

# Corticospinal excitability remains unchanged in the presence of residual force enhancement and does not contribute to increased torque production

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**Background.** Following stretch of an active muscle, muscle force is enhanced, which is known as residual force enhancement (rFE). As earlier studies found apparent corticospinal excitability modulations in the presence of rFE, this study aimed to test whether corticospinal excitability modulations contribute to rFE.

**Methods.** Fourteen participants performed submaximal plantar flexion stretch-hold and fixed-end contractions at 30% of their maximal voluntary soleus muscle activity in a dynamometer. During the steady state of the contractions, participants either received subthreshold or suprathreshold transcranial magnetic stimulation (TMS) of their motor cortex, while triceps surae muscle responses to stimulation were obtained via electromyography (EMG), and net ankle joint torque was recorded. B-mode ultrasound imaging was used to confirm muscle fascicle stretch during stretch-hold contractions in a subset of participants.

**Results.** Following stretch of the plantar flexors, an average rFE of 7% and 11% was observed for contractions with subthreshold and suprathreshold TMS, respectively. 41-46 ms following subthreshold TMS, triceps surae muscle activity was suppressed by 19-25%, but suppression was not significantly different between stretch-hold and fixed-end contractions. Similarly, the reduction in plantar flexion torque following subthreshold TMS was not significantly different between contraction conditions. Motor evoked potentials, silent periods and superimposed twitches following suprathreshold TMS were also not significantly different between contraction conditions.

**Discussion.** As TMS of the motor cortex did not result in any differences between stretch-hold and fixed-end contractions, we conclude that rFE is not linked to changes in corticospinal excitability.

1

2 **Corticospinal excitability remains unchanged in the**  
3 **presence of residual force enhancement and does not**  
4 **contribute to increased torque production**

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19

20 **Abstract**

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42 excitability.

43

## 44 Introduction

45 It is well known that stretch of an active muscle results in increased force production during the  
46 isometric steady state following stretch compared with the steady-state force produced at the  
47 same muscle length and activation level during a fixed-end contraction. This is referred to as  
48 residual force enhancement (rFE), which was initially investigated *in situ* (Abbott & Aubert,  
49 1952). Decades later, rFE was investigated in isolated muscle fibres and two opposing  
50 mechanisms were suggested: (1) that rFE following active muscle stretch results from non-  
51 uniformities in sarcomere lengths (Julian & Morgan, 1979), and (2) that rFE is due to the  
52 engagement of a parallel non-contractile element during active stretch (Edman, Elzinga & Noble,  
53 1978). Since then, numerous studies have investigated the development of rFE and suggested  
54 additional potential underlying mechanisms. These suggestions include stretch-induced increases  
55 in the number of cross-bridge attachments and/or the attachment of the second myosin head, and  
56 an increase in the average cross-bridge force and strain (Brunello et al., 2007; Rassier, 2012;  
57 Herzog, 2014). Lately, the engagement of a parallel non-contractile element during active stretch  
58 has been related to titin, which might increase its force contribution in the presence of calcium  
59 and by interacting with actin (Nishikawa, 2016; Herzog, 2018; Freundt & Linke, 2019).

60  
61 Complementary to *in vitro* research, several *in vivo* studies have investigated rFE (as  
62 approximated by net joint torque) during electrically-stimulated and voluntary contractions  
63 (Seiberl, Power & Hahn, 2015; Chapman et al., 2018). rFE during voluntary contractions has  
64 been observed for small muscles of the thumb (Lee and Herzog, 2002), for large muscles of the  
65 lower limb (Pinniger & Cresswell, 2007; Seiberl et al., 2010), and during multi-joint multi-  
66 muscle contractions of the lower limbs (Hahn et al., 2010). The potential relevance of rFE during  
67 human movement was demonstrated in studies that investigated rFE during submaximal  
68 voluntary contractions and at joint angle configurations that mimicked those of human  
69 locomotion (Hahn et al., 2010; Seiberl et al., 2013; Paternoster et al., 2016).

70  
71 Besides rFE, several *in vivo* studies have documented an activation reduction (AR) during the  
72 steady state following active muscle stretch. In contrast to rFE, which is observed when muscle  
73 activity is matched between stretch-hold (STR) and fixed-end reference (REF) contractions, AR  
74 occurs when force or torque is matched between contraction conditions. AR refers to a reduced  
75 muscle activity level needed to maintain a given force/torque following active muscle stretch  
76 compared with fixed-end contractions at the same final muscle length. Several studies have  
77 reported AR and concluded that neuromuscular efficiency following active muscle stretch is  
78 increased, which might be explained by enhanced passive forces due to increased titin forces  
79 (Oskouei & Herzog, 2005; Altenburg et al., 2008; Seiberl et al., 2012; Joumaa & Herzog, 2013;  
80 Jones, Power & Herzog, 2016; Mazara et al., 2018; Paquin & Power, 2018). However, Paquin  
81 & Power (2018) also found a rightward shift in the EMG-torque relationship following active  
82 stretch compared with fixed-end reference conditions, which indicates that the neuromuscular  
83 activation strategy might be altered in the presence of rFE.

84

85 Changes in EMG following active stretch have motivated a number of studies to investigate the  
86 neural control and/or neural modulations that occur during the isometric steady state following  
87 active muscle stretch (*Altenburg et al., 2008; Hahn et al., 2012; Paquin & Power, 2018; Sypkes*  
88 *et al., 2018; Contento, Dalton & Power, 2019; Jakobi et al., 2020*). For example, *Altenburg et al.*  
89 *(2008)* examined single motor unit behaviour of the vastus lateralis muscle during AR following  
90 active muscle stretch. These authors found similar discharge rates of VL motor units between  
91 STR and REF conditions, which led them to conclude that a derecruitment of motor units might  
92 have occurred during AR (*Altenburg et al. 2008*).

