

In vitro biomechanical evaluation of internal fixation techniques on the canine lumbosacral junction

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Few biomechanical studies have evaluated the effect of internal stabilization techniques after decompressive surgery on the stability of the canine lumbosacral junction. The purpose of this canine cadaver study is to evaluate the stability of the canine lumbosacral (LS) spine in flexion and extension following laminectomy and discectomy and then stabilization with each of the three techniques: pins and polymethylmethacrylate (P/PMMA), two dorsal locking plates (SOP) or bilateral transarticular facet screws (FACET). Using a cantilever biomechanical system, bending moments were applied to the LS and range of motion (ROM) was recorded via a rotational potentiometer. With 3Nm, the ROM (n=4 in each group) for P/PMMA, SOP and FACET were $1.92 \pm 0.96^\circ$, $2.56 \pm 0.55^\circ$ and $3.18 \pm 1.14^\circ$, respectively. With moments up to 35Nm, the P/PMMA specimens appeared stable. Sacroiliac motion in the SOP and FACET groups invalidated further comparisons. Each of the stabilization techniques (P/PMMA, SOP, and FACET) significantly decreased the range of motion in flexion and extension for low bending moments.

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3 **junction.**

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45 **Abstract**

46 Few biomechanical studies have evaluated the effect of internal stabilization techniques
47 after decompressive surgery on the stability of the canine lumbosacral junction. The purpose of
48 this canine cadaver study is to evaluate the stability of the canine lumbosacral (LS) spine in
49 flexion and extension following laminectomy and discectomy and then stabilization with each of
50 the three techniques: pins and polymethylmethacrylate (P/PMMA), two dorsal locking plates
51 (SOP) or bilateral transarticular facet screws (FACET).

52 Using a cantilever biomechanical system, bending moments were applied to the LS and
53 range of motion (ROM) was recorded via a rotational potentiometer. With 3Nm, the ROM (n=4
54 in each group) for P/PMMA, SOP and FACET were $1.92\pm 0.96^\circ$, $2.56\pm 0.55^\circ$ and $3.18\pm 1.14^\circ$,
55 respectively. With moments up to 35Nm, the P/PMMA specimens appeared stable. Sacroiliac
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60 *Keywords:* Lumbosacral; Biomechanics; Dog; PMMA; SOP; Transarticular Facet Screws

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68 **Introduction**

69 Degenerative Lumbosacral Stenosis (DLS) is a common cause of caudal lumbar pain,
70 difficulty in sitting and difficulty rising in middle aged large breed dogs (Meij and Bergknut,
71 2010). DLS is commonly associated with Hansen type II disc degeneration, ligamentous
72 hypertrophy, articular facet and joint capsule hypertrophy, spondylosis deformans, subluxation
73 of the sacrum and lumbosacral instability. It is thought that increased motion at the lumbosacral
74 junction is the most important contributor to the degenerative changes and progression of clinical
75 signs in dogs (Meij and Bergknut, 2010).

76 Surgical management is recommended for patients with severe or recurrent pain that is
77 not responsive to medical management or when neurologic deficits are present (Johnston and
78 Tobias 2012a). Common surgical options for DLS include dorsal laminectomy alone or in
79 combination with a partial discectomy, dorsal laminectomy combined with fixation and fusion or
80 lateral foraminotomy (Meij et al., 2007, Hankin et al., 2012, Smolders et al., 2012bc). Two
81 previous biomechanical studies have shown that a dorsal laminectomy with partial discectomy
82 increases lumbosacral movement, which may lead to instability (Smolder et al., 2012b, Early et
83 al., 2013). Some surgeons feel that dorsal stabilization is indicated to provide stability to the LS
84 junction. If instability is present, then dorsal stabilization will limit the range of motion. Even in
85 the absence of significant instability, if there is nerve impingement secondary to proliferation of
86 tissue around the LS junction, rigid fixation may reduce the intensity of the fibrous response,
87 thus relieving the pressure on the spinal nerves. An optimal configuration or system of fixation
88 has yet to be determined. Two of the most widely used and clinically accepted fixation
89 techniques are 1) positive profile threaded pins and polymethylmethacrylate (Weh and Kraus,
90 2007) and 2) bilateral transarticular facet screw stabilization (Hankin et al., 2012). The SOP™

91 locking plate system may also be suitable, enabling screws to be directed into the limited bone
92 available (Johnston and Tobias. 2012b).

