pH, and nutrients, should be
406 considered. Other factors, such as actual light, disturbance, biotic interactions, land use, and
407 bioclimatic information could also be incorporated into vegetation distribution models
408 (Dobrowski et al., 2008; Mod et al., 2016; Prasad, Iverson, & Liaw, 2006; Sesnie et al., 2010).
409 We suggest building more ecophysiological sound vegetation distribution models that require a
410 collaborative effort across the ecological, geographical, and environmental sciences (Mod et al.,
411 2016).

412

413 **Other factors affecting classification accuracy**

414 In addition to classification units, models, and input variables, classification accuracy is affected
415 by other factors, including algorithm error and image data (Li et al., 2014). We must
416 acknowledge the existence of errors in random sample selection, modeling, and data
417 preprocessing algorithms. Remote sensing data sources, as well as the date and processing of
418 selected images, vary, resulting in different simulated values and accuracies (Price, Guo, &
419 Stiles, 2002). Remote sensing images with high spectral and spatial resolutions provide rich
420 spectral and ground information, moderately improving the predictive ability of the vegetation
421 distribution model (Peng et al., 2002). However, the use of high spectral and spatial resolution
422 images creates a greater demand for data access, larger computer storage capacities, and faster
423 data processors (Price, Guo, & Stiles, 2002), which is why we did not use high spectral and
424 spatial resolution images in this study. Moreover, some cultivated vegetation and shelter forests
425 in the Jing-Jin-Ji region are greatly affected by human disturbance, which affects their water-heat
426 conditions and soil nutrition. Urbanization reduces vegetation, transforming some areas into
427 industrial, commercial, and residential land. This has led to the direct or indirect pollution of the
428 water, soil, and air, and the reduced predictive ability of vegetation distribution models. The
429 VMC we used for model assessment was published in 2007, and no updated study has been
430 published over the past 10 years. The current state of the Jing-Jin-Ji region's vegetation no
431 longer coincides with the VMC's assessment.

432

433 **Conclusions**

434 Our main objective was to determine the best simulation method for vegetation affected by high
435 socioeconomic disturbance in the Jing-Jin-Ji region. The RF model was the most capable at
436 simulating vegetation distribution across all three units. The DT model could simulate the
437 vegetation distribution in units I and II. The SVM and MLC models could not simulate the
438 distribution in any of the three units. Based on the Kappa coefficient, the RF model was

439 generally better than the DT model and the most suitable model for simulating vegetation
440 distribution in the Jing-Jin-Ji region. The most important variables affecting vegetation
441 classification accuracy were three climate variables (annual mean temperature, mean diurnal
442 range, and annual precipitation), one geospatial variable (slope), and two spectral variables (Mid-
443 infrared ratio of winter vegetation index and brightness index of summer vegetation index). We
444 recommend using the RF model to produce or improve the vegetation maps in areas of high
445 human disturbance.

446

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449

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Table 1 (on next page)

