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Spatial structure arising from neighbour-dependent bias in collective cell movement

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Abstract

Mathematical models of collective cell movement often neglect the effects of spatial structure, such 7 as clustering, on the population dynamics. Typically, they assume that individuals interact with one 8 another in proportion to their average density (the mean-field assumption) which means that cell-cell q interactions occurring over short spatial ranges are not accounted for. However, in vitro cell culture 10 studies have shown that spatial correlations can play an important role in determining collective 11 behaviour. Here, we take a combined experimental and modelling approach to explore how individual-12 level interactions give rise to spatial structure in a moving cell population. Using imaging data from in 13 vitro experiments, we quantify the extent of spatial structure in a population of 3T3 fibroblast cells. 14 To understand how this spatial structure arises, we develop a lattice-free individual-based model 15 (IBM) and simulate cell movement in two spatial dimensions. Our model allows an individual's 16 direction of movement to be affected by interactions with other cells in its neighbourhood, providing 17 insights into how directional bias generates spatial structure. We consider how this behaviour scales 18 up to the population level by using the IBM to derive a continuum description in terms of the 19 dynamics of spatial moments. In particular, we account for spatial correlations between cells by 20 considering dynamics of the second spatial moment (the average density of pairs of cells). Our 21 numerical results suggest that the moment dynamics description can provide a good approximation to 22 averaged simulation results from the underlying IBM. Using our in vitro data, we estimate parameters 23 for the model and show that it can generate similar spatial structure to that observed in a 3T3 24 fibroblast cell population. 25

26 Keywords

27 Collective movement; Cell migration; Spatial moment dynamics; Individual-based model; Directed move-

²⁸ ment; Spatial correlations

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²⁹ 1 Introduction

Collective cell movement is integral to tissue repair [Martin, 1997, Shaw and Martin, 2009], embryonic 30 development [Kurosaka and Kashina, 2008], the immune response [Rørth, 2009] and cancer [Friedl and 31 Wolf, 2003]. Interactions occurring between individual cells have implications for movement of the cell 32 population as a whole. However, the manner in which these individual-level events affect the collective 33 dynamics is not always well understood [Tambe et al., 2011, Vedel et al., 2013, Agnew et al., 2014]. 34 Cells interact over short length scales in various ways, for example via cell-secreted diffusible chemical 35 signals [Mason et al., 2001, Raz and Mahabaleshwar, 2009]. When detected by neighbouring cells these 36 signals can have a repulsive or attractive effect on an individual's direction of movement [Painter and 37 Hillen, 2002], or affect the rate at which a cell will move [Cai et al., 2006]. Physical forces, such as 38 cell-cell adhesion [Trepat et al., 2009, Tambe et al., 2011], and crowding effects also influence movement 39 [Abercrombie, 1979, Plank and Simpson, 2012]. These interactions may generate spatial structure in a 40 cell population which will in turn affect the collective dynamics [Plank and Law, 2015]. For instance, cell 41 clustering can arise due to attractive forces such as cell-cell adhesion [Green et al., 2010, Agnew et al., 42 2014]. On the other hand, repulsive forces such as chemorepellant signals can cause cells to segregate [Kay 43 et al., 2012, Keeley et al., 2014]. 44 Individual-based models (IBMs) have proven effective for simulating the movement of large numbers 45 of cells and can give insights into how interactions give rise to spatial structure [Grimm et al., 2006]. In 46 a lattice-free framework, cells are represented as individual agents undergoing movement through contin-47 uous space and features including proliferation [Plank and Simpson, 2012], cell-cell adhesion [Johnston 48 et al., 2013] and directional bias [Dyson and Baker, 2015] can be incorporated into the model. Equivalent 49 lattice-based models, where agent locations are restricted to discrete sites on a pre-defined lattice, often 50 require less computational power than their lattice-free counterparts. However, at high cell densities 51

⁵² agents become aligned along the lattice resulting in unrealistic spatial configurations of cells that do ⁵³ not correspond well to those observed experimentally [Plank and Simpson, 2012]. In lattice-free models, ⁵⁴ different approaches can be employed to account for crowding effects and volume-exclusion, the concept ⁵⁵ that the cells themselves take up space in the domain and may obstruct the movement of neighbouring ⁵⁶ cells. For instance, each individual may occupy a spherical region with fixed diameter through which the ⁵⁷ movement of other agents is restricted [Bruna and Chapman, 2012, Dyson and Baker, 2015].

⁵⁸ IBMs for cell movement in two spatial dimensions generate simulation data that can be compared to ⁵⁹ experimental images of moving cells studied *in vitro*. In two-dimensional cell migration assays, such as ⁶⁰ circular barrier assays [Simpson et al., 2013b] and scratch assays [Johnston et al., 2014], cells are seeded ⁶¹ into a well and allowed to attach to the well surface. The movement of cells across the surface can then ⁶² be monitored by imaging the well at regular discrete time intervals. Analysis of this time-lapse imaging ⁶³ data provides information about the properties of individual cells as well as the spatial distribution of ⁶⁴ the population over time [Simpson et al., 2010].

Using an IBM to obtain a reliable description of average cell behaviour can become computationally expensive because this involves carrying out many simulation repeats. In addition, IBMs are not particularly amenable to further mathematical analysis. This has motivated the development of more mathematically tractable approximation schemes which can provide greater insight into how population-level behaviour arises from interactions in the underlying stochastic process [Deroulers et al., 2009]. Models that aim to capture collective movement at the population level, such as the Fisher-Kolmogorov equa-

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⁷¹ tion [Fisher, 1937, Kolmogorov et al., 1937], typically do not account for spatial structure. The majority

⁷² of models invoke a mean-field assumption which assumes that cells interact with one another in propor-

tion to their average density [Anderson and Chaplain, 1998, Deroulers et al., 2009, Tremel et al., 2009].

Thus, they do not always provide an accurate representation of cell behaviour, particularly in highly clustered (or segregated) populations where interactions between neighbouring cells are often stronger

⁷⁵ clustered (or segregated) populations where interactions between neighbouring cells are often stronger
 ⁷⁶ (or weaker) than in populations where there is no spatial structure [Simpson et al., 2013a, Markham

77 et al., 2014].