93

94 Two further studies used motor evoked potentials (MEPs) and cervicomedullary motor evoked  
95 potentials (CMEPs) to investigate excitability modulations at cortical and spinal sites in the  
96 presence of rFE (*Hahn et al., 2012; Sypkes et al., 2018*). In the first study, *Hahn et al. (2012)*  
97 found larger MEPs and larger V-waves, but unchanged CMEPs, following stretch of the plantar  
98 flexors during maximal voluntary contractions. Based on the larger MEPs and unchanged  
99 CMEPs, all normalised to Mmax, it was interpreted that cortical excitability increased, but spinal  
100 excitability was unchanged in the rFE state. The increased V-waves were considered to represent  
101 greater cortical motoneuronal output and/or an increase in spinal stretch reflex excitability  
102 following active muscle stretch (*Hahn et al. (2012)*). In the second study, *Sypkes et al. (2018)*  
103 found smaller CMEPs (normalised to Mmax) and an unchanged MEP/CMEP ratio in the  
104 presence of rFE during submaximal dorsiflexion contractions, which was interpreted as reduced  
105 spinal excitability, but no change in cortical excitability. However, because it is not reported  
106 whether the MEP/Mmax ratio changed or remained constant, and Mmax varied within  
107 participants from -20 to 17% between the ISO and RFE conditions in that study, it is virtually  
108 impossible to interpret the provided MEP/CMEP ratio (see supplementary material Table 1 for a  
109 detailed explanation). Further, assuming that the MEPs' corresponding Mmax was unchanged,  
110 the combined results of the reduced CMEPs and unchanged MEPs in the study of *Sypkes et al.*  
111 *(2018)* can also be interpreted as reduced spinal excitability and increased cortical excitability  
112 (*Martin, Gandevia & Taylor, 2006; Martin et al., 2009*). Accordingly, both studies on neural  
113 excitability (*Hahn et al. 2012* and *Sypkes et al. 2018*) might indicate increased cortical  
114 excitability in the presence of rFE, but this currently remains a matter of debate.

115

116 Despite different muscle groups being tested under different levels of voluntary effort, the  
117 ambiguous results from the earlier studies likely rises due to both studies being underpowered  
118 and the statistical significance occurring due to chance. That is, the observed changes in CMEPs  
119 (*Sypkes et al. 2018*) and MEPs (*Hahn et al. 2012*) in the rFE state, while significant, were not  
120 large (Cohen's  $d_z = 0.70$  and  $0.75$ , respectively). A paired t-test with 11 participants, which was  
121 the maximum sample size tested across these studies, would not have been able to reliably detect  
122 effects smaller than a Cohen's  $d_z$  of  $0.94$  with 80% power at a two-tailed alpha level of  $0.05$ .  
123 Further, only a few responses (i.e. MEPs) to transcranial magnetic stimulation (TMS) were

124 averaged ( $n = 6$  in *Hahn et al. 2012* and  $n = 4$  minus outliers in *Sypkes et al. 2018*), although it  
125 has been shown that as many as 20 MEPs are needed to accurately estimate corticospinal  
126 excitability (*Brownstein et al., 2018*).

127

128 Therefore, the aim of this study was twofold. First, we wanted to partly replicate the above-  
129 mentioned studies and investigate whether corticospinal excitability was altered in the presence  
130 of rFE. This was done by eliciting 20 MEPs via TMS in the presence (STR) and absence (REF)  
131 of rFE in an adequately-powered study. Second, this study was designed to investigate whether  
132 cortical inhibition induced by subthreshold TMS affects force production in the presence of rFE  
133 differently to fixed-end reference contractions without rFE.

134

135 Based on a critical evaluation of previous research (*Hahn et al., 2012; Sypkes et al., 2018*), we  
136 predicted that the activation of cortical interneurons and pyramidal neurons by suprathreshold  
137 TMS (*Rothwell, 1997; Rossini et al., 2015*) would result in similar MEPs and superimposed  
138 twitches in the presence of rFE compared with the fixed-end reference contractions with matched  
139 background muscle activity. Further, we predicted that inhibiting motor cortical neurons by  
140 subthreshold TMS (*Davey et al., 1994; Petersen et al., 2001; Zuur et al., 2010*) would lead to a  
141 similar suppression in muscle activity (EMG) and plantar flexion torque in the presence of rFE  
142 compared with fixed-end reference contractions with matched background muscle activity. If  
143 both predictions hold, the results would indicate that corticospinal excitability is not altered and  
144 does not contribute to the increased torque production in the presence of rFE.

145

## 146 **Materials & Methods**

### 147 **Participants**

148 Fourteen recreationally-active participants (six women,  $26.7 \pm 5.3$  yrs.,  $1.77 \pm 0.11$  m, and  $74.0 \pm$   
149  $16.8$  kg) voluntarily participated in this study after providing free written informed consent. A  
150 total sample size of 10 was calculated to have over 90% power to detect a minimum effect size  
151 of 0.62 with a two-tailed alpha level of 0.05. This was calculated with Superpower  
152 ([https://shiny.ieis.tue.nl/anova\\_power/](https://shiny.ieis.tue.nl/anova_power/)) from 2000 simulations using data from (*Hahn et al.,*  
153 *2012*), which incorporated a  $2 \times 2$  repeated-measures design and observed a common standard  
154 deviation of 5.11 (note a conservative within-subjects factor correlation of 0.5 was used in the  
155 simulations). Participants were free of any neuromuscular disorders and injuries to their right  
156 lower limb. The experimental protocol was approved by the local Ethics Committee of the  
157 Faculty of Sport Science at Ruhr University Bochum, Germany (EKS10072018).

158

### 159 **Experimental setup**

160 During the experiment, participants laid prone on a dynamometer bench with their upper body  
161 supported by their forearms and their right foot tightly strapped onto the footplate attachment of  
162 a dynamometer (IsoMed 2000, D&R Ferstl GmbH, GER). The axes of rotation of the ankle joint  
163 and the dynamometer were aligned prior to testing and the foot was firmly secured to the  
164 footplate using three straps (forefoot, ankle, heel) to minimize heel lift during the plantar flexion

165 contractions. Additionally, the participants' hips were secured to the dynamometer bench with a  
166 belt. A computer monitor positioned directly in front of the participants was used to provide  
167 visual feedback of their soleus muscle activity (moving 0.25-s root-mean-square amplitude  
168 calculation) during the plantar flexion contractions. Net ankle joint torques and ankle joint angles  
169 of the right leg were sampled at 1 kHz using a 16-bit Power-3 1401 and Spike2 data collection  
170 system (v.8.01, Cambridge Electronics Design, Cambridge, UK)

171

### 172 **Surface electromyography**

173 Muscle activity and responses to TMS from soleus (SOL), medial gastrocnemius (MG) and  
174 lateral gastrocnemius (LG) muscles were recorded via bipolar surface electromyography (EMG).  
175 EMG of the antagonistic tibialis anterior (TA) was not obtained as it has been shown that TA  
176 EMG during fixed-end plantar flexion is more likely from crosstalk than coactivation (*Raiteri,*  
177 *Cresswell & Lichtwark, 2015*). After skin preparation, self-adhesive surface electrodes (Ag/  
178 AgCl, Kendall, ECG Electrodes, 8 mm recording diameter) were positioned with an inter-  
179 electrode distance of 20 mm over the triceps surae muscle bellies following the  
180 recommendations of SENIAM (Hermens et al., 1999). A reference electrode was placed over the  
181 right fibular head. Cables were fixed to the skin with tape to prevent motion artefacts. EMG  
182 signals were amplified 1000 times by a multichannel analogue amplifier (AnEMG12,  
183 Bioelectronica, Turin, IT) and band-pass filtered between 10 Hz and 4.4 kHz, prior to being  
184 sampled at 5 kHz. EMG and torque/angle data were synchronised and sampled using the same  
185 analogue-to-digital converter and software described above.