Classification units of the vegetation of China

1 **Table 1: Classification units of the vegetation of China**

Vegetation groups (I)	Vegetation types (II)	Formations and sub-formations (III)
0. No vegetation	0 No vegetation	0 No vegetation
1. Needleleaf forest	1 Temperate needleleaf forest	1 <i>Pinus tabulaeformis</i> forest
2. Broadleaf forest	2 Temperate broadleaf deciduous forest	2 <i>Quercus mongolica</i> forest 3 <i>Quercus liaotungensis</i> forest 4 <i>Quercus variabilis</i> forest 5 <i>Robinia pseudoacacia</i> forest 6 <i>Salix matsudana</i> forest 7 <i>Populus davidiana</i> forest 8 <i>Betula platyphylla</i> forest
3. Scrub	3 Temperate broadleaf deciduous scrub	9 <i>Corylus heterophylla</i> scrub 10 <i>Lespedeza bicolor</i> scrub 11 <i>Prunus armeniaca</i> var. <i>ansa</i> scrub 12 <i>Vitex negundo</i> var. <i>heterophylla</i> , <i>Zizyphus jujuba</i> var. <i>spinosa</i> scrub 13 <i>Cotinus coggygria</i> var. <i>cinerea</i> scrub 14 <i>Spiraea</i> spp. scrub 15 <i>Ostryopsis davidiana</i> scrub
4. Steppe	4 Temperate grass-forb meadow steppe 5 Temperate needlegrass arid steppe	16 <i>Stipa baicalensis</i> , forb meadow steppe 17 <i>Filifolium sibiricum</i> , grass-forb meadow steppe 18 <i>Aneurolepidium chinense</i> , needlegrass steppe 19 <i>Stipa krylovii</i> steppe 20 <i>Stipa bungiana</i> steppe 21 <i>Thymus mongolicus</i> , needlegrass steppe
5. Grass-forb community	6 Temperate grass-forb community	22 <i>Bothriochloa ischaemum</i> community 23 <i>Bothriochloa ischaemum</i> community 24 <i>Vitex negundo</i> var. <i>heterophylla</i> , <i>Zizyphus jujuba</i> var. <i>spinosa</i> , <i>Bothriochloa ischaemum</i> scrub and grass community 25 <i>Vitex negundo</i> var. <i>heterophylla</i> , <i>Zizyphus jujuba</i> var. <i>spinosa</i> , <i>Themeda triandra</i> var. <i>japonica</i> scrub and grass community
6. Meadow	7 Temperate grass and forb meadow 8 Temperate grass and forb holophytic meadow	26 <i>Arundinella hirta</i> , <i>Spodiopogon sibiricus</i> , forb meadow 27 <i>Carex</i> spp., forb meadow 28 <i>Achnatherum splendens</i> holophytic meadow 29 <i>Suaeda glauca</i> holophytic meadow
7. Swamp	9 Cold-temperate and temperate swamp	30 <i>Phragmites communis</i> swamp

8. Cultural
vegetation

- | | |
|---|--|
| 10 One crop
annually and
cold-resistant
economic crops | 31 Spring wheat, naked oats, buckwheat, potatoes; flux |
| 11 One crop
annually, cold-
resistant
economic crops
and deciduous
orchards | 32 Coarse grains |
| 12 Three crops two
years and two
crops annually
non irrigation,
deciduous
orchards | 33 Winter wheat, coarse grains
34 Coarse grains
35 Rice
36 Winter wheat, corn, cotton
37 Apple, pear orchard
38 Winter wheat, corn, Chinese sorghum, sweet
potatoes; cotton, tobacco, peanut, sesame; apple,
pear, hauthorn, persimmon, walnut, pomegranat,
grape
39 Winter wheat, coarse grains (loamy soil) |
-

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4

Table 2 (on next page)