An alternative approach incorporates spatial correlations by employing the dynamics of spatial mo-78 ments. The dynamics of individual cells, pair of cells, triplets of cells, and so on, can be considered in 79 order to explore how spatial structure changes over time. In ecology, spatial moment models have been 80 developed to study the effects of spatial patterns in animal and plant communities [Bolker and Pacala, 81 1997, Lewis and Pacala, 2000, Dieckmann and Law, 2000]. Models incorporating birth, death [Bolker 82 and Pacala, 1997, Law et al., 2003], growth [Adams et al., 2013] and movement [Murrell and Law, 2000] 83 have been considered, as well as interactions between different types or species, for example predator-84 prey relationships [Murrell, 2005]. More recently, moment dynamics approaches have also been applied 85 to collective cell movement, such as in lattice-free models with chemotactic interactions [Newman and 86 Grima, 2004, Binny et al., 2015] and cell-cell adhesion [Middleton et al., 2014], and a lattice-based model 87 for interacting cell populations [Johnston et al., 2015]. 88

A closure assumption is required in order to solve a dynamical system of spatial moments. The 89 mean-field assumption closes the system at first order so ignores the spatial information held in higher 90 moments. In order to retain information about spatial structure a second-order closure, at least, is needed. 91 A number of different second-order closures are possible [Murrell et al., 2004, Raghib et al., 2011], however 92 the Kirkwood Superposition Approximation is often applied in the context of cell movement [Kirkwood, 93 1935, Kirkwood and Boggs, 1942, Markham et al., 2014]. Other schemes which do not rely on a closure 94 assumption have also been developed, for example perturbation approximations [Bruna and Chapman, 95 2012] and methods that deal with spatial moments at all orders [Ovaskainen et al., 2014]. 96

In this paper we extend the model described in our recent work [Binny et al., 2015] from one to two spatial dimensions, making it more amenable for use in conjunction with experimental data. To explore whether our model can provide insights into the behaviour of moving cells studied *in vitro*, we analyse imaging data generated from experiments with populations of motile 3T3 murine fibroblast cells.

We present a lattice-free IBM for collective cell movement in which an individual's rate and direction 101 of movement are determined by interactions with cells in its neighbourhood. This neighbour-dependent 102 directional bias allows us to explore how attractive or repulsive interactions between cells give rise to 103 spatial structure in the population. The first spatial moment, the average density of individual cells, 104 holds no spatial information. Therefore, in order to account for spatial correlations we consider the 105 second spatial moment, an average density of pairs of cells. We use our IBM to derive a population-level 106 description for the second moment dynamics and solve this for a distribution of cells that is homogeneous 107 in space. Our results suggest that the spatial moment model can provide a good approximation to the 108 underlying stochastic process. 109

Motile cells possess dynamic cytoskeletons which allow them to change their shape and flex around neighbouring cells [Abercrombie, 1979, Le Clainche and Carlier, 2008]. To try and capture this trait we also make use of the neighbourhood-dependent directional bias as a mechanism for incorporating crowding effects, rather than defining cells as hard spheres with a fixed exclusion area. Using our *in vitro*

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data, we estimate parameters for the model and quantify the spatial structure in a moving population 114

of fibroblast cells. 115

$\mathbf{2}$ Experimental methods 116

2.1Cell culture 117

Murine fibroblast 3T3 cells were cultured in Dulbecco's modified Eagle medium (Invitrogen, Australia) 118 with 5% foetal calf serum (FCS) (Hyclone, New Zealand), 2 mM L-glutamine (Invitrogen), 50U/ml 119 penicillin and 50μ g/ml streptomycin (Invitrogen), in 5% CO₂ and 95% air at 37 °C. Monolayers of 3T3 120 cells were cultured in T175 cm² tissue culture flasks (Nunc, Thermo Scientific, Denmark). Prior to 121 confluence, cells were lifted with 0.05% trypsin (Invitrogen). Viable cells were counted using the trypan 122 blue exclusion test and a haemocytometer. 123

Two cell suspensions were created at approximate average cell densities of 20,000 cells/ml and 30,000 124 cells/ml. The experiments were performed in triplicate for each initial cell density. Cells were seeded in 125 a 24 well tissue culture plate (each well of diameter 15.6 mm) and incubated overnight in 5% CO_2 and 126 95% air at 37 °C to allow them to attach to the base of the plate. Initially, cells were approximately 127 uniformly distributed in each well. 128

2.2Imaging techniques and analysis 129

Time-lapse images of the cells were captured, over a period of 12 hours at 3 hour intervals, using a light 130 microscope and Eclipse TIS software at 100x magnification. For each sample, a 4500 μ m x 450 μ m image 131 was reconstructed from overlapping adjacent images captured at approximately the centre of the well. 132 The locations of the n cells in each image were manually determined by superimposing markers onto 133 cells and recording the Cartesian coordinates of markers using ImageJ image analysis software. These 134 coordinates were used to calculate a pair-correlation function (PCF) for each image following the method 135 in Section 3.2. 136

Mathematical modelling of cell movement 3 137

3.1Individual-based model 138

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We extend our previous model [Binny et al., 2015] to consider the collective movement of n individuals in 139 two-dimensional continuous space, with periodic conditions at the boundaries. The following framework 140 is analogous to the one-dimensional model described in [Binny et al., 2015] and we refer the reader there 141 for a more comprehensive description of the concepts outlined below. 142

The location of a cell i is represented by a coordinate $\mathbf{x}_i \in \mathbb{R}^2$ and the state of the system at time t 143 comprises the locations of all n individuals. Cell i moves as a Poisson process over time with movement 144 rate per unit time $\psi_i(\mathbf{x})$, i.e. the probability of an event occurring in a short time δt is $\psi_i(\mathbf{x})\delta t + O(\delta t^2)$. 145

The movement rate $\psi_i(\mathbf{x})$ is dependent on the state of the system at time t so the Poisson process is 146 inhomogeneous over time. When cell i undergoes a movement event, it moves a displacement \mathbf{r} to a new

location $\mathbf{x}_i + \mathbf{r}$ drawn from a probability density function (PDF) $\mu(\mathbf{x}_i, \mathbf{x}_i + \mathbf{r})$. 148

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¹⁴⁹ We use the Gillespie algorithm to simulate this stochastic process [Gillespie, 1977]. The IBM can ¹⁵⁰ be tailored to suit different cell types and experimental conditions by choosing different functions for ψ_i ¹⁵¹ and $\mu(\mathbf{x}_i, \mathbf{x}_i + \mathbf{r})$. In the following description we choose functions suitable for simulating movement of ¹⁵² fibroblast cells.

The movement rate ψ_i comprises an intrinsic movement rate m and a density-dependent component that sums contributions from n neighbouring cells at \mathbf{x}_j to individual *i*'s motility:

$$\psi_i = \max\left(0, \ m + \sum_{\substack{j=1\\i\neq j}}^n w(\mathbf{x}_j - \mathbf{x}_i)\right),\tag{1}$$

which ensures that $\psi_i \ge 0$. The kernel $w(\mathbf{z})$ weights the strength of interaction between a pair of cells displaced by \mathbf{z} and for simplicity we choose it to be a Gaussian function

$$w(\mathbf{z}) = \alpha \exp\left(-\frac{|\mathbf{z}|^2}{2\sigma_w^2}\right).$$
(2)

¹⁵⁷ The parameter α determines the interaction strength while σ_w^2 determines the range over which interac-¹⁵⁸ tions occur.