186

### 187 **Transcranial Magnetic Stimulation (TMS)**

188 TMS (MagPro Compact, MagVenture, Farum, Denmark) was used to either inhibit or activate  
189 the motor cortical area of the right plantar flexor muscles in the left hemisphere, slightly left of  
190 the vertex, via a double-cone coil (D-B80 Butterfly Coil, MagVenture, Farum, Denmark). The  
191 coil had monophasic current running through its centre in an anterior-posterior direction. The  
192 vertex was marked on the scalp and defined as halfway between the left and right processus  
193 zygomaticus ossis temporalis and halfway between the os nasale and the external occipital  
194 protuberance. The vertex location helped to find the optimal location for TMS of the motor  
195 cortical area innervating the right plantar flexor muscles (TMS hotspot), which is generally  
196 defined as the position in which a single stimulation evokes the largest peak-to-peak MEP  
197 amplitude in the target muscle (Siebner and Ziemann, 2007). In order to find the TMS hotspot,  
198 several stimuli were delivered while the TMS coil was slightly left, in front or behind the vertex,  
199 while participants performed fixed-end plantar flexion contractions at 30% of their maximal  
200 voluntary EMG activity (MVA) as measured during maximal voluntary fixed-end contractions  
201 (see experimental protocol). Once the TMS hotspot was located, the wings of the coil were  
202 marked on the scalp with a semi-permanent marker. Subthreshold and suprathreshold intensities  
203 were then determined by either decreasing or increasing the stimulator output. To achieve a  
204 suppression of soleus muscle activity, stimulator output was reduced in small increments until  
205 the active motor threshold (AMT) was reached. This threshold was defined as the point when

206 stimulation during 30% MVA resulted in visible MEP responses in only five of ten consecutive  
207 trials (*Petersen et al.*, 2001). Once the AMT was determined, stimulation intensity was slightly  
208 reduced again so that MEPs were no longer elicited. For activation of the motor cortex,  
209 stimulator output was increased until MEPs were clearly visible in comparison to the  
210 immediately preceding background EMG in at least five consecutive trials.

211

### 212 **Ultrasound imaging**

213 Muscle fascicle behaviour of the MG from three participants was examined during  
214 familiarisation sessions using B-mode ultrasound imaging (LS128 CEXT-1Z, Teleded, Vilnius,  
215 Lithuania) to ensure muscle fascicle stretch occurred during ankle rotation in the stretch-hold  
216 condition. Ultrasound images were recorded using a flat, linear, 128-element transducer  
217 (LV7.5/60/128Z-2, 6 MHz, 60 x 50 mm (width x depth)) operating at ~60 fps in EchoWave II  
218 software (Teleded, Vilnius, Lithuania). The transducer was placed on the skin over the MG mid-  
219 muscle belly in the longitudinal plane and rotated to obtain a clear image with continuous  
220 aponeuroses and muscle fascicles. The position of the probe was marked on the skin to ensure  
221 consistent placement during the stretch-hold contractions.

222

### 223 **Contraction conditions**

224 The experiment involved participants performing submaximal plantar flexion contractions at  
225 30% MVA. The background activity level was controlled throughout the contractions by having  
226 participants visually match their SOL EMG amplitude (moving 0.25-s root-mean-square (RMS)  
227 amplitude calculation) to a horizontal cursor on a computer monitor. The conditions involved  
228 fixed-end reference contractions (REF) at 20° dorsiflexion (DF) and active stretch-hold  
229 contractions (STR) from 0°-20° DF (0° refers to the sole of the foot being perpendicular to the  
230 shank).

231

232 All contractions started with a 2-s linear ramp from 0-30% MVA. Following the ramp, the  
233 isometric steady state during REF was maintained for 13-s. During STR, the ramp was followed  
234 by a 1-s isometric steady state at the initial ankle joint angle (0° DF), before the active plantar  
235 flexor muscles were stretched to an ankle joint angle of 20° DF at an angular velocity of 30°s<sup>-1</sup>.  
236 Following active stretch, participants maintained the subsequent isometric steady state for ~11-s,  
237 resulting in an overall contraction duration of 15-s (Fig. 1).

238

### 239 **Experimental protocol**

240 Participants attended two sessions on two different days. In the first session, participants were  
241 familiarised with the test protocol and trained to perform maximal voluntary fixed-end  
242 contractions (MVC) and the submaximal contractions described above. Additionally, participants  
243 were familiarised with TMS.

244

245 The second session consisted of the test protocol (Fig. 2). After a short warm-up (eight  
246 submaximal plantar flexion contractions with increasing torque), at least two MVCs were

247 performed to determine 100% MVA. Participants were instructed to push their forefoot into the  
248 footplate as hard as possible and to maintain the contractions so that a torque plateau was clearly  
249 visible. MVC torque was calculated as the difference between peak torque during the contraction  
250 and the mean baseline over 500 ms prior to the beginning of contraction. To ensure that the  
251 MVCs were repeatable, peak-to-peak torques were required to be within a 5% range. 100%  
252 MVA was determined as the smoothed (moving 0.25-s RMS amplitude calculation) SOL EMG  
253 amplitude at peak MVC torque from the MVC with the highest peak-to-peak torque. Three  
254 minutes of rest was provided between MVCs to minimise fatigue.

255

256 Following the MVCs, the TMS hotspot and the subthreshold and suprathreshold TMS intensities  
257 were determined during sustained fixed-end contractions at 30% MVA. Once hotspot and  
258 stimulation intensities were determined, 100 subthreshold stimulations were delivered for each  
259 contraction condition to study motor cortex inhibition. For this purpose, contractions from each  
260 condition (i.e. STR or REF) were separated into ten sets with ten TMS (1 Hz) during the  
261 isometric steady state phase of the contractions at 20° DF starting 5-s following contraction onset  
262 (Fig. 1). Contractions were randomised and a minimum of three minutes rest was provided  
263 between each set. Activation of the motor cortex was investigated by providing 20  
264 suprathreshold stimulations per contraction condition. Suprathreshold stimulations were  
265 delivered at the same time points as the subthreshold stimulations, but participants performed  
266 only two contractions per condition. The contractions with suprathreshold TMS were always  
267 performed after all sets of the subthreshold stimulations had been completed. During all  
268 contractions, trials were excluded and repeated if participants could not maintain their soleus  
269 EMG activity within 25-35% MVA.