The vegetation indices

1 **Table 2: The vegetation indices**

Indices	Abbreviation	Formula
Ratio vegetation index	RVI	NIR/Red
Brightness index	BI	$0.2909\text{Blue} + 0.2493\text{Green} + 0.4806\text{Red} + 0.5568\text{NIR} + 0.4438\text{SWIR1} + 0.1706\text{SWIR2}$
Green vegetation index	GI	$-0.2728\text{Blue} - 0.2174\text{Green} - 0.5508\text{Red} + 0.7221\text{NIR} + 0.0733\text{SWIR1} - 0.1648\text{SWIR2}$
Wetness index	WI	$0.1446\text{Blue} + 0.1761\text{Green} + 0.3322\text{Red} + 0.3396\text{NIR} - 0.6210\text{SWIR1} - 0.4186\text{SWIR2}$
Differenced vegetation index	DVI	$\text{NIR} - \text{Red}$
Green ratio	GR	NIR/Green
Mid-infrared ratio	MR	$\text{NIR}/\text{SWIR1}$
Soil-adjusted vegetation index	SAVI	$(1.5(\text{NIR} - \text{Red})) / ((\text{NIR} + \text{Red} + 0.5))$
Optimization of soil-adjusted vegetation index	OSAVI	$(1.16(\text{NIR} - \text{Red})) / ((\text{NIR} + \text{Red} + 0.16))$
Atmospherically resistant vegetation index	ARVI	$(\text{NIR} - (2 * \text{Red} - \text{Blue})) / (\text{NIR} + (2 * \text{Red} - \text{Blue}))$
Normalized difference vegetation index	NDVI	$(\text{NIR} - \text{Red}) / (\text{NIR} + \text{Red})$
Enhanced vegetation index	EVI	$2.5[(\text{NIR} - \text{Red}) / (\text{NIR} + 6 * \text{Red} - 7.5\text{Blue} + 1)]$
Normalized difference tillage index	NDTI	$(\text{SWIR1} - \text{SWIR2}) / (\text{SWIR1} + \text{SWIR2})$
Normalized difference senescent vegetation index	NDSVI	$(\text{SWIR1} - \text{Red}) / (\text{SWIR1} + \text{Red})$

2

3

Table 3(on next page)

Variable combinations

Note: DT10 and RF10 represent the top 10 important variables of decision tree (DT) and random forest (RF) methods with combination 9 in the vegetation group level, respectively. The vegetation indices and their abbreviations were shown in Table 2.

1 **Table 3: Variable combinations.**

- 2 DT10 and RF10 represent the top 10 important variables of decision tree (DT) and random forest
 3 (RF) methods with combination 9 in the vegetation group level, respectively. The vegetation
 4 indices and their abbreviations were shown in Table 2.

Number	Variables combinations
1	Summer land surface albedos of band 1 and 5.
2	Winter land surface albedos of band 1 and 6.
3	Summer land surface albedos of band 1 and 5. Winter land surface albedos of band 1 and 6.
4	Summer vegetation indices BI, WI, MR, NDVI, EVI.
5	Winter vegetation indices MR, NDVI, EVI, NDTI.
6	Summer vegetation indices BI, WI, MR, NDVI, EVI. Winter vegetation indices MR, NDVI, EVI, NDTI.
7	Annual mean temperature, Annual precipitation, Mean diurnal range, Precipitation of driest month.
8	Slope, Aspect, Annual mean temperature, Annual precipitation, Mean diurnal range, Precipitation of driest month.
9	Summer land surface albedos of band 1. Winter land surface albedos of band 6. Summer vegetation indices BI, WI, MR, NDVI, EVI. Winter vegetation indices MR, NDVI, EVI, NDTI. Slope, Aspect, Annual mean temperature, Annual precipitation, Mean diurnal range, Precipitation of driest month.
10	DT10: Annual mean temperature, Annual precipitation, Mean diurnal range, Precipitation of driest month, Slope, Winter vegetation indices MR, Summer land surface albedos of band 1, Summer vegetation indices BI and EVI, Winter land surface albedos of band 6.
11	RF10: Annual precipitation, Annual mean temperature, Mean diurnal range, Slope, Summer vegetation indices BI, MR, NDVI and EVI, Winter vegetation indices MR and NDVI.

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Table 4(on next page)

Model assessment of vegetation groups by field point data and VMC.

Variable combinations were shown in Table 3. VMC, the Vegetation Map of the People's Republic of China. **, the kappa coefficient larger than 0.56; *, the kappa coefficient larger than 0.4 and less than 0.56. OA, Overall accuracy; KC, Kappa coefficient.

1 **Table 4: Model assessment of vegetation groups by field point data and VMC.**

2 Variable combinations were shown in Table 3. VMC, the Vegetation Map of the People's Republic of China. **, the kappa coefficient
 3 larger than 0.56; *, the kappa coefficient larger than 0.4 and less than 0.56. OA, Overall accuracy; KC, Kappa coefficient.