¹⁵⁹ We now describe a mechanism which allows a cell's direction of movement to be determined by the ¹⁶⁰ degree of crowding in its neighbourhood. This mechanism is comparable to that of [Binny et al., 2015] ¹⁶¹ but with some differences that are required for extension to two spatial dimensions. The neighbour-¹⁶² dependent bias $\mathbf{b}(\mathbf{x})$ accounts for the effect of *n* neighbouring cells located at \mathbf{x}_j on the direction of ¹⁶³ movement of an individual at \mathbf{x}

$$\mathbf{b}(\mathbf{x}) = \sum_{j=1}^{n} \nabla v(\mathbf{x}_j - \mathbf{x}).$$
(3)

The kernel $v(\mathbf{z})$ weights the strength of interaction between a cell pair displaced by \mathbf{z} . For simplicity, we choose $v(\mathbf{z})$ to be a Gaussian function

$$v(\mathbf{z}) = \beta \exp\left(-\frac{|\mathbf{z}|^2}{2\sigma_v^2}\right),\tag{4}$$

which means the interaction will be strong for a pair of cells located close together and negligible if they are far apart. Interaction strength and range are determined by β and σ_v^2 , respectively. The neighbourdependent bias $\mathbf{b}(\mathbf{x})$ is a vector holding information about both the extent and direction of crowded regions in the neighbourhood of a cell at x. We use the angle $\arg(\mathbf{b}(\mathbf{x}))$ to describe the direction of $\mathbf{b}(\mathbf{x})$. When $\beta > 0$, $\arg(\mathbf{b}(\mathbf{x}))$ is the direction in which the lowest degree of cell crowding arises locally. Conversely for $\beta < 0$, $\arg(\mathbf{b}(\mathbf{x}))$ is the direction of greatest local crowding. The magnitude $|\mathbf{b}(\mathbf{x})|$ provides a measure of the extent of crowding.

When a cell moves, its direction of movement $\theta \in [0, 2\pi]$ is drawn from a PDF $g(\theta; \mathbf{b})$ which depends on the neighbour-dependent bias $\mathbf{b}(\mathbf{x})$. The function $g(\theta; \mathbf{b})$ is a von Mises distribution with mean $\arg(\mathbf{b})$ and concentration $|\mathbf{b}|$:

$$g(\theta; \mathbf{b}) = \frac{\exp\left(|\mathbf{b}|\cos\left(\theta - \arg(\mathbf{b})\right)\right)}{2\pi I_0(|\mathbf{b}|)},\tag{5}$$

where I_0 is the modified Bessel function of order 0. Thus, a cell is most likely to move in the direction arg(**b**) and the strength of this directional bias increases with $|\mathbf{b}|$, as shown in Fig. 1.

The distance moved by a cell is drawn from a non-negative normal distribution with mean step length $1/\lambda_{\mu}$ and variance σ_{μ}^2 . Therefore, the probability of an individual at **x** moving to a new location at **y** is

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180 distributed according to

$$\mu(\mathbf{x}, \mathbf{y}) = N \exp\left(-\frac{\left(|\mathbf{y} - \mathbf{x}| - \frac{1}{\lambda_{\mu}}\right)^2}{2\sigma_{\mu}^2}\right) g\left(\arg(\mathbf{y} - \mathbf{x}); \mathbf{b}(\mathbf{x})\right).$$
(6)

This means that a cell at x is biased to move away from close-lying neighbours when $\beta > 0$. From 181 a biological perspective this repulsive force could correspond to, for example, movement in response 182 to a cell-released chemorepellant [Cai et al., 2006] or physical forces due to deformation of the cell 183 membrane under direct contact with other cells [Trepat et al., 2009]. When $\beta < 0$ the bias is towards 184 crowded regions, such as might arise in the presence of a cell-released chemoattractant [Painter and Hillen, 185 2002]. The bias strength increases with increasing neighbourhood cell density. Setting $\beta = 0$ results in 186 $g(\arg(\mathbf{y}-\mathbf{x});\mathbf{b}(\mathbf{x})) = 1/(2\pi)$ and the cell is equally likely to move in any direction, i.e. movement is 187 unbiased. The PDF $\mu(\mathbf{x}, \mathbf{y})$ has dimension L^{-2} and normalising by the constant N satisfies the constraint 188 $\int \mu(\mathbf{x}, \mathbf{y}) d\mathbf{y} = 1$ for any fixed \mathbf{x} . 189

¹⁹⁰ 3.2 Pair-correlation function

The second spatial moment, the average density of pairs of cells, can be expressed as a pair-correlation 191 function (PCF) C(r), written in terms of a separation distance r [Illian et al., 2008]. The PCF is 192 normalised by dividing by the first moment squared such that C(r) = 1 in the complete absence of 193 spatial structure, i.e. the distribution of cells is completely random (a Poisson spatial pattern). For 194 C(r) > 1, pairs of cells are more likely to be found in close proximity than if they were distributed 195 according to a Poisson pattern. We describe such a configuration of cells as a cluster spatial pattern. In 196 contrast, for C(r) < 1, cell pairs separated by short displacements are less likely to arise, generating a 197 regular spatial pattern. 198

We compute a PCF C(r) from a particular arrangement of agents in a domain of width L_x and height L_y . A reference agent at \mathbf{x}_i is selected and the distance $r = |\mathbf{x}_j - \mathbf{x}_i|$ to a neighbour at \mathbf{x}_j is calculated for n-1 neighbours. A periodic PCF can be calculated by allowing a distance r to be measured across periodic boundaries. A different reference agent is then chosen and the process repeated until each agent has been selected as a reference once. A PCF is constructed by counting the distances that fall into an interval $[r - \frac{\delta r}{2}, r + \frac{\delta r}{2}]$, i.e. binning distances using a bin width δr . To ensure C(r) = 1 in the complete absence of spatial structure we normalise by $n(n-1)(2\pi r\delta r)/(L_x L_y)$.

The choice of δr is important because very small values can yield a PCF dominated by fluctuations while values that are too large result in an overly-smooth function which may mask spatial structure [Binder and Simpson, 2015].

²⁰⁹ 3.3 Spatial moment model

The IBM can be used to derive a population-level model in terms of the dynamics of spatial moments [Plank and Law, 2015]. Mathematical descriptions of spatial moments and derivations of the rate of change equations for the first moment $Z_1(\mathbf{x}, t)$ and second moment $Z_2(\mathbf{x}, \mathbf{y}, t)$ are given in [Binny et al., 2015] and still hold for movement in two dimensions. Spatial moments are functions of time as well as space but, for brevity, from here on we omit the time argument from the notation. Briefly, for the

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 $_{215}$ dynamics of the first spatial moment the corresponding description for ψ_i is

$$M_1(\mathbf{x}) = m + \int w(\mathbf{y} - \mathbf{x}) \frac{Z_2(\mathbf{x}, \mathbf{y})}{Z_1(\mathbf{x})} d\mathbf{y},$$
(7)

 $_{216}$ the expected movement rate of a cell at x. In (1) a maximum formula ensured a non-negative movement

rate but is not incorporated here because we only consider solutions in which negative expected movement rates do not arise. When a cell at \mathbf{x} moves, its new location \mathbf{y} is drawn from a PDF

$$\mu_1(\mathbf{x}, \mathbf{y}) = N \exp\left(-\frac{\left(|\mathbf{y} - \mathbf{x}| - \frac{1}{\lambda_{\mu}}\right)^2}{2\sigma_{\mu}^2}\right) g\left(\arg(\mathbf{y} - \mathbf{x}); \mathbf{b}_1(\mathbf{x})\right).$$
(8)