270

## 271 **Data analysis**

### 272 **Residual Force Enhancement (rFE)**

273 rFE for the subthreshold and suprathreshold conditions was determined by calculating the  
274 difference between the isometric steady-state torque during the STR and REF conditions. Net  
275 plantar flexion torque was averaged across contractions for each contraction condition and mean  
276 rFE was calculated during the isometric steady state at 20° DF, from 500-990 ms after each TMS  
277 stimulus. While most rFE studies have analysed torque or force with a 500 ms time window, we  
278 excluded the final 10 ms to ensure that the stimulations delivered at 1 Hz would not affect our  
279 analysis. Stimulations delivered before the isometric steady state of SOL muscle activity were  
280 excluded. In cases where participants showed no rFE for a specific stimulation condition (i.e.  
281 suprathreshold or subthreshold TMS), their data were excluded from statistical analysis..

282

### 283 **TMS inhibition**

284 Suppression of muscle activity (SOL, MG and LG) following subthreshold TMS was determined  
285 via averaged rectified raw EMG signals from each muscle and contraction condition. Waveform  
286 averages were calculated over a time window of 100 ms after stimulation and again, stimulations  
287 delivered before the isometric steady state of SOL muscle activity were excluded. The latency

288 and duration of EMG amplitude suppression were determined using the evaluation methods by  
289 *Petersen et al. (2001)* and *Zuur et al. (2010)*. The onset of EMG amplitude suppression was  
290 marked when the EMG amplitude first dropped under the background EMG amplitude (mean  
291 value calculated 15–25 ms following stimulation) for at least 4 ms. The offset of EMG amplitude  
292 suppression was calculated when the EMG amplitude rose above the background EMG  
293 amplitude for at least 1 ms (*Zuur et al., 2010*) (Fig. 3). The mean EMG amplitude between the  
294 onset and offset of suppression was calculated and compared with the background EMG  
295 amplitude right before suppression.

296

297 Torque production following TMS-induced EMG amplitude suppression was analysed via  
298 moving correlations (50-ms time intervals) between the torque of the STR and REF conditions.  
299 A reduction in torque due to TMS-induced EMG amplitude suppression was identified when  
300 torque data of REF and STR contractions were correlated ( $r \geq 0.7$ , i.e. a very large effect). This  
301 data analysis was based on the random fluctuations in torque steadiness that should result in non-  
302 correlated torque signals. However, when torque was affected by the TMS-induced EMG  
303 amplitude suppression in a similar manner, large positive correlations were expected. Once the  
304 time window of torque reduction was identified, the torque offset between the REF and STR  
305 conditions was removed by subtracting the mean torque difference between REF and STR over  
306 the first 10 ms after the onset of torque reduction. Finally, the mean torque during the period of  
307 TMS-induced torque reduction (i.e. during the times where  $r \geq 0.7$ ) was calculated for REF and  
308 STR and compared between contraction conditions.

309

### 310 **TMS activation**

311 MEPs of SOL, MG and LG following suprathreshold TMS were calculated as peak-to-peak  
312 amplitudes from the raw EMG signals and averaged across contractions for each muscle and  
313 contraction condition (*Lewis et al., 2014*) (Fig. 4). Additionally, the silent period (SP) duration  
314 was analysed for both contraction conditions as the time from stimulation to the end of the SP.  
315 The end of the SP was defined as the time when the EMG signal following the MEP exceeded  
316 the threefold standard deviation (SD) of the raw EMG during the visually apparent SP (Fig. 4).  
317 SD during the SP was determined as the smallest SD of the raw EMG over a moving 30-ms  
318 window. The sizes of superimposed twitch torques following suprathreshold TMS were  
319 calculated separately as the difference in torque between the peak of the twitch and the torque at  
320 the time of stimulation and averaged for each contraction condition.

321

### 322 **Statistical analysis**

323 A two-way repeated-measures ANOVA was used to assess if the difference in triceps surae  
324 muscle activity between REF and STR conditions across the tested muscles were significantly  
325 different (contraction type  $\times$  muscle). Due to missing values, two-way repeated-measures  
326 restricted maximum likelihood mixed-effects models were used to test for significant differences  
327 in EMG amplitude suppression (6 missing values), MEP amplitude (2 missing values) and SP  
328 duration (5 missing values) between REF and STR conditions across the tested muscles

329 (contraction type  $\times$  muscle). If a significant interaction was observed, Bonferroni post-hoc  
330 comparisons were performed to determine which muscle significantly differed between REF and  
331 STR conditions. Paired t-tests or Wilcoxon signed-rank tests, based on the normality of paired  
332 differences as assessed by Shapiro-Wilk tests, were used to test for significant differences in  
333 steady-state plantar flexion torque, torque reduction following subthreshold TMS, and  
334 superimposed twitch torque following suprathreshold TMS between REF and STR conditions.  
335 The alpha level was set at 0.05 and statistical analysis was performed using Prism 9 software  
336 (GraphPad, USA). Values are presented as mean  $\pm$  SD in the text.

337

## 338 **Results**

339 Five and four participants were excluded from statistical analysis as they did not show rFE  
340 following the subthreshold (n=9) and suprathreshold (n=10) stimulations, respectively.

341

### 342 **Contraction conditions**

343 During both contraction conditions, participants managed to maintain a constant level of muscle  
344 activity ( $\sim$ 30% MVA). EMG of SOL, MG and LG did not significantly differ between STR and  
345 REF conditions ( $P = 0.504$ ) during the isometric steady state of contractions with suprathreshold  
346 TMS. However, for subthreshold TMS, while EMG of SOL or LG was not significantly different  
347 between conditions (SOL:  $P > 0.999$ , LG:  $P > 0.999$ ), EMG of MG was significantly higher in  
348 the REF compared with STR condition ( $P = 0.001$ ; see Supplementary Fig. 1). Ultrasound  
349 imaging confirmed that the muscle-tendon unit stretch during the 20° dynamometer rotation of  
350 the stretch-hold contraction resulted in muscle fascicle stretch of the MG at 30% MVA (n=3).

351

### 352 **Contractions with subthreshold TMS**

353 The isometric steady-state net plantar flexion torque in the STR condition exceeded the time-  
354 matched steady-state torque in the REF condition (STR:  $105.9 \pm 34.5$  Nm; REF:  $99.0 \pm 33.4$  Nm,  
355  $P = 0.004$ ), which resulted in mean rFE of  $7.3 \pm 4.2\%$  (Fig. 5A).

356 Subthreshold stimulation of the motor cortex led to significant ( $P < 0.001$ ) EMG amplitude  
357 suppression for SOL, MG and LG without any significant difference in amplitude suppression ( $P$   
358  $= 0.794$ ) between STR and REF conditions. The mean EMG amplitude suppression ranged  
359 between 19-25% of the background EMG amplitude, it occurred 41-46 ms after stimulation, and  
360 it lasted 10-15 ms in total (Table 1). After accounting for the torque offset between the REF and  
361 STR conditions, the net plantar flexor torque following EMG amplitude suppression did not  
362 significantly differ ( $P = 0.729$ ) between STR and REF conditions.