Variable combinations	Decision tree				Random forest				Support vector machine				Maximum likelihood classification			
	Point data		VMC		Point data		VMC		Point data		VMC		Point data		VMC	
	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC
1	34%	0.18	55%	0.22	37%	0.24	32%	0.09	36%	0.21	53%	0.21	23%	0.08	11%	0.02
2	38%	0.20	52%	0.23	39%	0.27	37%	0.13	35%	0.20	55%	0.24	18%	0.07	9%	0.03
3	45%	0.31	54%	0.26	47%	0.36	45%	0.21	41%	0.27	54%	0.27	24%	0.12	15%	0.05
4	32%	0.16	46%	0.16	42%	0.30	42%	0.17	37%	0.22	57%	0.26	11%	0.04	3%	0.01
5	31%	0.11	59%	0.14	44%	0.32	44%	0.19	36%	0.22	51%	0.22	9%	0.04	4%	0.02
6	41%	0.26	44%	0.18	50%	0.40*	52%	0.27	42%	0.29	54%	0.27	13%	0.08	4%	0.03
7	54%	0.45*	57%	0.34	72%	0.66**	55%	0.35								
8	55%	0.46*	56%	0.35	69%	0.63**	56%	0.37								
9	55%	0.46*	53%	0.34	68%	0.61**	57%	0.38								
10	55%	0.46*	53%	0.33	69%	0.63**	57%	0.38								
11	56%	0.46*	56%	0.36	68%	0.62**	57%	0.38								

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Table 5 (on next page)

Model assessment of vegetation types by field point data and VMC.

The Abbreviations were same with Table 4.

1 **Table 5: Model assessment of vegetation types by field point data and VMC.**

2 The Abbreviations were same with Table 4.

Variable combinations	Decision tree				Random forest				Support vector machine				Maximum likelihood classification			
	Point data		VMC		Point data		VMC		Point data		VMC		Point data		VMC	
	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC
1	42%	0.24	63%	0.33	32%	0.22	23%	0.09	32%	0.18	40%	0.18	6%	0.02	7%	0.00
2	44%	0.27	58%	0.31	34%	0.23	30%	0.14	31%	0.18	44%	0.24	5%	0.02	14%	0.00
3	43%	0.30	58%	0.35	44%	0.34	38%	0.22	37%	0.26	43%	0.25	9%	0.05	13%	0.00
4	36%	0.20	47%	0.20	39%	0.29	31%	0.15	32%	0.19	43%	0.21	13%	0.07	6%	0.02
5	32%	0.14	59%	0.23	41%	0.31	36%	0.19	34%	0.22	43%	0.22	6%	0.03	6%	0.03
6	36%	0.23	45%	0.24	47%	0.38	44%	0.27	40%	0.29	43%	0.25	14%	0.09	21%	0.06
7	55%	0.46*	72%	0.54*	70%	0.65**	54%	0.41*								
8	53%	0.44*	68%	0.52*	68%	0.63**	55%	0.43*								
9	54%	0.45*	65%	0.49*	66%	0.60**	55%	0.43*								
10	54%	0.45*	65%	0.49*	68%	0.63**	55%	0.43*								
11	53%	0.44*	68%	0.52*	67%	0.62**	55%	0.43*								

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Table 6 (on next page)

Model assessment of formations and subformations by field point data and VMC.

The Abbreviations were same with Table 4.

1 **Table 6: Model assessment of formations and subformations by field point data and VMC.**