 $_{219}$ The neighbour-dependent bias for a cell at ${\bf x}$ is

$$\mathbf{b}_1(\mathbf{x}) = \int \nabla v(\mathbf{y} - \mathbf{x}) \frac{Z_2(\mathbf{x}, \mathbf{y})}{Z_1(\mathbf{x})} \mathrm{d}\mathbf{y}.$$
(9)

²²⁰ The equation for the dynamics of the first spatial moment is

$$\frac{\mathrm{d}Z_1(\mathbf{x})}{\mathrm{d}t} = -M_1(\mathbf{x})Z_1(\mathbf{x}) + \int \mu_1(\mathbf{u}, \mathbf{x})M_1(\mathbf{u})Z_1(\mathbf{u})\mathrm{d}\mathbf{u}, \qquad (10)$$

where the first and second terms on the right-hand side correspond to movement out of \mathbf{x} and into \mathbf{x} , respectively. The first moment is constant with respect to time because there are no birth/death events and there is no net flux across the boundaries.

For the dynamics of the second moment the expected movement rate of a cell at \mathbf{x} in a pair with a cell at \mathbf{y} is given by

$$M_2(\mathbf{x}, \mathbf{y}) = m + \int w(\mathbf{z} - \mathbf{x}) \frac{Z_3(\mathbf{x}, \mathbf{y}, \mathbf{z})}{Z_2(\mathbf{x}, \mathbf{y})} d\mathbf{z} + w(\mathbf{y} - \mathbf{x}),$$
(11)

where $Z_3(\mathbf{x}, \mathbf{y}, \mathbf{z})$ denotes the third spatial moment, the average density of triplets of cells. When a cell at \mathbf{x} moves, its new location \mathbf{y} is drawn from a PDF $\mu_2(\mathbf{x}, \mathbf{y}, \mathbf{z})$, where the third argument accounts for the fact that \mathbf{x} is in a pair with a cell at \mathbf{z} :

$$\mu_2(\mathbf{x}, \mathbf{y}, \mathbf{z}) = N \exp\left(-\frac{\left(|\mathbf{y} - \mathbf{x}| - \frac{1}{\lambda_{\mu}}\right)^2}{2\sigma_{\mu}^2}\right) g\left(\arg(\mathbf{y} - \mathbf{x}); \mathbf{b_2}(\mathbf{x}, \mathbf{z})\right).$$
(12)

The neighbour-dependent bias for a cell at \mathbf{x} in a pair with a cell at \mathbf{y} is given by

$$\mathbf{b}_{2}(\mathbf{x}, \mathbf{y}) = \int \nabla v(\mathbf{z} - \mathbf{x}) \frac{Z_{3}(\mathbf{x}, \mathbf{y}, \mathbf{z})}{Z_{2}(\mathbf{x}, \mathbf{y})} d\mathbf{z} + \nabla v(\mathbf{y} - \mathbf{x}).$$
(13)

²³⁰ Finally, the equation for the dynamics of the second moment is

$$\frac{\mathrm{d}Z_2(\mathbf{x}, \mathbf{y})}{\mathrm{d}t} = -(M_2(\mathbf{x}, \mathbf{y}) + M_2(\mathbf{y}, \mathbf{x}))Z_2(\mathbf{x}, \mathbf{y}) + \int \mu_2(\mathbf{u}, \mathbf{x}, \mathbf{y})M_2(\mathbf{u}, \mathbf{y})Z_2(\mathbf{u}, \mathbf{y})\mathrm{d}\mathbf{u} + \int \mu_2(\mathbf{u}, \mathbf{y}, \mathbf{x})M_2(\mathbf{u}, \mathbf{x})Z_2(\mathbf{u}, \mathbf{x})\mathrm{d}\mathbf{u}.$$
(14)

²³¹ Movement out of \mathbf{x} , conditional on the presence of a cell at \mathbf{y} , is accounted for in the first negative term ²³² in (14). The first integral term describes movement into \mathbf{x} from a starting location \mathbf{u} , conditional on the

²³³ presence of a cell at **y**. The remainder are symmetric terms for movement out of and into **y**.

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A closure for the third spatial moment is required to solve equation (14) and we use the Kirkwood superposition approximation [Kirkwood, 1935, Kirkwood and Boggs, 1942] given by

$$\tilde{Z}_3(\mathbf{x}, \mathbf{y}, \mathbf{z}) = \frac{Z_2(\mathbf{x}, \mathbf{y}) Z_2(\mathbf{x}, \mathbf{z}) Z_2(\mathbf{y}, \mathbf{z})}{Z_1(\mathbf{x}) Z_1(\mathbf{y}) Z_1(\mathbf{z})},\tag{15}$$

however other choices of closure are possible [Murrell et al., 2004]. This closes the dynamical system
at second order, therefore we retain information on spatial structure that would be ignored by instead
employing a first-order closure, such as the mean-field assumption.

239 4 Results

²⁴⁰ 4.1 Comparing IBM simulation data and moment dynamics approximations

To explore whether our model is capable of generating spatial structure in a simulated cell population we 241 average results from repeated simulations of the IBM and compute a periodic PCF $C_{IBM}(r)$ as outlined 242 in Section 3.2. We compare this to numerical solutions of our spatial moment model to examine whether 243 it provides a good approximation to the underlying stochastic process. The equation for the dynamics 244 of the second moment (14) is solved for a spatially homogeneous distribution of cells, which means that 245 we assume the probability of finding an individual in a given small region is independent of its location 246 in space. This allows the equation to be rewritten in terms of displacements between pairs of cells, as 247 outlined in the appendix. The PCF $C_{SM}(\boldsymbol{\xi})$ is given by $Z_2(\boldsymbol{\xi})/Z_1^2$ such that $C_{SM}(\boldsymbol{\xi}) = 1$ in the complete 248 absence of spatial structure. The second spatial moment is radially symmetric about the origin of $\boldsymbol{\xi}$. 249 Therefore, in the results below we show only a radial section of $C_{SM}(\boldsymbol{\xi})$ which we denote $C_{SM}(r)$, where 250 $r = |\boldsymbol{\xi}|$. Cells are initially distributed across a domain of width L_x and height L_y , according to a spatial 251 Poisson process with intensity $n/(L_xL_y)$. In the spatial moment model this corresponds to $Z_2(\boldsymbol{\xi}) = Z_1^2$ 252 at t = 0. The system is allowed to reach steady state before results from each model are compared. 253 Parameters used in this section are summarised in Table 1. 254

In the complete absence of interactions, an individual's direction of movement is unbiased and its movement rate is solely determined by the intrinsic component. It is straightforward to show analytically that the steady-state solution for $Z_2(\boldsymbol{\xi})$ is a constant under these conditions. Numerical solutions and averaged IBM simulations confirm this.