363

### 364 **Contractions with suprathreshold TMS**

365 The isometric steady-state net plantar flexion torque in the STR condition exceeded the time-  
366 matched steady-state torque in the REF condition (STR:  $89.4 \pm 26.0$  Nm; REF:  $82.2 \pm 27.2$  Nm,  
367  $P = 0.002$ ), which resulted in mean rFE of  $10.8 \pm 10.0\%$  (Fig. 5A). For all muscles analysed  
368 (SOL, MG, LG), MEP amplitudes ( $P = 0.529$ ) and SP durations ( $P = 0.609$ ) following

369 suprathreshold TMS did not significantly differ between STR and REF conditions (MEP: Fig.  
370 5B; SP: Table 2). TMS-evoked superimposed twitches following suprathreshold stimulations  
371 were  $9.1 \pm 3.5$  Nm (STR) and  $8.6 \pm 3.5$  Nm (REF), and did not significantly differ between STR  
372 and REF conditions ( $P = 0.131$ , Fig. 5C).

373

374

## 375 Discussion

376 The aims of this study were to determine whether corticospinal excitability is modulated in the  
377 presence of rFE and to assess whether an inhibition of motor cortical neurons affects muscle  
378 activity and the increased torque production in the presence of rFE compared with fixed-end  
379 reference contractions without rFE. To achieve this, we compared reductions in EMG activity  
380 and torque production following inhibition of motor cortical neurons, and MEPs, SPs and  
381 superimposed twitch torques following activation of motor cortical neurons between submaximal  
382 stretch-hold and fixed-end contractions.

383

384 Participants managed to keep muscle activity constant (30% MVA) throughout the fixed-end  
385 reference contractions and during the isometric steady state of the stretch-hold contractions. As  
386 the observed differences in MG background EMG were rather small (2% MVA), they are  
387 considered negligible regarding the interpretation of the results. Mean rFE magnitudes of 7%  
388 (subthreshold TMS) and 11% (suprathreshold TMS) were observed during the steady state in  
389 STR compared with REF, which is in line with former studies (*Oskouei & Herzog, 2005*;  
390 *Pinniger & Cresswell, 2007*; *Seiberl et al., 2013*; *Paternoster et al., 2016*). Inhibition of motor  
391 cortical neurons by subthreshold TMS caused reductions in EMG activity and net plantar flexion  
392 torque, however the reductions did not differ significantly between contraction conditions.  
393 Similarly, MEP amplitudes, SP durations and superimposed twitch torque amplitudes evoked by  
394 suprathreshold TMS were not significantly different between STR and REF conditions.

395

396 Following subthreshold TMS, we found a suppression of triceps surae muscle activity by 19-  
397 24% relative to the background activity. This is similar to the ~15% EMG amplitude suppression  
398 in SOL induced by subthreshold TMS during walking and jumping (*Petersen et al., 2001*; *Zuur*  
399 *et al., 2010*), but smaller compared with the 50% suppression in hand and arm muscles during  
400 voluntary fixed-end contractions (*Davey et al., 1994*). Also, the latency and the duration of the  
401 observed EMG amplitude suppression was similar to values reported previously (*Petersen et al.,*  
402 *2001*; *Zuur et al., 2010*). Importantly, the TMS-induced EMG amplitude suppression showed no  
403 significant difference between STR and REF conditions, which also resulted in similar  
404 magnitudes of torque reduction for both contraction conditions. This supports our prediction that  
405 inhibiting motor cortical neurons by subthreshold TMS would not affect the STR and REF  
406 conditions differently.

407

408 Our data also support our prediction that suprathreshold TMS does not elicit larger MEP  
409 amplitudes and SP durations, or larger superimposed twitch torque amplitudes in the presence of  
410 rFE compared with fixed-end reference contractions (twitch amplitude of ~9 Nm for both  
411 contraction conditions). The unchanged MEP amplitudes and SP durations indicate that  
412 corticospinal excitability was unaltered in the presence of rFE, which, based on a re-analysis of  
413 the previously published data is in line with the earlier studies on corticospinal excitability in the  
414 presence of rFE (*Hahn et al. 2012; Sypkes et al. 2018*).

415  
416 Interestingly, we found that activation of the motor cortex with a given suprathreshold  
417 stimulation intensity elicited comparable twitch torque amplitudes for both contraction  
418 conditions, despite steady-state torques following active stretch being enhanced because of rFE.  
419 We think that this finding further supports our interpretation of an unaltered corticospinal in the  
420 presence of rFE. This is because increased cortical excitability, but unchanged spinal excitability  
421 in the presence of rFE, as observed by *Hahn et al. (2012)*, should lead to larger superimposed  
422 twitches, while unchanged cortical excitability, but reduced spinal excitability in the presence of  
423 rFE, as observed by *Sypkes et al. (2018)*, should lead to smaller superimposed twitches.  
424 However, as neither of these findings were observed in the current study, we think that the  
425 overall excitability of the neuromuscular system was unchanged in the presence of rFE.

426  
427 Finally, from a mechanical point of view, the unchanged superimposed twitches are in opposite  
428 to what would be expected based on the work of *Merton (1954)*, who showed that superimposed  
429 twitch size decreases as the pre-stimulus torque of the voluntary contraction increases.  
430 Accordingly, we interpret the equally-sized superimposed twitches following TMS in the  
431 presence of rFE as support for the idea that rFE is not due to a higher number of cross bridges  
432 following active stretch, but due to passive structural elements within the muscle that are  
433 engaged during active stretch (*Edman, Elzinga & Noble, 1978; Nishikawa, 2016; Herzog, 2018;*  
434 *Freundt & Linke, 2019*). The contribution of such passive structural elements to the increased  
435 force and torque production following stretch could also explain the observed reduction in EMG  
436 activity following stretch observed in force/torque-matched contractions (*Oskouei & Herzog,*  
437 *2005; Seiberl et al., 2012*).

438

### 439 **Limitations**

440 First, we only performed TMS of the motor cortex to assess corticospinal excitability, which  
441 does not allow us to distinguish between cortical and spinal aspects of corticospinal excitability.  
442 Accordingly, the unchanged MEP amplitudes and SP durations that we found in the presence of  
443 rFE compared with the reference contractions do not exclude potential cortical and/or spinal  
444 modulations in the presence of rFE. Second, we did not obtain M-waves to normalise MEPs.  
445 Although the earlier studies (*Hahn et al. 2012; Sypkes et al. 2018*) reported statistically  
446 unchanged M-wave amplitudes in the presence of rFE, theoretically, we might have missed  
447 potential changes in MEP amplitudes due to possible changes in M-wave amplitudes. Further,  
448 the similar superimposed twitches in the STR and REF conditions provide support that the

449 overall excitability of the neuromuscular system was unchanged. Finally, we did not obtain TMS  
450 input-output curves, which would reveal the relative sizes of the measured MEPs. However,  
451 when setting up the individual stimulation intensities, we ensured that MEPs could still increase  
452 with increasing stimulation intensity so that changes due to the contraction conditions would be  
453 detectable.