2 The Abbreviations were same with Table 4.

Variable combinations	Decision tree				Random forest				Support vector machine				Maximum likelihood classification			
	Point data		VMC		Point data		VMC		Point data		VMC		Point data		VMC	
	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC	OA	KC
1	23%	0.14	19%	0.08	20%	0.18	5%	0.02	11%	0.09	6%	0.03	8%	0.06	8%	0.04
2	22%	-0.04	49%	0.04	19%	0.17	6%	0.03	13%	0.11	7%	0.04	8%	0.06	13%	0.05
3	26%	0.14	45%	0.23	29%	0.27	9%	0.07	21%	0.19	10%	0.07	12%	0.09	13%	0.07
4	30%	0.20	30%	0.04	22%	0.20	7%	0.04	16%	0.14	6%	0.03	9%	0.07	8%	0.04
5	33%	0.01	67%	0.00	22%	0.20	7%	0.04	15%	0.13	5%	0.03	11%	0.09	10%	0.04
6	26%	0.15	22%	0.02	31%	0.30	11%	0.08	21%	0.19	8%	0.06	12%	0.09	15%	0.08
7	33%	0.20	52%	0.27	58%	0.57**	23%	0.20								
8	27%	0.17	34%	0.18	55%	0.54*	23%	0.20								
9	25%	0.15	22%	0.15	55%	0.53*	22%	0.20								
10	30%	0.17	41%	0.22	56%	0.55*	23%	0.21								
11	31%	0.20	41%	0.22	56%	0.55*	23%	0.20								

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Table 7 (on next page)

Top ten most important variables of models in the different vegetation classification units.

The abbreviations of indices were shown in Table 2.

1 **Table 7: Top ten most important variables of models in the different vegetation classification units.**

2 The abbreviations of indices were shown in Table 2.

	Vegetation groups				Vegetation types				Formations and sub-formations			
	Decision tree		Random forest		Decision tree		Random forest		Decision tree		Random forest	
	Important variables	Standardized Importance	Important variables	Normalized importance	Important variables	Standardized Importance	Important variables	Normalized importance	Important variables	Standardized Importance	Important variables	Normalized importance
1	Annual mean temperature	1.00	Annual mean temperature	3.68	Annual mean temperature	1.00	Annual mean temperature	3.51	Annual mean temperature	1.00	Annual mean temperature	4.16
2	Annual precipitation	0.88	Slope	2.94	Slope	0.83	Slope	3.35	Annual precipitation	0.86	Annual precipitation	3.28
3	Slope	0.80	Mean diurnal range	2.60	Annual precipitation	0.51	Mean diurnal range	3.06	Slope	0.63	Mean diurnal range	3.25
4	Winter vegetation index MR	0.36	Annual precipitation	2.38	Winter vegetation index MR	0.30	Annual precipitation	2.8	Mean diurnal range	0.52	Slope	2.24
5	Mean diurnal range	0.33	Summer vegetation index BI	1.88	Mean diurnal range	0.28	Summer vegetation index BI	1.84	Precipitation of driest month	0.52	Precipitation of driest month	2.16
6	Summer surface albedo of band 1	0.29	Winter vegetation index NDVI	1.37	Summer vegetation index EVI	0.22	Winter vegetation index NDVI	1.61	Winter vegetation index MR	0.4	Summer vegetation index BI	1.83
7	Summer vegetation index BI	0.28	Summer vegetation index EVI	1.36	Precipitation of driest month	0.21	Winter vegetation index MR	1.45	Summer surface albedo of band 1	0.32	Summer vegetation index NDVI	1.7
8	Precipitation of driest month	0.25	Winter vegetation index MR	1.30	Summer vegetation index BI	0.20	Summer vegetation index WI	1.31	Summer vegetation index BI	0.32	Winter vegetation index NDVI	1.61
9	Summer vegetation index EVI	0.23	Summer vegetation index NDVI	1.22	Summer surface albedo of band 1	0.19	Precipitation of driest month	1.24	Summer vegetation index WI	0.31	Winter vegetation index MR	1.47
10	Winter surface albedo of	0.19	Summer vegetation index MR	1.12	Winter surface albedo of	0.14	Summer vegetation index NDVI	1.22	Winter surface albedo of band 6	0.28	Summer vegetation indices EVI	1.32

band 6

band 6

and MR

Figure 1

The location and DEM of the Jing-Jin-Ji region.