The effect of the neighbour-dependent directional bias, in the absence of neighbour-dependent motility 259 (i.e. $\alpha = 0$), is shown in Fig. 2. The PCF quantifies differences in the spatial structure, depending on the 260 strength and nature of cell-cell interactions, which may not be readily apparent from a qualitative visual 261 inspection of the cell locations (Fig. 2 insets). Regular spatial patterns are generated by the directional 262 bias when $\beta > 0$ while $\beta < 0$ gives rise to clustering. The spatial moment model performs very well as an 263 approximation to the IBM except when there is strong clustering (Fig. 2D). This can likely be attributed 264 to limitations of the moment-closure assumption. The Kirkwood Superposition Approximation provides 265 a reasonable approximation to the third moment for Poisson spatial patterns and regular patterns, but 266 performs quite poorly for cluster spatial patterns where it can cause the model to underestimate the 267 second moment [Raghib et al., 2011, Murrell et al., 2004, Dieckmann and Law, 2000]. 268

Figure 3 shows the spatial structure generated by the mechanism for neighbour-dependent motility when there is no local directional bias (i.e. $\beta = 0$). Neighbourhood interactions give rise to regular spatial patterns when $\alpha > 0$ and cluster spatial patterns when $\alpha < 0$. Again, we see good agreement

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between $C_{SM}(r)$ and $C_{IBM}(r)$ except for large magnitudes of $\alpha < 0$ where the pattern is clustered and 272 the moment model under-predicts spatial structure (Fig. 3D). While the limitations associated with the 273 moment closure may play a role, there is another factor that could also be contributing to the poor fit 274 here. We have chosen values of α such that the probability of $\psi_i > 0$ is high. However $\psi_i = 0$ can 275 arise by chance in an IBM simulation and while such occurrences are relatively rare they can have a 276 self-propagating effect, leading to strong clustering. The spatial moment model does not account for 277 these chance events so this might explain why spatial structure is underestimated more dramatically 278 even for relatively weak clustering. 279

Our numerical results show that the same spatial structures can be generated by either neighbourdependent mechanism acting in isolation. When both mechanisms affect movement together, the choice of α and β determines whether they work cooperatively, to promote spatial structure to an even greater extent, or in opposition.

²⁸⁴ 4.2 Model validation using experimental data

We will now use *in vitro* experimental data to validate our model. We begin by exploring whether the directional bias mechanism is capable of generating spatial structure that is qualitatively similar to that observed in 3T3 fibroblast cell populations studied *in vitro* and aim to estimate parameters which yield a reasonable qualitative match to our data.

Movement rates for 3T3 fibroblast cells are discussed in the literature [Ware et al., 1998, Vedel et al., 289 2013]. We choose a biologically relevant rate of 50 μ m/hour for the speed at which an isolated cell moves 290 (i.e. in the absence of neighbourhood interactions). Cell speed is not itself a parameter of our model, but 291 can be decomposed into two constituent parts for input into the model: a mean step length $1/\lambda_{\mu} = 10 \ \mu m$ 292 and an intrinsic movement rate m = 5 hour⁻¹. For the movement PDF $\mu(\mathbf{x}, \mathbf{y})$ we set $\sigma_{\mu} = 2.5 \ \mu \text{m}$ which 293 is biologically reasonable as it ensures cells are more likely to take short steps than undergo large jumps 294 across the space. We employ the directional bias mechanism to incorporate volume exclusion effects by 295 interpreting $2\sigma_v$ as the approximate range over which a cell interacts with neighbours and treating this 296 as a proxy for the average diameter of a cell. From the literature, the average cell diameter for 3T3 297 fibroblast cells is approximately 20 μ m which yields $\sigma_v = 10 \ \mu$ m [Simpson et al., 2013a, Vedel et al., 298 2013]. Here, we consider the directional bias mechanism in the absence of neighbour-dependent motility 299 (i.e. we set $\alpha = 0$). With these parameter choices in place, interaction strength β is the only parameter 300 that we need to estimate. 301

Images are taken at the centre of the well to avoid edge effects and when analysing our in vitro 302 data, we assume that cells are distributed homogeneously across this region. An average cell density 303 is estimated from each image, by dividing the number of cells in an image (which ranged between 80 304 and 318 cells) by the image area. In Section 4.1 we implemented periodic boundary conditions in our 305 IBM simulations such that cells located near a boundary of the domain could interact with those at an 306 opposite boundary. Therefore it was reasonable to calculate a periodic PCF from the configurations of 307 cells that arose. However, for our experimental data, the motility of a cell located near the edge of an 308 image will not be affected by a cell at an opposite edge. Therefore, to calculate an accurate average pair 309 density for the short displacements we are primarily interested in, we choose to generate a non-periodic 310 PCF $C_{exp}(r)$ from the experimental images. 311

To obtain an estimate for β we consider a single experimental image of dimensions 4500 μ m x 450

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 μm with 286 cells, as shown in Fig. 4A with markers superimposed over cell locations. We use our 313 IBM to simulate movement in this 4500 μ m x 450 μ m region using the parameters discussed above (and 314 summarised in Table 1) and explore different values of β . In each simulation, 286 cells are initially 315 distributed according to a spatial Poisson process and we compute a PCF once the system has converged 316 to steady state. Figure 4B shows a snapshot from an IBM simulation at t = 15 hours. The presence 317 of spatial structure is not obvious from visual inspection of Figs. 4A-B alone but calculating a PCF 318 (Fig. 4C) indicates a regular spatial pattern over displacements $< 50 \ \mu m$. We find that for $\beta = 1000$ 319 μm the PCFs predicted by our IBM and spatial moment model provide a very good visual match to 320 that computed from the *in vitro* data for this sample. Unlike $C_{IBM}(r)$ and $C_{SM}(r)$, the PCF computed 321 from each experimental image does not tend to 1 for large displacements because it is computed from 322 non-periodic distances and owing to the image dimensions. However, we see good agreement at short to 323 moderate displacements. To validate our estimate, we compare PCFs obtained using the same parameter 324 choices and $\beta = 1000 \ \mu m$ for the average cell densities in each of the other images (Figures given in the 325 Supplementary Material). For all samples we see a reasonable qualitative agreement between the PCFs 326 predicted by the model and the PCF generated from the *in vitro* data. 327

The PCFs $C_{exp}(r)$ and $C_{IBM}(r)$ employ a bin width δr which provides a reasonably smooth function for the majority of experimental samples yet contains sufficient information about spatial structure to allow us to carry out our analysis. Smaller values of δr give a better match to $C_{SM}(r)$, however $C_{exp}(r)$ becomes dominated by fluctuations.