93 Currently there remains inadequate case-based evidence to support the use of surgical
94 intervention over conservative management for DLS (Jeffery et al, 2014). There seems to be
95 major controversy with regard to the type of surgery that may be chosen as well. Most
96 veterinarians would support surgical intervention in dogs with severe pain and fecal or urinary
97 incontinence. Of the common surgical options listed above, none is without limitations. Dorsal
98 laminectomy and discectomy may not alleviate compression of the L7 nerve in the foramen.
99 Foraminotomy alone does not allow for removal of protruding disc and ligamentous
100 compression within the spinal canal. Combining a dorsal laminectomy and foraminotomy may
101 increase the risk of articular facet fracture. Stabilization of the LS junction is performed when
102 the goal is to reduce the dynamic components of nerve compression within the vertebral canal,
103 or when it is the surgeon's opinion that the LS junction is unstable. Potential problems with the
104 LS stabilization techniques include poor implant placement (i.e. implants within the vertebral
105 canal) and inability to assure long term rigid fixation and bony fusion (Smolders et al., 2012c).

106 The purpose of this canine cadaver study was to evaluate the range of flexion and
107 extension and load to failure of the canine lumbosacral spine following stabilization with pins
108 and polymethylmethacrylate (P/PMMA), two dorsal locking plates (SOP) and bilateral
109 transarticular facet screws (FACET), after a dorsal laminectomy and partial discectomy.

110 **Materials and Methods**

111 The caudal lumbar spine (L6-7), sacrum and pelvis were harvested from 12 euthanized
112 skeletally mature non-chondrodystrophic dogs with weights ranging from 23.6-36.7 kg (median
113 30.4 kg). Specimens were radiographed and no degenerative changes were noted. The pelvis

114 was fixed in a resin mold (Bondo, Bondo Corporation, Atlanta, GA), which was mounted to the
115 base of a testing machine (MTS, Canton, MA). An eyebolt screwed into the center of L6 was
116 attached to the actuator so that the spine segment could be flexed and extended. The applied
117 moment (Nm) was calculated by multiplying the applied load (N) by the distance from the LS
118 space to the actuator (m). Movement of L7 was monitored by a weighted rotational
119 potentiometer (P1411, Novotechnik, Southborough, MA) attached to the ventral aspect of the
120 vertebra. In a previously reported study, the specimens were conditioned at ± 1.5 Nm, at a rate of
121 two cycles per second and range of motion (ROM) were measured for ± 3 Nm of bending (Early
122 et al., 2013). An L7-S1 dorsal laminectomy and partial discectomy was performed and the ROM
123 measured. The ROM of the intact specimens was $32.8 \pm 6.4^\circ$ and, after laminectomy and
124 discectomy, this increased to $40.2 \pm 5.6^\circ$ (Early et al., 2013).

125 Following the ROM analysis, one of the three fixation techniques (P/PMMA, SOP and
126 FACET) was applied to each of the specimens. There were 4 specimens per group. Implant
127 entry points for the three fixation techniques are identified in Figure 1 and radiographs depicting
128 each technique are given in Figure 2. The P/PMMA construct consisted of six positive profile
129 4.0 mm (5/32") external fixation half-pins (Interface™, Imex Veterinary, Inc., Longview, TX).
130 Two pins were placed into the pedicle of L7, two pins into the sacrum and two pins into the
131 ilium. Pre-drilling for pins was not performed. PMMA was applied, incorporating all of the pins
132 (Fossum 1997). The PMMA was contoured and in close contact with the bone surface of L7
133 and sacrum. The PMMA was allowed to harden for a minimum of 1 hour before testing.

134 The SOP fixation consisted of two 5-hole 3.5mm locking plates (SOP™, Orthomed Ltd.,
135 West Yorkshire, UK) that were positioned parallel on either side dorsolaterally and secured to
136 the pedicle of L7 and sacrum with two 3.5 mm cortical screws (Depuy Synthes Vet, West

137 Chester, PA) in each plate. All of the screws for the SOP construct were placed in the most
138 cranial pearl (hole 1) skipping the second pearl and then placing the second screw in the third
139 pearl (hole 3).

140 The FACET fixation consisted of two 3.5mm cortical screws oriented from the dorsal
141 articular processes of L7, into the sacrum using a positional technique (Sharp and Wheeler.
142 2005).

143 After each fixation technique was applied, the specimen was preconditioned at ± 1.5 Nm
144 for 5 cycles, then loaded at ± 3 Nm for 5 cycles to measure ROM. Subsequently, the stabilized
145 specimens were subject to an incrementally increasing load, starting at ± 2.5 Nm and increasing
146 by 2.5 Nm after each set of 5 loading cycles, until testing was concluded. Testing was
147 concluded if: 1) motion of L7 was greater than 10° in flexion or extension, 2) implant failure or
148 bony fracture occurred; or 3) a bending moment of 35 Nm was applied (Smith et al. 2004).
149 After all ROM testing was complete, lateral and dorsoventral radiographs were made of all
150 specimens and the failure mechanism evaluated on these and on the specimens.