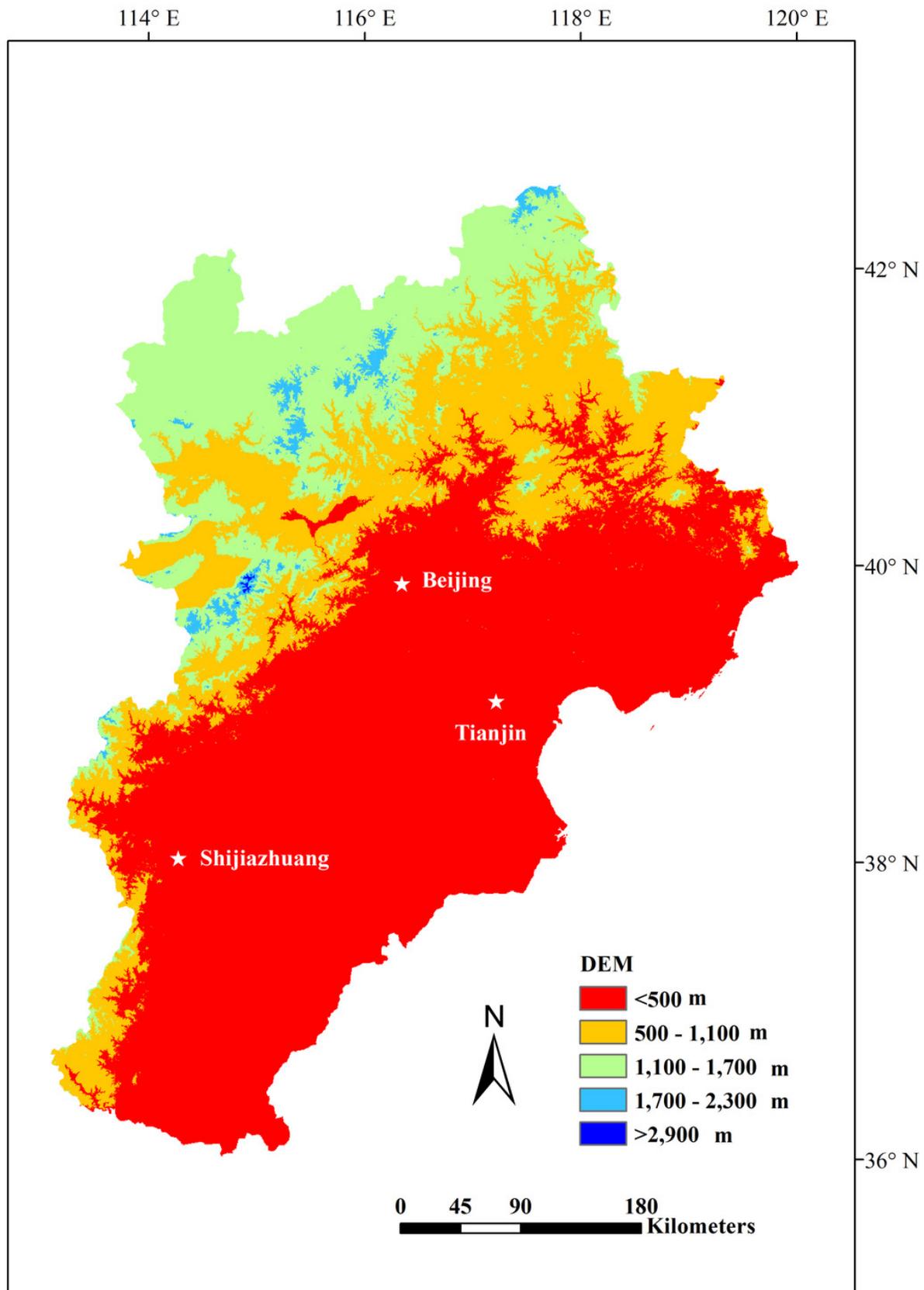


Figure 2

The modeling vegetation map of vegetation groups with highest accuracy by four methods and the VMC in Jing-Jin-Ji region.

