

Real-time bioacoustics monitoring and automated species identification.

Traditionally, animal species diversity and abundance is assessed using a variety of methods that are generally costly, limited in space and time, and most importantly, they rarely include a permanent record. Given the urgency of climate change and the loss of habitat, it is vital that we use new technologies to improve and expand global biodiversity monitoring to thousands of sites around the world. In this article, we describe the acoustical component of the Automated Remote Biodiversity Monitoring Network (ARBIMON), a novel combination of hardware and software for automating data acquisition, data management, and species identification based on audio recordings. The major components of the cyberinfrastructure include: a solar powered remote monitoring station that sends 1-minute recordings every 10 minutes to a base station, which relays the recordings in real-time to the project server, where the recordings are processed and uploaded to the project website (arbimon.net). Along with a module for viewing, listening, and annotating recordings, the website includes a species identification interface to help users create machine learning algorithms to automate species identification. To demonstrate the system we present data on the vocal activity patterns of birds, frogs, insects, and mammals from Puerto Rico and Costa Rica.

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44 INTRODUCTION

45 Ecologists, conservation biologists, and park and resource managers are expected to
46 make decisions to mitigate or manage the threats of climate change and the high rates of species
47 loss. Unfortunately, they rarely have the information needed to make informed decisions
48 because our understanding of most biological systems is based on very limited spatial and
49 temporal coverage. In most biomes, data collection, particularly of the fauna, is concentrated in
50 a few sites, and this highly aggregated distribution of information, limits our ability to
51 understand large-scale ecological processes and to properly manage fauna in large areas (Gentry,
52 1990; Terborgh et al. 1990; Condit, 1995; Porter et al., 2005; Underwood et al., 2005; Porter et
53 al., 2009). Furthermore, long-term information is needed to understand the implications of land
54 and climate change on biological systems (Porter et al., 2005). From both a conceptual and
55 management perspective there is an urgent challenge to increase biological data collection over
56 large areas and through time.

57 What is needed are long-term population and distribution data for thousands of species
58 across their range. For some economically important species (e.g. salmon) we have long-term
59 data (Niemela et al., 2000), but for the majority of species the data is limited to a few years and a
60 few populations. Other areas of science, such as meteorology and land change science have
61 taken advantage of new technologies, such as inexpensive sensors, wireless communication, and
62 satellite images to expand their data sets to the global scale (Porter et al., 2009). Given the
63 urgency of the biodiversity crisis, it is essential that we take advantage of all available tools to
64 improve biodiversity monitoring to thousands of sites around the world.

65 Traditionally, biodiversity is assessed using a variety of methods that are generally costly,
66 limited in space and time (e.g., Parker, 1991; Sauer et al., 1994; Sueur et al., 2008), and most
67 importantly, they rarely include a permanent record. Furthermore, most fauna monitoring
68 protocols require the presence of experts in the field because data are often acquired through
69 indirect cues (e.g. animal vocalizations). This creates various problems. First, in terms of
70 acoustic identification, there are few experts that can confidently identify animals based on
71 vocalization, yet there are many studies that could benefit from this information. Second,
72 experts vary in their abilities to correctly identify species, and this leads to observer bias
73 (Fitzpatrick et al., 2009). Additionally, these protocols often collect data over a very limited
74 spatial and temporal scale, and these constraints reduce the researcher's ability to understand the
75 dynamic patterns of animal populations. Furthermore, most traditional sampling methodologies
76 do not include a permanent record and, thus, there is no way to validate the data.

77 In contrast, automated digital recording systems can monitor animal populations 24 hours
78 a day, every day of the year, in stations across a variety of habitats simultaneously, and all
79 recordings can be permanently stored (Acevedo and Villanueva-Rivera, 2006; Brandes, 2008;
80 Lammers et al., 2008; Sueur et al., 2008; Acevedo et al., 2009; Hoeke et al., 2009; Tricas and
81 Boyle, 2009). This type of monitoring can be effective because in most ecosystems a large
82 proportion of the fauna emits sounds for a variety of reasons including inter and intraspecific
83 communication, orientation (Peter and Slabbekoorn, 2004), and detection and localization of
84 prey and predators (Richardson et al., 1995), but most importantly, these sounds are species
85 specific.