454

## 455 **Conclusions**

456 In conclusion, we found that subthreshold and suprathreshold TMS of motor cortical neurons  
457 affected muscle activity and torque production, but the mechanical and neural responses to TMS  
458 did not differ between stretch-hold and fixed-end reference contractions. This is in line with our  
459 predictions and suggests that corticospinal excitability remains unaltered in the presence of rFE.  
460 This further suggests that the enhanced torque production following active muscle stretch is not  
461 due to changes in corticospinal excitability, but that rFE is likely caused by a stretch-induced  
462 engagement of passive structural elements.

463

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465 None.

466

467

468 **References**

469

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- 566

**Table 1** (on next page)

EMG responses following subthreshold transcranial magnetic stimulation.

Mean  $\pm$  SD values of EMG amplitude suppression following subthreshold transcranial magnetic stimulation from soleus (SOL), medial gastrocnemius (MG) and lateral gastrocnemius (LG) muscles during stretch-hold (STR) and fixed-end reference (REF) contractions.

	<b>SOL</b>	<b>MG</b>	<b>LG</b>
<b>EMG suppression REF [%]</b>	24.0 ± 6.7	24.7 ± 7.2	19.4 ± 2.3
<b>EMG suppression STR [%]</b>	24.2 ± 5.4	23.7 ± 6.9	20.9 ± 6.4
<b>Latency REF [ms]</b>	44 ± 4	41 ± 5	44 ± 5
<b>Latency STR [ms]</b>	45 ± 3	43 ± 6	46 ± 5
<b>Duration REF [ms]</b>	14 ± 4	15 ± 4	12 ± 5
<b>Duration STR [ms]</b>	13 ± 6	12 ± 4	10 ± 4

---

1

2

**Table 2** (on next page)

EMG responses following suprathreshold transcranial magnetic stimulation.

Mean  $\pm$  SD values of motor evoked potentials (MEPs) and silent periods (SPs) after suprathreshold transcranial magnetic stimulation from soleus (SOL), medial gastrocnemius (MG) and lateral gastrocnemius (LG) muscles during stretch-hold (STR) and fixed-end reference (REF) contractions.

	<b>SOL</b>	<b>MG</b>	<b>LG</b>
<b>MEPs REF [V]</b>	$1.30 \pm 0.78$	$2.54 \pm 2.67$	$1.19 \pm 0.46$
<b>MEPs STR [V]</b>	$1.37 \pm 0.72$	$2.70 \pm 2.97$	$1.14 \pm 0.50$
<b>SPs REF [ms]</b>	$115 \pm 31$	$112 \pm 22$	$118 \pm 29$
<b>SPs STR [ms]</b>	$116 \pm 31$	$115 \pm 23$	$123 \pm 34$

1

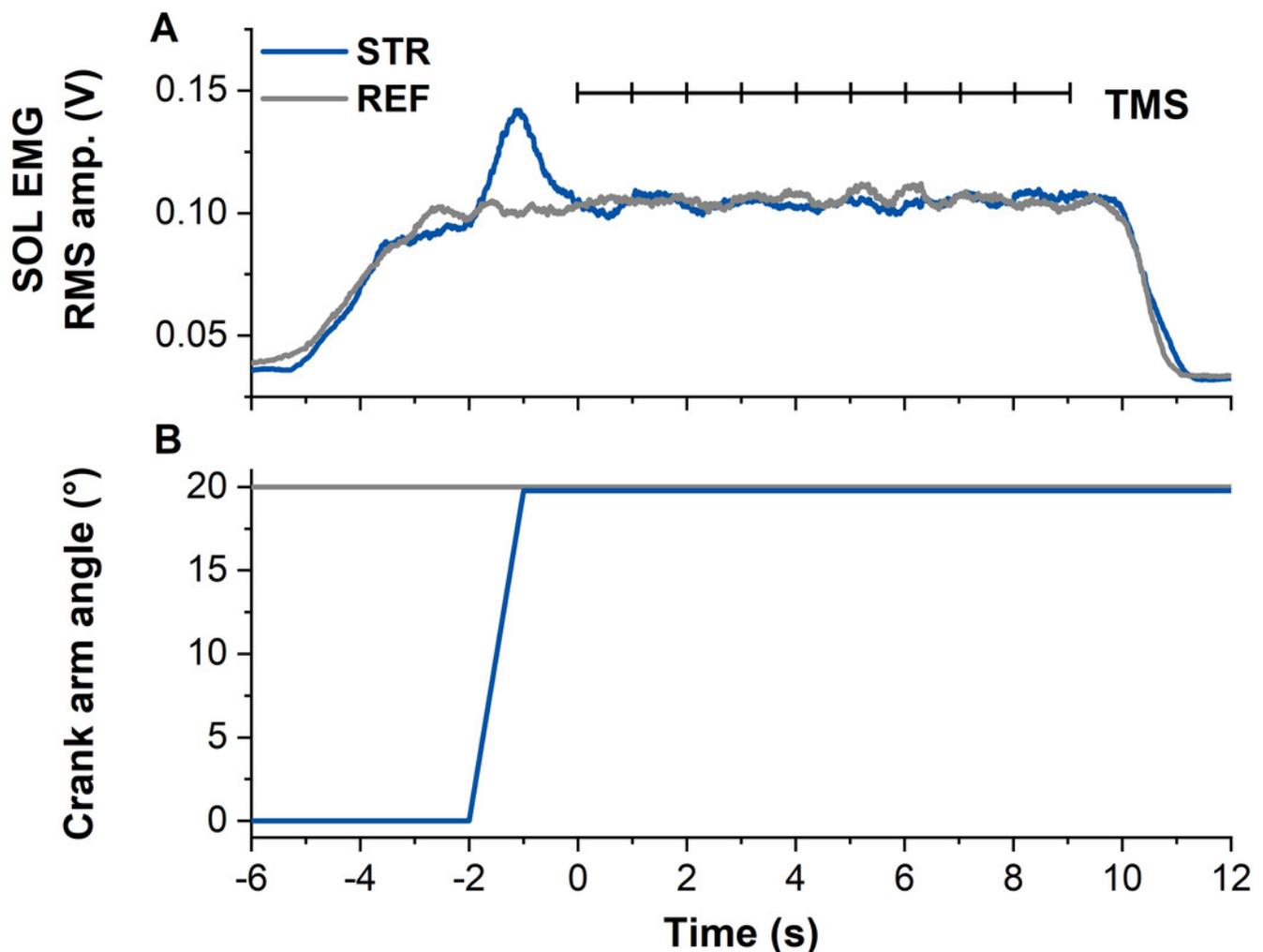
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## Figure 1

Example data from the stretch-hold (STR, blue) and fixed-end reference (REF, grey) contraction conditions.