Decision tree model (a), random forest model (b), support vector machine (c), maximum likelihood classification (d), the Vegetation Map of the People's Republic of China (VMC) (e); The legend represents vegetation groups shown in Table 1.

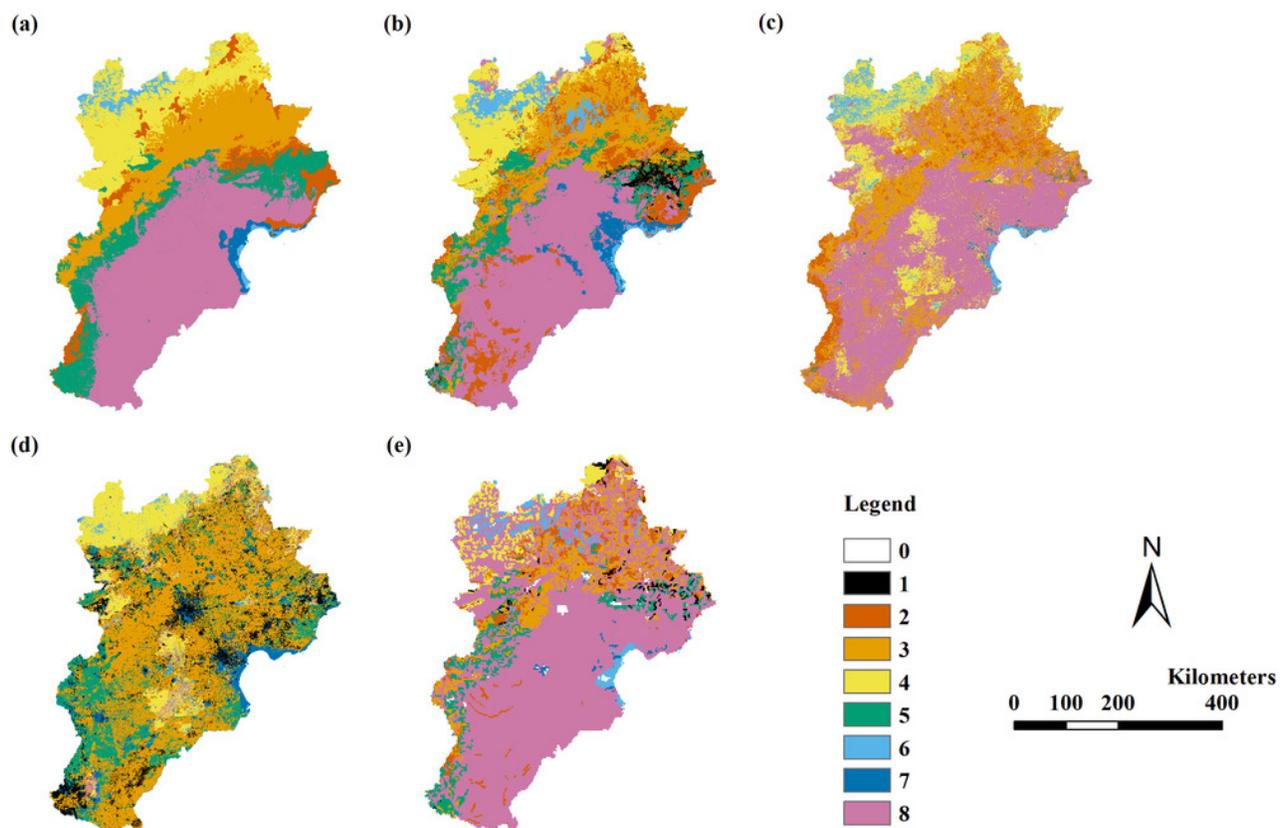


Figure 3

The modeling vegetation map of vegetation types with highest accuracy by four methods and the VMC in Jing-Jin-Ji region.