86 Automated data collection systems can collect an overwhelming amount of data, creating
87 problems of data management and analysis (Villanueva-Rivera and Pijanowski, 2012). To help
88 solve these problems, researchers have developed algorithms to automate species identification
89 of vocalizations of bats (Herr et al., 1997; Walters et al., 2012; Parsons and Jones, 2000), whales

90 (Murray et al., 1998; Brandes, 2008; Marques et al., 2012; Mellinger and Clark, 2000; Moore et
91 al. 2006), dolphins (Oswald et al., 2003), insects (Chesmore, 2004; Chesmore and Ohya, 2004),
92 and birds and amphibians (Anderson et al., 1996; Kogan and Margoliash, 1998; Acevedo and
93 Villanueva-Rivera, 2006; Hilje and Aide, 2012; Ospina et al., 2013). A limitation with this
94 approach is that most users do not have the programming or math skills to develop these
95 algorithms. Furthermore, most projects have only produced algorithms for one or a few target
96 species.

97 In this manuscript, we describe the acoustical component of the Automated Remote
98 Biodiversity Monitoring Network (ARBIMON), a novel combination of hardware and software
99 (cyberinfrastructure) for automating data acquisition, data management, and identification of
100 multiple species of amphibians, birds, insects, and mammals. The main objectives of the
101 manuscript are to demonstrate: 1) how detailed, long-term acoustical data can be collected and
102 managed, 2) how users can create species-specific identification algorithms with no machine
103 learning experience, and 3) how the information created by the system can be used to better
104 understand the activity patterns and long-term population trends of the fauna. To demonstrate
105 this system we present data on the activity patterns of nine species (4-amphibian, 2-birds,
106 1-mammal, and 2-insects) from an herbaceous wetland in Puerto Rico and a lowland tropical
107 forest in La Selva Biological Station in Costa Rica.

108 **METHODS**

109 **Data Acquisition**

110 The cyberinfrastructure for collecting and storing the audio recordings includes: 1) the
111 acoustic permanent station, 2) the field base station, and 3) the ARBIMON server (Fig. 1).
112 The permanent monitoring station includes an iPod Touch (2G) with a pre-amplifier, which is
113 powered with a 50W solar panel, voltage converter, a router, and a 12 V car battery (Fig. 1). A
114 microphone with a frequency response range from 20 Hz to 20 kHz is attached to the iPod via
115 the pre-amplifier. The battery, pre-amplifier, voltage converter, router, and iPod are housed in a
116 water/shock proof case. The pre-amplifier has three gain settings. The gain was set at the
117 intermediate level. Informal experiments suggest that this recording systems will detect the
118 common coqui (*Eleutherodactylus coqui*) in a forest habitat up to approximately 50 m,
119 suggesting that for this species the sampling area would be approximately 1 ha. An application
120 in the iPod controls the duration of the recording and the time between recordings. Presently, it
121 is programmed to record 1 minute of audio every 10 minutes for a total of 144 1-minute
122 recordings per day. The recording schedule can be easily modified depending on the objectives
123 of each project. The application generates a filename for each recording, instructs the software to
124 make the recording, and sends the recording using Secure Copy (SCP) to a MacMini computer at
125 the base station. These files are forwarded by wireless communication from the iPod to a router
126 that is connected to a directional antenna (Avalan Wireless 900Mhz Radio Ethernet extender),
127 which forwards the file to the receiving antenna that is connected to the base station computer.
128 Our experience shows that this radio/antenna system can maintain a strong connection at a
129 distance of 2 km through vegetation and up to 40 km if there is line-of-site between the antennas.