151 The ROM with ± 3.5 Nm applied moment was compared between the stabilized
152 specimens and the intact and decompressed data available from a previous study (Early et al,
153 2013). If differences were identified using ANOVA, individual comparisons were made using
154 the least squares means test, and an overall P value of 0.05 to determine significance (SAS
155 v9.1.3 Service pack 4, SAS Institute Inc., Cary, NC). Because of issues identified during the
156 incremental load to failure study, statistical comparison of load to failure data was not
157 performed.

158 **Results**

159 The ROM with $\pm 3.5\text{Nm}$ for the P/PMMA, SOP and FACET techniques were $1.92\pm 0.96^\circ$,
160 $2.56\pm 0.55^\circ$, and $3.18 \pm 1.14^\circ$ respectively, Figure 3. After each fixation technique was applied
161 the ROM of the stabilized specimens was significantly decreased ($p<0.001$) compared to ROM
162 after dorsal laminectomy and discectomy (mean of all specimens for all three groups = $40.2\pm 5.6^\circ$
163 (Early et al., 2013). One of the FACET specimens failed because of fracture around the screw
164 with 14.1 Nm applied while in extension. One of the SOP specimens failed by loosening of the
165 screws in L7 with 12.7 Nm applied while in extension. The other three specimens in each of the
166 FACET and SOP groups failed because L7 motion was greater than 10° , though most of that
167 motion originated at the SI joints. There was no failure of the fixation noted on gross inspection,
168 or on radiographs. In the P/PMMA group, testing was stopped at 35 Nm of bending for three
169 specimens, with no implant failure noted on gross inspection, or on radiographs. In the other
170 P/PMMA specimen, the eyebolt fractured through L6 when a 25 Nm moment was applied.

171 Discussion

172 This study demonstrates that the LS region had much less range of motion after
173 stabilization with each fixation technique, but, because the P/PMMA technique bridges the SI
174 joint, and the FACET and SOP techniques did not, the specimens moved very differently during
175 testing at higher bending moments. For this reason we felt that it was not appropriate to make
176 direct comparisons of failure using the mechanical data.

177 Visually and mechanically, the P/PMMA technique appeared to provide good stability.
178 Three of four specimens resisted the highest applied moment with no evidence of failure. As the
179 flexion and extension moment was increased on the FACET and SOP specimens, there was
180 increasing motion of the SI joint. As this allowed L7 to move relative to the pelvis, this motion

181 was included in the data. Movement of L7 relative to S1 could not be separated from the SI
182 motion.

183 Visually, no motion was observed in the SOP specimens, except in one, where one screw
184 loosened in L7. This suggests that, in this configuration and testing mode, the screw-bone
185 interface was the weaker element. This may be due to slightly incorrect placement of this
186 particular screw, or to the fact that there were only 2 screws in each vertebrae. There is a very
187 narrow region into which the screw is inserted in L7 to optimize its purchase, while not
188 damaging adjacent structures (Smolders et al., 2012c). The recently developed SOP™ Locking
189 Plate System combines the advantages of a fixed angle stabilization system, like the P/PMMA,
190 with lower bulk. The SOP™ plate can be contoured so that the locked screws are directed into
191 the limited available bone stock (Johnston and Tobias 2012b). When using the SOP™ locking
192 plate system in the lumbar and sacral vertebrae, the following guidelines have been
193 recommended recently - use SOP locking plates bilaterally, twist and contour the SOP caudally
194 to engage the iliac shaft, recommend 4 screws but a minimum of 3 screws in each vertebral
195 body, use the longest possible cortical screws to engage maximum amount of vertebral bone and
196 have the SOP plate as close to the bone as possible while avoiding damage to emerging nerve
197 roots (Orthomed product information brochure). The configuration used in this study was
198 selected before the above recommendations were available. The 2-screw configuration was
199 chosen to mimic the pedicle rod and screw stabilization technique commonly used in humans
200 and by some surgeons in dogs (Smolders et al., 2012c).