Decision tree model (a), random forest model (b), support vector machine (c), maximum likelihood classification (d), the Vegetation Map of the People's Republic of China (VMC) (e); The legend represents vegetation groups shown in Table 1.

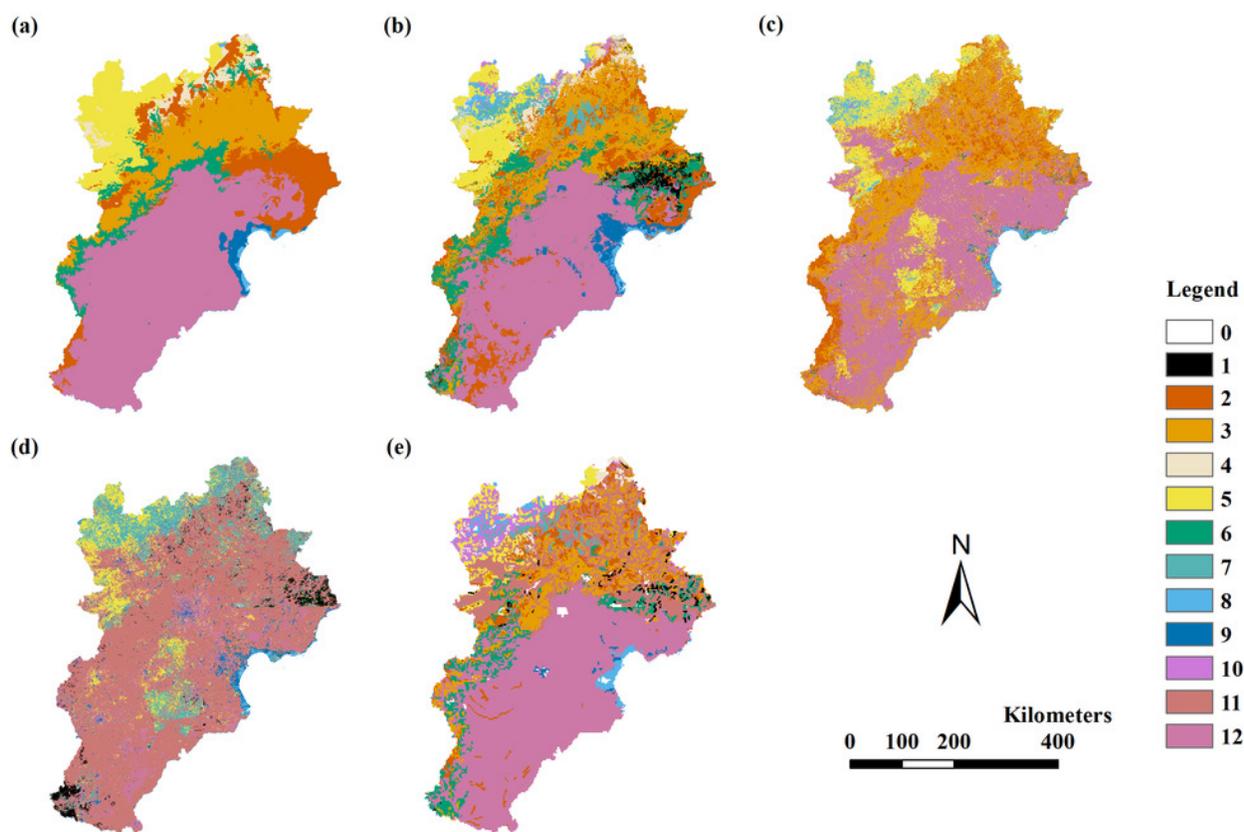


Figure 4

The modeling vegetation map of formations and sub-formations with highest accuracy by four methods and the VMC in Jing-Jin-Ji region.

Decision tree model (a), random forest model (b), support vector machine (c), maximum likelihood classification (d), the Vegetation Map of the People's Republic of China (VMC) (e); The legend represents vegetation groups shown in Table 1.