130 The main functions of the base station are to provide internet access, store all data files
131 locally on a 1Tb external hard drive, compress the recordings to reduce the file size, and to
132 forward these files to the project server at the University of Puerto Rico (Fig. 1). These functions
133 are activated every time a recording is received via a folder action and an Applescript. The script
134 converts the recording from stereo to mono, and compresses it using flac format (an open source
135

136 alternative for lossless compression and decompression of audio files,
137 <http://flac.sourceforge.net/>), stores the file locally, and sends a copy to the project server. The
138 project server, an Apple Xserve (2.8 GHz Quad-Core Intel Xeon, 4-12 GB 800 MHz DDR2
139 FB-DIMM) running MacOS X 10.5.4 Server, Apache 2.2, Php 5.2.5 and MySQL5.0.45, is used
140 for data storage, data backup, data management, analysis, and web hosting. The server also
141 includes a Promise VTrak E610f RAID Subsystem with 12TB configured as a RAID6 for a total
142 of 9TB of available space.

143 In addition, acoustic files collected using portable recorders (e.g. Passive Acoustic
144 Monitoring (PAM) equipment) can be uploaded to the database. These files are managed and
145 analyzed in the same way as the recordings from the acoustic permanent stations.
146

147 **Database and data management**

148 A normalized open source database schema using the MySQL database system is the
149 cornerstone of our web application. The database is general enough so that it can be used for
150 any acoustic project, allowing researchers to work with the data of their specific projects, but
151 when appropriate it allows the merger and sharing of data among projects.

152 The centerpieces of the design are the sensors that acquire the data and the methods used
153 to process the data, allowing our system to handle a variety of sensors, use different
154 configurations of these sensors, and to create an efficient way to relate the data with the type of
155 sensor and configuration. Additionally, this database architecture provides easy access to the
156 data at different points in the processing path. This was accomplished by handling the data as
157 both input and output, thus each data entity is output in one instance and input in the other. Up
158 to now the principal sensors have been the recording stations described above and the core data
159 of the database are the audio recordings (Fig. 1) with their associated attributes: recording site
160 (id, name, longitude, latitude and elevation) and study area (id, name, organization in charge
161 and time zone).

162 **Database management** – Although anyone can view and listen to the recordings on the
163 project website, only approved users can analyze or annotate recordings. To manage projects
164 and users within projects we have developed an administrative interface, which has three
165 sections: administration, project creation and management, and global security. The
166 administration component maintains the databases of all projects, keeps a log of all users'
167 activity, and documents any security breach or system failure. The project creation and
168 management component allows a new user to 1) create a project, 2) specify site names, location,
169 and time zone, and 3) assign users with different privilege levels of to the project. The global
170 security component manages users and their privileges.
171

172 **Data processing**

173 When the audio files arrive to the project server, they are archived, and then sent to a program
174 that extracts the raw data from the wav format to create a spectrogram of the recording. This
175 spectrogram is created using a short-time Fourier transform (STFT) using 512 samples and a
176 Hann window overlapping 256 samples. For one-minute recordings with a sample rate of 44,100
177 samples per second each cell of the matrix represents 86 Hz by 0.005 s. This matrix is used to
178 generate the spectrogram image of the recording and is the input for another program that
179 demarks areas of high energy within the recording as regions of interest (ROIs). In addition, an
180 mp3 file is generated using LAME (<http://lame.sourceforge.net/>) a high quality MPEG Audio
181 Layer III (MP3) encoder licensed under the Lesser General Public License (LGPL). The smaller

182 size of mp3 files makes them more appropriate for the web application, but the quality of the
183 spectrogram or ROIs are not affected because they were generated using the original wav files.
184 The algorithm to create the regions of interest (ROIs) starts by analyzing the frequency-time
185 matrix to determine the level of background noise within each frequency band. This information
186 is used to define thresholds of audio intensity that the input signals in the recording must surpass
187 to be considered as an acoustic event. For each frequency band, we determine the mean intensity
188 value and keep only the samples that are greater than 10% above the mean. This process greatly
189 reduces the data, making it suitable for storing as a compressed sparse matrix (CSR). We analyze
190 the CSR containing the acoustic events using a depth-first search algorithm to create
191 neighborhoods of pixels into a single region of interest (ROI). Once, the sample is used in a ROI
192 they are removed from the CSR and the algorithm selects another event until all samples that
193 were selected as an acoustic event participates in a ROI. The time and frequency variables that
194 describe the bounding box of each ROI (minimum and maximum frequency, duration, maximum
195 intensity and bandwidth) are the variables that are later used to create the automated species
196 identification algorithms.