From our numerical results we know that both the mechanisms for neighbour-dependent motility and 332 directional bias are capable of generating spatial structure. In the absence of directional bias, large values 333 of α are required to generate the extent of spatial structure observed in the *in vitro* data. When carrying 334 out IBM simulations under these conditions, individuals experience strong neighbourhood interactions 335 and, as a result, movement rates ψ_i are often considerably higher than the average movement rates of 336 fibroblast cells discussed in the literature [Ware et al., 1998, Vedel et al., 2013]. For example, using the 337 same parameter choices as for Fig. 4 but in the absence of directional bias ($\beta = 0$), an interaction 338 strength of $\alpha = 1000$ hour⁻¹ generates spatial structure which is a reasonable qualitative match to the 339 in vitro data. However, 23% of individuals undergo movement with a rate $\psi_i > 100$ hour⁻¹, which 340 corresponds to a biologically unreasonable cell speed of 1000 μ m/hour. Therefore, we do not consider 341 neighbour-dependent motility in isolation here. When both mechanisms are acting together, numerous 342 combinations of α and β exist that would give rise to similar spatial structure. 343

Numerical and analytical results suggest that there is a relationship between the average cell density 344 and the extent of spatial structure in the moving cell population. Increasing the average cell density 345 causes a decrease in the extent of spatial structure, i.e. for a regular spatial pattern average pair densities 346 at short displacements increase towards 1. However, for the average cell densities studied here, it is not 347 immediately obvious whether our *in vitro* experimental data supports the suggestion that a significant 348 relationship exists. We now explore this idea in more depth by using the area between the PCF to 349 calculate a summary statistic which quantifies the extent of spatial structure, as shown in Fig. 5. We 350 consider two metrics and compute each for PCFs generated from the IBM, spatial moment model and 351 in vitro data. The first metric measures spatial structure as $\int_0^R (1 - C(r)) dr$ (Fig. 5A). Positive values 352 indicate a regular spatial pattern while negative values indicate a cluster spatial pattern. The second 353 is given by $\int_0^R |1 - C(r)| dr$ (Fig. 5B). Both metrics are calculated for $R = 80 \ \mu m$ and have units μm . 354 The average cell densities obtained from the *in vitro* data lie within a relatively small range and so the 355

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³⁵⁶ overall change in the metric is small. Nevertheless, for both metrics our model predicts that increasing

³⁵⁷ average cell density decreases the extent of spatial structure. To investigate whether our *in vitro* data

³⁵⁸ supports this we carry out a simple linear regression, yielding p-values of 0.0211 and 0.0435 for the first
³⁵⁹ (Fig. 5A) and second metric (Fig. 5B), respectively. Thus, using either metric and despite the noise in

- ³⁵⁹ (Fig. 5A) and second metric (Fig. 5B), respectively. Thus, using either metric and despite the noise in ³⁶⁰ our *in vitro* data, the results suggest that a significant relationship does indeed exist between average
- ³⁶¹ cell density and spatial structure.

362 5 Discussion

IBMs of collective movement allow us to explore how interactions between individuals give rise to spatial 363 structure and how, in turn, this self-generated spatial structure affects the population dynamics. How-364 ever, IBMs are limited when it comes to explaining population-level behaviour as they can be difficult to 365 analyse mathematically. To move beyond these limitations, population-level models can be derived from 366 IBMs but often employ a mean-field assumption which neglects spatial correlations between cells. We 367 have derived a population-level description in terms of spatial moment dynamics to account for spatial 368 correlations and give insight into how neighbour-dependent directional bias generates spatial structure 369 in a moving cell population. Extending our original model [Binny et al., 2015] from one to two spatial 370 dimensions makes it more amenable for use alongside experimental data. Our results verify that the 371 spatial moment model can provide a good approximation to averaged simulations of the underlying IBM 372 when cells are distributed homogeneously through space. 373

Volume exclusion effects can be incorporated into lattice-free models of interacting agents, for example using a hard sphere approach where neighbours are explicitly excluded from a region surrounding an individual. Instead, we employ the mechanism for neighbour-dependent directional bias as a means of accounting for crowding effects. Using an interaction kernel concentrated around short pair displacements allows us to reduce the likelihood of two cells being found in very close proximity, although it does not altogether rule out the possibility.

In vitro studies have shown that cell motility can be heavily influenced by the average density of 380 cells, particularly at high densities where crowding effects come into play, affecting the movement rate 381 or direction of individuals [Lee et al., 1994, Tremel et al., 2009, Vedel et al., 2013]. In addition, spatial 382 correlations between cells can have major implications for motility, for example cell populations with 383 clustering exhibit different behaviour to those that adopt regular spatial patterns [Green et al., 2010, Kee-384 ley et al., 2014]. We carried out in vitro experiments with motile 3T3 fibroblast cells for model validation 385 and to explore the extent to which spatial structure is generated in fibroblast cell populations. It is not 386 obvious from visual inspection of the imaging data alone whether spatial structure is present, however 387 calculating a PCF indicates a regular spatial pattern. The spatial structure arises over displacements 388 $< 50 \ \mu \text{m}$ and is likely predominantly a consequence of space being excluded by the cells, however chemo-389 tactic interactions, such as chemokine signalling, may also contribute to a lesser extent [Vedel et al., 390 2013]. We consider whether our model's mechanism for neighbour-dependent directional bias can gener-391 ate a similar spatial structure. The majority of model parameters are obtained by selecting biologically 392 relevant values from the literature and we use our *in vitro* data to provide an estimate for the interaction 393 strength β . This parameter was estimated from a single experimental image and for validation we use the 394 same estimate for the average cell densities in each of the other images. A visual comparison of the PCFs 395

³⁹⁶ suggests that our parameterised model can successfully predict the spatial structure of 3T3 fibroblasts

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³⁹⁷ at various average cell densities. We do not consider the neighbour-dependent motility mechanism in ³⁹⁸ the absence of directional bias because the spatial structure observed *in vitro* could only be generated ³⁹⁹ if a large proportion of cells moved at biologically unreasonable rates. However, it is possible that both ⁴⁰⁰ mechanisms acting together could give rise to the observed spatial structure and further information ⁴⁰¹ would be required to distinguish the relative contributions of each effect occurring *in vitro*.

We choose to calculate a non-periodic PCF from each experimental image to obtain an accurate 402 average pair density at short displacements. Because we do not apply edge corrections and owing to 403 the image dimensions, the PCF often has values less than 1 for large displacements. However, we would 404 expect that a PCF calculated either for a very large number of cells (at the same average density) or 405 by averaging results from many identically-prepared repeated experiments, would give $C(r) \approx 1$ for 406 large displacements. A number of methods to account for edge effects are discussed in the literature, 407 for example the use of buffer zones, toroidal edge corrections or employing weighting factors [Haase, 408 1995, Law et al., 2009]. However, in some cases, applying an edge correction may yield results that do 409 not provide an accurate representation of the spatial structure in the population. For instance, when 410 analysing spatial patterns that are clustered or regular, the use of a toroidal correction can lead to an 411 unknown extent of bias in the resulting distribution of distances [Haase, 1995]. To avoid this uncertainty, 412 we have chosen to work with the actual pair distances between cells in the experimental images and not 413 correct for edge effects. 414