A: The traces show soleus (SOL) EMG (moving 0.25-s root-mean-square (RMS) amplitude calculations). Transcranial magnetic stimulation (TMS, vertical black lines) was delivered at 1 Hz from 5 s after contraction onset (marked as time zero). In case the first stimulation was delivered before SOL EMG reached the target level, the stimulation was excluded from analysis. B: Traces show the corresponding crank arm angles.

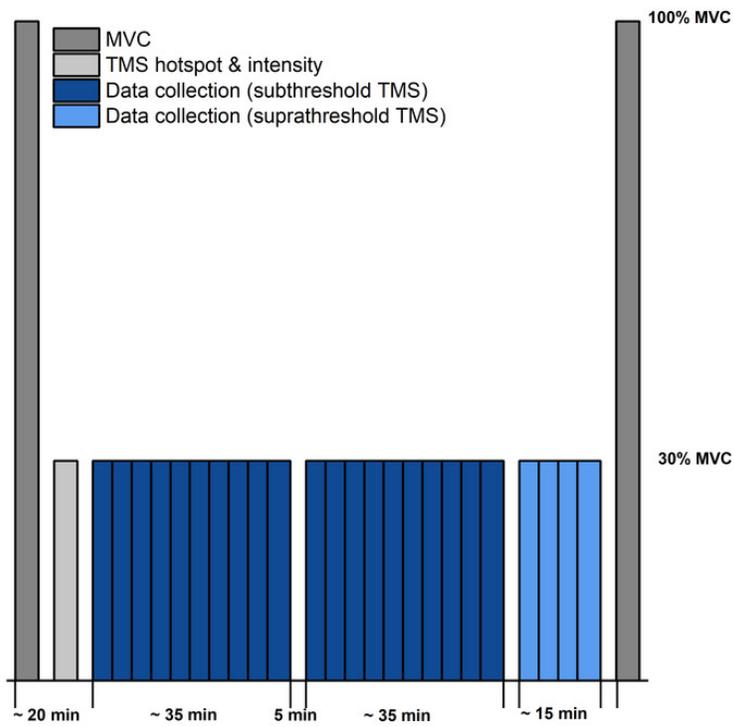


## Figure 2

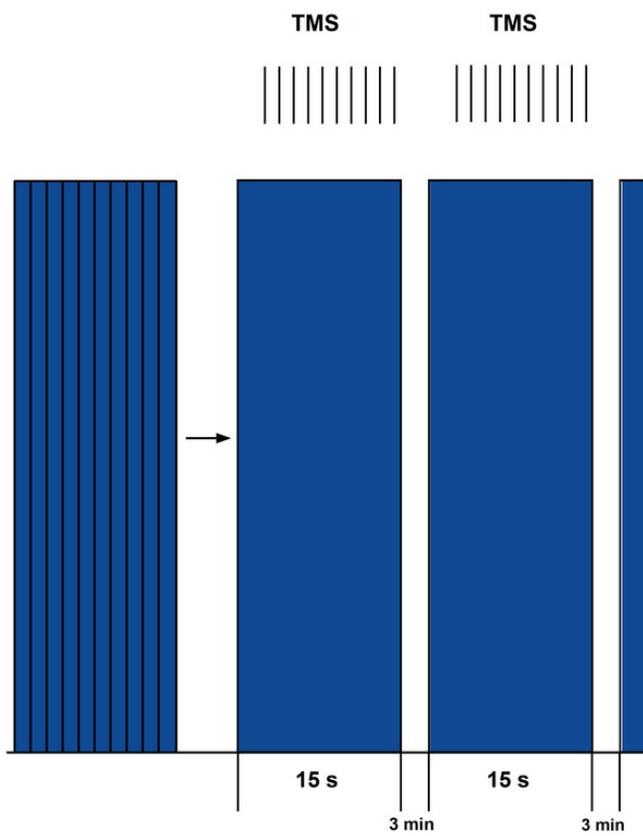
Schematic diagram of the experimental protocol.

A: The protocol started and ended with maximal voluntary contractions (MVC, dark grey). Transcranial magnetic stimulation (TMS) hotspot and sub-/suprathreshold intensities (light grey) were then determined before data collection. Twenty contractions with subthreshold TMS (dark blue) and 4 contractions with suprathreshold TMS (light blue) were separated into three sets, with 5 min rest between each set. B: Schematic description of contractions within sets (blue bars) and delivery of TMS (same procedure for sub- and suprathreshold TMS). Vertical black lines indicate the timing of TMS during the submaximal contractions. Each set during subthreshold TMS consisted of 10 contractions of 15 s duration, followed by a 3 min rest.