201 In the FACET specimens, slight motion was apparent between the facets. Fracture of the
202 facet because it is weakened by the screw, as occurred in one specimen, is a known potential
203 complication of this technique (Sharp & Wheeler, 2005, Hankin et al., 2012)

204 Previous in vitro cadaver studies have evaluated the biomechanical effects of
205 stabilization after concurrent dorsal laminectomy and partial discectomy on the lumbosacral
206 junction in the dog have yielded similar results (Meij et al., 2007, Smolders et al., 2012a). In the
207 Meij et al. 2007 study, a pedicle screw and rod fixation significantly stabilized the lumbosacral
208 spine by decreasing the ROM from $29.1 \pm 5.60^\circ$ to $11.7 \pm 3.30^\circ$. In the Smolders et al. 2012a
209 study, a nucleus pulposus prosthesis effectively decreased the ROM of the lumbosacral spine by
210 8.8%. These studies evaluated the lumbosacral spine segments using 4-point bending. In this
211 study, a cantilever system was used as it was easier to instrument and load the spinal segment.
212 While the applied moment varies over the length of the specimen in cantilever bending, the
213 moment applied to the LS articulation is easily calculated.

214 This study was intended to evaluate clinically accepted techniques for stabilization of the
215 LS junction. Several distinctions should be noted as these potentially alter and give significant
216 advantages to the various biomechanics of each construct. The P/PMMA fixation has the
217 potential advantage of six screws and points of fixation, while the SOP and FACET have four
218 and two points of fixation respectively. The P/PMMA constructs used 4.0mm positive profile
219 pins with a 3.2mm shaft, while the SOP and FACET constructs used 3.5 mm cortical screws,
220 with a 2.4 mm shaft. The P/PMMA construct was thicker, bulkier and in more intimate contact
221 with the L7 and sacral vertebrae providing a buttress stabilization, which likely contributed to
222 the more stable appearance of this group.

223 An interesting finding of this study was that the motion at the sacroiliac (SI) joint was not
224 constant between stabilization techniques. The P/PMMA technique stabilized the SI joint such
225 that no motion was appreciated at that articulation. The SI joint was not stabilized in the SOP
226 and FACET specimens. It is unknown if preserving SI motion may have a clinical advantage. In

227 the recommendations for SOP placement described above, bridging the SI joint is advised, so SI
228 motion would be lost if this was performed. Anchoring implants to the ilium is suggested
229 because of the historically poor screw purchase achieved in the sacrum alone.

230 Cantilever bending does typically result in a higher bending moment at the point of
231 fixation of the specimen to the rigid stand compared to at the tip where the load is applied. In
232 contrast, an even bending moment is applied with a 4-point fixture. The cantilever model was
233 selected because it appeared to replicate the loads that would be applied to the LS region when
234 the hind limbs were in stance phase and the load of the front half of the body was acting on the
235 lumbar spine. Because the ilial shafts were potted right up to the sacrum, the highest bending
236 moments would have been present on the SI joints and the LS joint. Of course, all models of
237 spine motion are gross simplifications since they disregard the very important contribution of the
238 active stabilizers of the system.

239 The primary limitation of this study was that, because SI motion was much greater than
240 expected, we were not able to compare the failure properties of the three different stabilization
241 techniques. Another limitation of the study design was that the ability of the fixation methods to
242 resist lateral bending and axial rotational forces was not evaluated.

243 **Conclusion**

244 This cadaver study demonstrated that stabilization of the lumbosacral junction by all
245 three of the applied fixation techniques leads to decreased motion in flexion and extension. It is
246 unknown whether the stabilization techniques used in combination with the dorsal laminectomy
247 and partial discectomy procedures will provide sufficient stability for healing in clinical cases.

248 **Acknowledgements**

249 We thank Kristal Wilson for her assistance in acquiring data in the bioengineering
250 laboratory and Robert Thatcher for his assistance with the figures.

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Figure 1(on next page)

Implants points of entry into L7, Sacrum and Ilium.

Dorsal view of the skeletal structures of the canine lumbosacral junction, showing the points of entry of the implants into L7, Sacrum and Ilium. The external fixation pins (for the P/PMMA) entry points are denoted with open dark gray circles with cross marks in the middle. The SOP locking plate entry points are denoted by solid black circles and the bilateral transarticular facet screws entry points and directions are denoted by black arrows.



Figure 2(on next page)

Postoperative radiographs of the three stabilization techniques. `

Postoperative radiographs, lateral and dorsoventral, of the three stabilization techniques. (A) External fixation pins and PMAA, (B) SOP™ Locking Plate System and (C) Bilateral transarticular facet screws.



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Figure 3(on next page)

Typical load-deflection curve in a canine cadaver lumbosacral spine during cyclic loading of spines after dorsal laminectomy and partial discectomy and each stabilization technique.

Typical load-deflection curve in a canine cadaver lumbosacral spine during cyclic loading (flexion and extension) of spines after dorsal laminectomy and partial discectomy (DL) and each stabilization technique (SOP - black solid, FACET - light grey solid and P/PMMA - dark grey dashed). Range of motion (ROM) was the L7 angulation change between flexion and extension with 3 Nm of bending moment applied.