We have further validated our model by considering in more detail the relationship between average 415 cell density and the extent of spatial structure in a cell population. Numerical and analytical results from 416 our model suggest that increasing the average cell density decreases the extent of spatial structure. There 417 is considerable noise in the *in vitro* data because we choose to analyse PCFs generated from individual 418 images as opposed to working with averaged results. In addition, the data considers a relatively small 419 range of average cell densities. Nevertheless, our experimental data also supports the idea that such a relationship exists. The most likely explanation for this effect is that as average cell density increases, 421 there is less free space available and cells are forced into closer proximity. Because of their deformable 422 plasma membranes, pairs of cells can arise at displacements less than the average diameter of a cell. This 423 increases the average pair density at short displacements, thus reducing the extent of spatial structure. 424 Because we do not employ a hard sphere volume-exclusion method, instead representing cells by points 425 in space, our model will predict a Poisson spatial pattern for very high average cell densities (far greater 426 than those in our data). In reality, the fact that 3T3 fibroblasts have a minimum area they can occupy 427 means that this would never be observed in vitro. 428

The spatial moment model is only an approximation to the IBM because it invokes a closure as-429 sumption which closes the dynamical system at second order and ignores higher order moments. The 430 performance of our model depends on the suitability of this closure as an approximation to the third 431 moment. Different closures are proposed in the literature and we use the Kirkwood Superposition Ap-432 proximation, which is a relatively simple closure that is often applied in cell movement models. This 433 closure is known to perform reasonably well for regular and Poisson spatial patterns but causes the model 434 to underestimate the second moment for cluster patterns. A number of other closures also share this 435 limitation. The asymmetric power-2 closure, which expresses the third moment in terms of weighted 436 sums of lower order moments, can prove more successful for cluster spatial patterns. However it is not 437 always obvious which weighting constants are most appropriate and the closure has the potential to pre-438 dict negative average densities of triplets [Dieckmann and Law, 2000, Murrell et al., 2004, Raghib et al., 439

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2011]. 440

We have chosen to use kernels suitable for modelling fibroblast movement but different kernels could 441 be employed for applications in other contexts. However, there is a numerical constraint associated with 442 choosing the movement PDF μ . If using a PDF that has large positive values concentrated at pair dis-443 placements very close to zero, the spatial moment model cannot always accurately capture the full extent 444 of the directional bias at these short displacements. This, in turn, causes the model to underestimate 445 the extent of spatial structure. Choosing a movement PDF with positive values at displacements further 446 from zero, such as the PDF employed here, overcomes this issue. Expressing and solving the moment 447 dynamics equations in polar coordinates may also allow for greater flexibility in the choice of movement 448 PDF. 449

There are a number of possible extensions to the work presented here. For example, the model 450 could be extended to a birth-death-movement process to investigate how cell proliferation and cell death 451 contribute to the collective dynamics. Models of spatial moment dynamics that incorporate density-452 independent or density-dependent birth, death and movement have previously been discussed in the 453 literature (see for example [Dieckmann and Law, 2000, Murrell, 2005]) but it would be useful to explore 454 the role that neighbour-dependent directional bias plays in this setting. We have applied our model to 455 cell movement, however the types of interaction experienced by cells are also relevant in other contexts. 456 For instance, our model could be applied in an ecological context to consider the effect of directional 457 bias on moving animal populations. 458

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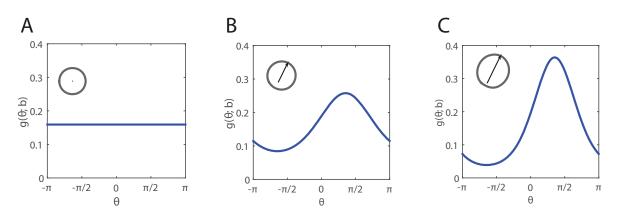


Figure 1: Examples of probability density function $g(\theta; \mathbf{b})$ (blue solid line) for movement in a direction $\theta \in [0, 2\pi]$. The neighbour-dependent bias \mathbf{b} is a vector indicating the direction $(\arg(\mathbf{b}))$ in which the greatest/lowest degree of crowding arises in a cell's neighbourhood, as well as the extent to which it occurs ($|\mathbf{b}|$). Insets are schematics illustrating $g(\theta; \mathbf{b})$ (grey solid line), where black arrows indicate the direction $(\arg(\mathbf{b}))$ in which an individual (black dot) is most biased to move. (A) Unbiased movement; (B) weak directional bias $\mathbf{b} = (0.25, 0.5)^T$; (C) strong directional bias $\mathbf{b} = (0.5, 1)^T$.

			Value		
Symbol	Description	Units	Fig. 2	Fig. 3	Fig. 4
m	intrinsic movement rate	$hour^{-1}$	10	10	5
α	strength of interaction for	$hour^{-1}$	0	1; 10; -1.5; -2	0
	movement rate				
σ_w	spatial range of interac-	$\mu { m m}$	0.5	0.5	10
	tions for movement rate				
β	strength of interaction for	$\mu { m m}$	0.1; 1; -0.03; -0.05	0	1000
	directional bias				
σ_v	spatial range of interac-	$\mu { m m}$	0.5	0.5	10
	tions for directional bias				
λ_{μ}	rate parameter of PDF for	$\mu {\rm m}^{-1}$	5	5	0.1
	movement distance				
σ_{μ}	spatial range of PDF for	$\mu { m m}$	0.05	0.05	2.5
	movement distance				
δr	bin width for PCF	$\mu { m m}$	0.12	0.12	8
Δ	grid spacing for discreti-	$\mu { m m}$	0.1	0.1	5
	sation of spatial displace-				
	$\mathrm{ment}\; \boldsymbol{\xi}$				
ξ_{max}	maximum distance of ξ_1 ,	$\mu { m m}$	4	4	150
	ξ_2 for computing $Z_2(\boldsymbol{\xi})$				

Table 1: Table of model parameters in order of appearance, with values used in the numerical results.

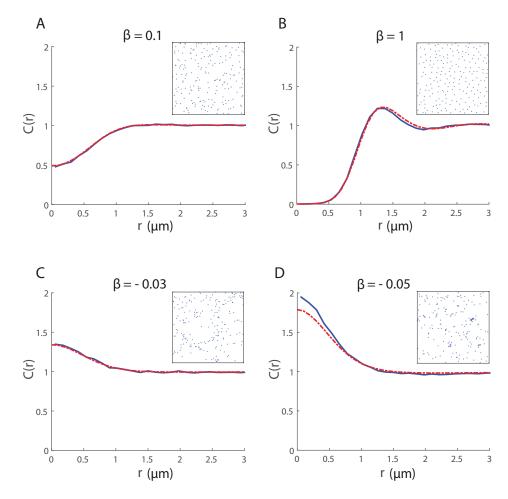


Figure 2: Spatial structure for 200 cells undergoing collective movement with neighbour-dependent directional bias ($\alpha = 0$ hour⁻¹) in a 20 μ m x 20 μ m domain at time t = 25 hours. The PCF $C_{IBM}(r)$ (blue solid line) provides a quantitative measure of the spatial structure in the simulated cell population and is computed (using a bin width $\delta r = 0.12 \ \mu$ m) by averaging results from 500 repeated simulations of the IBM. For ease of visualisation, a snapshot of the configuration of cells in a single simulation at t = 25 is shown in the inset. The spatial structure approximated by the spatial moment model (solved using $\Delta = 0.1 \ \mu$ m and $\xi_{max} = 4 \ \mu$ m) is expressed as a PCF $C_{SM}(r)$ (red dashed line). Parameters are $\alpha = 0$ hour⁻¹, $\sigma_w = \sigma_v = 0.5 \ \mu$ m, $m = 10 \ hour^{-1}$, $\lambda_{\mu} = 5 \ \mu$ m⁻¹, $\sigma_{\mu} = 0.05 \ \mu$ m; (A) $\beta = 0.1 \ \mu$ m; (B) $\beta = 1 \ \mu$ m; (C) $\beta = -0.03 \ \mu$ m; (D) $\beta = -0.05 \ \mu$ m.