A



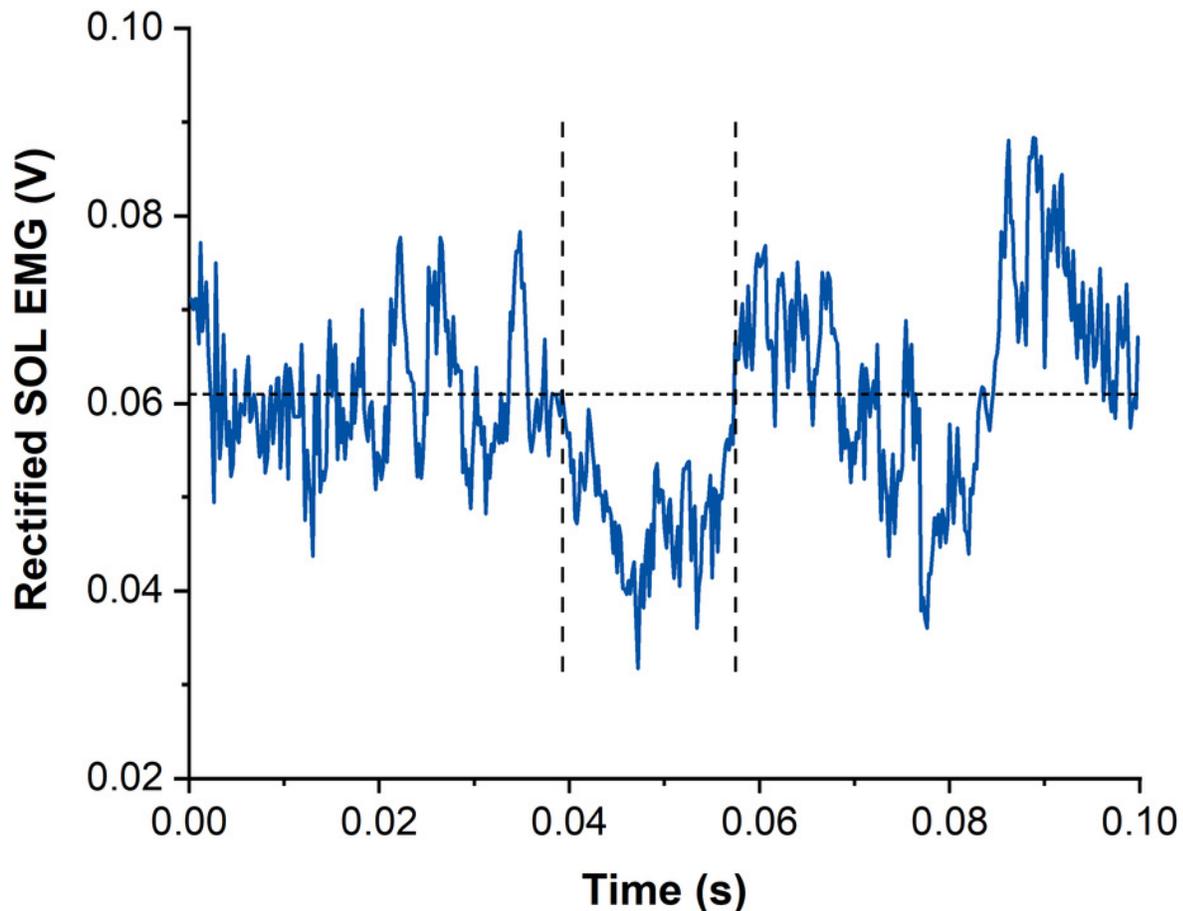
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## Figure 3

Example data of rectified and averaged soleus (SOL) EMG from contractions with subthreshold transcranial magnetic stimulation (TMS).

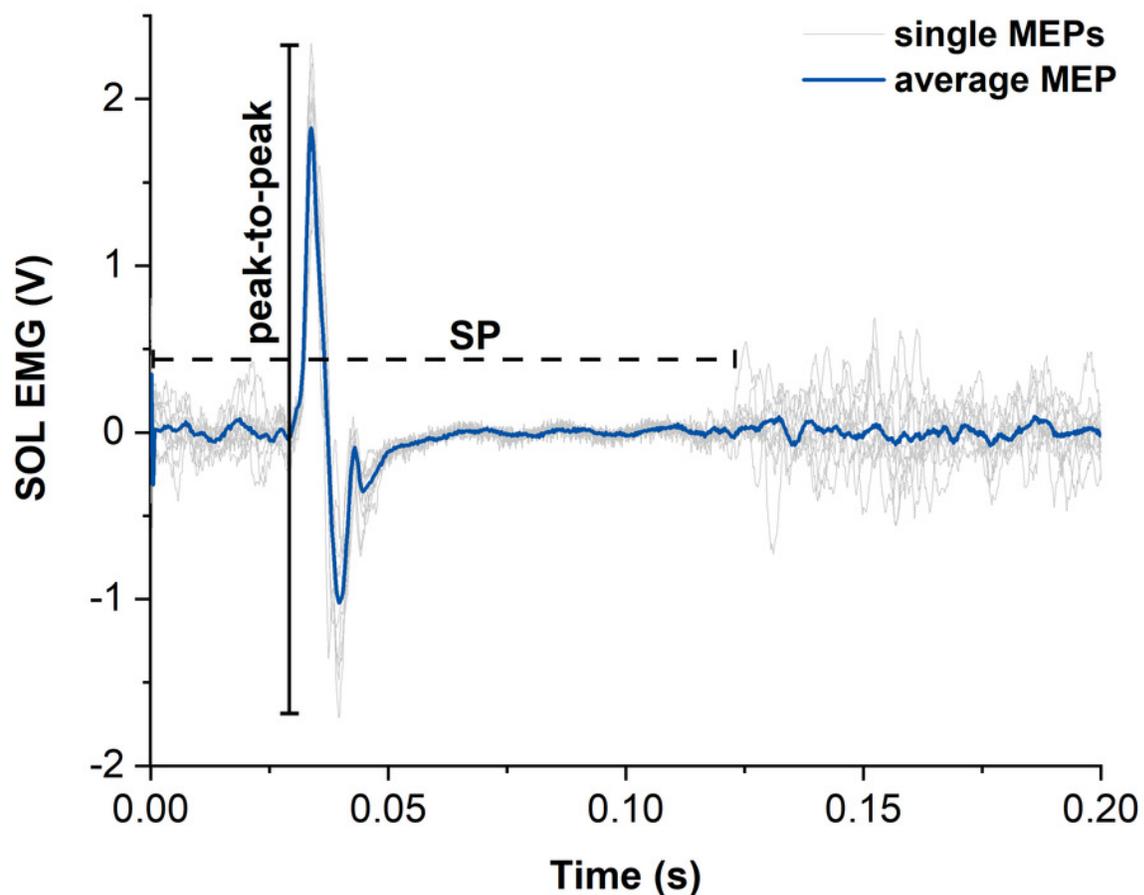
The horizontal dotted line represents the averaged background EMG amplitude calculated from 15-25 ms following stimulation. Vertical dashed lines indicate onset and offset of EMG amplitude suppression following TMS. Time zero indicates the time of stimulation.



## Figure 4

Representative example of motor evoked potentials (MEPs) and silent periods (SPs) from raw soleus (SOL) EMG signals elicited by suprathreshold transcranial magnetic stimulation (TMS).

The light grey traces show the single MEPs and the dark blue trace shows the average of all SOL MEPs from one participant. The horizontal dashed black line indicates the duration of the silent period (SP) and the vertical black line indicates the peak-to-peak amplitude of the largest single MEP. Time zero indicates the time of stimulation.



## Figure 5

Residual force enhancement (rFE), motor evoked potentials (MEPs), and twitch torques.

A: Residual force enhancement during stretch-hold (STR) contractions normalized to the time-matched torque during fixed-end reference (REF) contractions. The open circles and error bars represent the means and 95% confident intervals for the contractions with subthreshold transcranial magnetic stimulation (TMS) (left) and suprathreshold TMS (right), respectively. The grey dots represent the individual data points. B: Normalised MEP amplitude differences between STR and REF. The open circles and error bars represent the means and the 95% confident intervals and the grey dots represent the individual data points for soleus (SOL), medial gastrocnemius (MG) and lateral gastrocnemius (LG) muscles, respectively. C: Superimposed twitch torques after suprathreshold TMS. The open circles and error bars represent the means and the 95% confident intervals and the grey dots represent the individual data points for REF (left) and STR (right).