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198 **User interface for automating species identification**

199 To automate species detection, we developed an application that uses Hidden Markov Models
200 (HMMs). The application was designed so that the users can develop their own models using
201 tools to view and listen to their recordings and to create, test, and validate species-specific
202 identification models. The four major components that make up this interface included: 1)
203 visualizer, 2) species validation, 3) model builder, and 4) model application.

204 **Visualizer** - This module is used for viewing, listening, and annotating recordings. The
205 visualizer was developed in OpenLaszlo (a flash framework) so that it would be compatibility
206 across browsers. The interface can accept recordings of any length and from most recording
207 devices. The visualizer includes tools/features (e.g. zoom, filters) to facilitate viewing, listening,
208 and data analysis.

209 **Species validation** – This tool allows the user to specify which species/vocalization is
210 present or absent in each recording (Fig. 2). Users need to have a validation data set to verify the
211 accuracy and precision of each model. In addition, the user can determine if the particular
212 vocalization is correctly marked by the automated ROI generator.

213 **Model builder** – This component has four sub-components.

- 214 a. **Training data** – The first step in developing a species-specific model is to provide training
215 data for the model (Fig. 2). The user provides the training data by identifying examples of
216 the vocalization. Each model is based on a specific vocalization of a species. The user
217 selects a series of ROIs from the recording that reflect the desired vocalization model. For
218 example, two chirps followed by a shrill. This process is repeated to provide the program
219 with additional training examples. This information is saved in the database and is later used
220 for the optimization of the model using the Baum-Welch algorithm (Baum et al., 1970).
- 221 b. **Model creation** – We describe the sequence of a song as a Hidden Markov Model (HMM).
222 The model is expressed as $\lambda=(A, B, \pi)$ where A is a probability matrix for the transitions
223 between states, B is a probability matrix for the emissions given the state and π is a vector of
224 the probabilities of each state in the sequence. These probabilities are then optimized based
225 on the observations in the training set using the Baum-Welch algorithm. The application
226 requires the user to define the number and types of tones/notes in the species vocalization
227 (Fig. 2). Then, using the training data acquired by the users, the program calculates the

228 initial probabilities for the transition and emission matrices. The result of the Baum-Welch
 229 algorithm are the three optimized matrices A' , B' , π' that are then used to calculate the
 230 probability that a given observation was generated by the model λ .

- 231 c. Applying model – The initial model can be applied to any number of recordings (e.g. the
 232 default is 500 random recordings) in the database. The web application allows the user to
 233 visualize the results of the initial model, select correct responses, incorporate the correct
 234 responses into the training data to improve the model, and then reanalyze the data if
 235 necessary. These tools and the iterative process quickly allow the user to build an accurate
 236 species identification model. Once the user is satisfied with the model, it can then be tested
 237 against the validation data.
- 238 d. Validation – In this step, the system applies the model only to the recordings that were
 239 validated for the presence/absence of the species/vocalization (Fig. 2). Next, the user is
 240 provided with an error matrix and statistics on the accuracy and precision of the model.
 241 Based on these statistics the user can modify the model by varying the range of values (e.g.
 242 minimum frequency, duration) used in determining which ROIs are used in the model. In
 243 addition, in this component the user can review the results. For example, the user can inspect
 244 recordings with false positives to determine how to improve the model.