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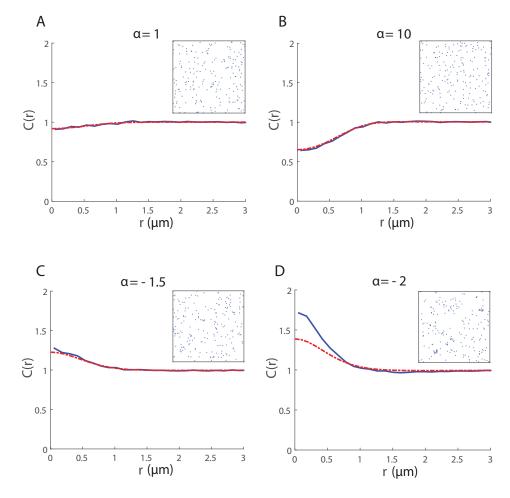


Figure 3: Spatial structure for 200 cells undergoing collective movement with neighbour-dependent motility ($\beta = 0 \ \mu$ m) in a 20 μ m x 20 μ m domain at time t = 25 hours. The PCF $C_{IBM}(r)$ (blue solid line) provides a quantitative measure of the spatial structure in the simulated cell population and is computed (using a bin width $\delta r = 0.12 \ \mu$ m) by averaging results from 500 repeated simulations of the IBM. For ease of visualisation, a snapshot of the configuration of cells in a single simulation at t = 25 is shown in the inset. The spatial structure approximated by the spatial moment model (solved using $\Delta = 0.1 \ \mu$ m and $\xi_{max} = 4 \ \mu$ m) is expressed as a PCF $C_{SM}(r)$ (red dashed line). Parameters are $\beta = 0 \ \mu$ m, $\sigma_w = \sigma_v = 0.5 \ \mu$ m, $m = 10 \ hour^{-1}$, $\lambda_{\mu} = 5 \ \mu m^{-1}$, $\sigma_{\mu} = 0.05 \ \mu$ m; (A) $\alpha = 1 \ hour^{-1}$; (B) $\alpha = 10 \ hour^{-1}$; (C) $\alpha = -1.5 \ hour^{-1}$; (D) $\alpha = -2 \ hour^{-1}$.

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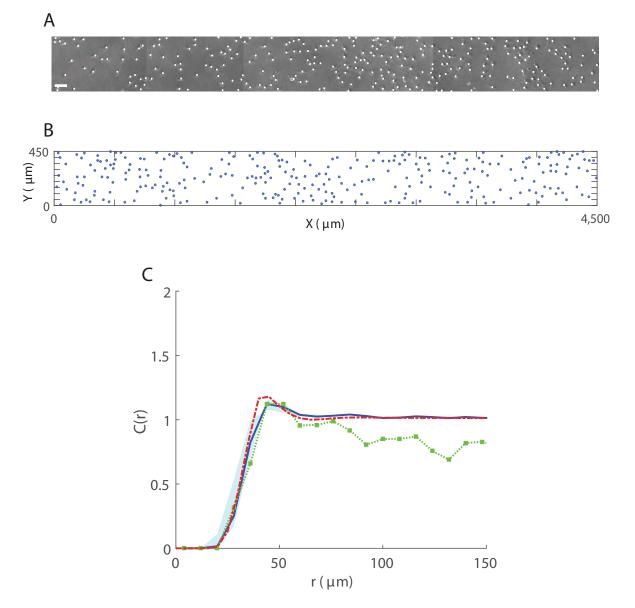


Figure 4: Spatial structure in 3T3 fibroblast cells for 286 cells in a 4500 μ m x 450 μ m region. (A) Sample image (obtained from a well containing cell suspension of approximate initial density 30,000 cells/ml) showing superimposed markers (white dots). Scale bar corresponds to 100 μ m; (B) Cell locations (blue dots) at t = 15 hours from a single IBM simulation. Parameters are $\alpha = 0$ hour⁻¹, $\beta = 1000 \ \mu$ m, $\sigma_w = \sigma_v = 10 \ \mu$ m, $m = 5 \ hour^{-1}$, $\lambda_\mu = 0.1 \ \mu$ m⁻¹, $\sigma_\mu = 2.5 \ \mu$ m; (C) PCF $C_{IBM}(r)$ (blue solid line) obtained from averaging results from 200 simulations of the IBM at t = 15 hours. PCFs computed from the IBM using values of β within the range $\pm 75\%$ of $\beta = 1000 \ \mu$ m, lie within the region indicated by the blue shaded area. PCF $C_{exp}(r)$ (green squares-dotted line) generated from experimental image, for $\delta r = 8 \ \mu$ m. PCF $C_{SM}(r)$ (red dashed line) approximated by spatial moment model at t = 15 hours, for $\Delta = 5 \ \mu$ m and $\xi_{max} = 150 \ \mu$ m.

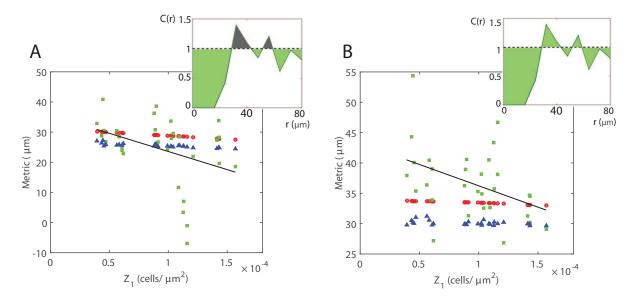


Figure 5: Relationship between average cell density and the extent of spatial structure. Metrics calculated from IBM (blue triangles), spatial moment model (red circles) and *in vitro* data (green squares) for the average cell densities in each of the images. A regression line (black line) is fitted to the experimental data. (A) Metric calculated by integrating (1-C(r)) over displacements $0 \le r \le 80 \ \mu$ m, i.e. summing the green-shaded area and subtracting the grey-shaded area (inset Fig.). (B) Metric calculated by integrating |1 - C(r)| over displacements $0 \le r \le 80 \ \mu$ m, i.e. summing the green-shaded area (inset Fig.).