245 The error or confusion matrix shows the number of true positives
 246 (species/vocalization determined as present by the user and detected by algorithm), true
 247 negative (species/vocalization determined as absent by the user and not detected by the
 248 algorithm), false positives (species/vocalization determined as absent by the user, but
 249 detected by the algorithm) and false negatives (species/vocalization determined as present by
 250 the user, but was not detected by the algorithm). In addition, the output includes estimates of
 251 precision and accuracy, which are calculated as:

252 1) Precision = true positives / (true positives + false positives)

253 2) Accuracy = (true positives + true negatives) / total

254 **Model application** - In this component, the user can apply the model to their complete
 255 data set (Fig. 2). In our case, we have tested the system with more than five years of 1-minute
 256 recordings ($n = 173,526$) from our original permanent recording station site in Sabana Seca,
 257 Puerto Rico, and 19,043 recordings from La Selva Biological Station in Costa Rica. The system
 258 took less than two hours to run the three models for Sabana Seca through all of the recordings.
 259 The results from this analysis can be exported in cvs format for further analyses. In addition, the
 260 user can “publish” the model, making it available to other users and other projects.

261

262 Study site and study species

263 To demonstrate the use of the ARBIMON-acoustic application we created
 264 species-specific models for amphibians, birds, mammals, and insects based on recordings from a
 265 site in Puerto Rico and a site in Costa Rica. The species were selected to cover a range of taxa
 266 with different types of vocalizations. The site in Puerto Rico, Sabana Seca (SS), is a small (180
 267 ha) wetland near the Caribbean Primate Research Center (CPRC) in Toa Baja, Puerto Rico
 268 ($18^{\circ}25'56.01''N$ and $66^{\circ}11'45.62''W$). *Typha dominguensis* (cattail) is the dominant species in
 269 the wetland. This site is the only known locality of *Eleutherodactylus juanariveroi* (coqui
 270 llanero), an endangered frog species that was recently discovered (Rios-Lopez and Thomas,
 271 2007). The major motivation for establishing a permanent recording station in Sabana Seca was
 272 to improve the information on the calling activity and population dynamics of *E. juanariveroi*.
 273 The station was established in March 2008, and for this study we present the results of

274 species-specific identification models of the endemic frog species, *E. juanariveroi*, an exotic frog
275 species *Rana gryllo* (pig frog), and an unidentified insect (insect #1).

276 The other study site was La Selva Biological Station (LSBS) in Costa Rica (10°25`N,
277 84°01`W). This reserve encompasses approximately 1,510 ha of which 64% is primary tropical
278 forest, and contains a high diversity of flora and fauna (Clark and Gentry 1991). The objective
279 of this project was to conduct broad acoustic monitoring within mature forest for all species that
280 contribute to the acoustic community. For this site, we created species-specific identification
281 models for six species: *Tinamus major* (great tinamou), *Ramphastos swainsonii*
282 (chestnut-mandibled toucan), *Oophaga pumilio* (strawberry poison-dart frog), *Diasporus*
283 *diastema* (tink frog), *Alouatta palliata* (mantled howler monkey), and an unidentified insect
284 (insect #2).

285 In addition to the recordings from the two permanent stations described in this
286 manuscript, other recordings have been added to the ARBIMON database from other permanent
287 stations in Puerto Rico, Hawaii, and Arizona, and from portable recording systems in Puerto
288 Rico, Costa Rica, Argentina, and Brazil. As of May 7, 2013, the system has >1.3 million
289 1-minute recordings, which can be freely accessed through the project web page (arbimon.net).
290

291 RESULTS

292 Species identification models

293 To determine the accuracy and precision of the species identification models we
294 compared the decisions made by the expert (i.e. validation data set) with the decision made by
295 the models (Table 1). The *Oophaga pumilio* vocalization model had the highest accuracy (99%),
296 while the model for insect sp#2 had the lowest accuracy (79%). Similarly, the *Oophaga pumilio*
297 vocalization model had the highest precision (100%), but the *Alouatta palliata* model had the
298 lowest precision (76%) due to the high level of false positives. In general, most of the models
299 had relatively low levels of false positives (<5%), and higher levels of false negatives. For
300 example, the *Tinamous major* model reported only 1 presence when the vocalization was actually
301 absent (i.e. false positive), but 41 times the model reported the species was absent when it was
302 really present (i.e. false negative). These results suggest that these models are relatively
303 conservative; they rarely confused the species with another, but they do not always detect the
304 species when it is present as determined by an expert through visual and/or aural inspection.
305

306 There are two main causes for the false negatives. First, if the ROI generator does not
307 mark the vocalization, it will not be incorporated into the analysis. This usually happens when
308 the calling individual is far from the microphone and the vocalization was too faint to be detected
309 by the ROI generator, but the expert could observe or hear the species in spectrogram and
310 included the species as present in the validation data set. A second cause of false negatives
311 occurred because we restricted the range of some parameters to minimize false positives, which
312 could increase the number of false negatives.

313 There were many different causes of false positives. For example, thunderstorms created ROIs
314 that were similar to those of *Alouatta palliata*. Mechanical noise caused by wind was the main cause of
315 misidentifications of *Rana gryllo*. The main source of false positives of *Diaspora diastema* was
316 vocalizations of *Oophaga pumilio*. Nevertheless, this level of confusion in the identifications of *D.*
317 *diastema* did not significantly change the description of the daily vocal activity pattern in comparison
318 with previous studies (Graves, 1999; Hilje and Aide, 2012).
319

320 Species daily and annual activity patterns

321 These species-specific models were applied to all recordings from the two sites (SS –
322 173,526; LSBS – 19,043), and the detection data were used to determine the patterns of daily (SS
323 and LSBS) and annual (SS) activity.

324 In Sabana Seca, the vocalization patterns of the three species were concentrated during
325 the night, but the peak in activity of each species occurred at different times (Fig. 3 a-c). The
326 native species, *Eleutherodactylus juanariveroi* had two peaks of vocal activity, one at dawn
327 (5:00) and a higher and narrower peak at dusk (18:00). The exotic frog, *Rana grylio*, had a peak
328 of vocal activity at 4:00; while insect sp #1 had a peak of activity at 21:00. The two frog species
329 had low levels of activity during the day (6:00 – 18:00), and there were virtually no detections of
330 the insect during the day.

331 The same data were used to visualize the pattern of vocal activity between October 2008
332 and April 2013 (Fig. 3d-f). On average, the monthly detection frequencies of *E. juanariveroi*
333 were around 0.20, but between October 2008 and May 2012 there was a significant decline in
334 vocal activity (Ospina et al., 2013). Our data show that since May 2012 there has been a
335 dramatic increase in detection frequency, and in September 2012, *E. juanariveroi* was detected in
336 ~30% of the recordings. The activity pattern of *Rana grylio* was more seasonally predictable.
337 Each year there was a peak in vocal activity during the rainy season, between April and October,
338 when calling activity (i.e. detection frequency) increased from <0.02 during most of the year to
339 ~0.10 during the peaks. In 2009, the detection frequency increased to 0.30 during the peak.
340 These results reflect the biology of this aquatic species, which breeds during the wettest and
341 warmest time of the year (Thorson and Svihla, 1943). In contrast to the seasonal pattern of *R.*
342 *grylio*, the vocal activity of insect sp#1 was highly variable and much less frequent (Fig. 3f). In
343 some months the species was rarely detected, but the following month the detection rate could
344 increase by 2 to 4 fold, suggesting that the population of this species is highly dynamic.

345 In La Selva Biological Station, the variable pattern of daily vocal activity reflects the
346 diversity of taxa that were studied (Fig. 4). The great tinamou (*Tinamus major*) and the
347 chestnut-mandibled toucan (*Ramphastos swainsonii*) had peaks of activity at dawn and another
348 at dusk, as is expected for most bird species (Terborgh et al. 1990). The howler monkey
349 (*Alouatta palliata*) also had peaks of activity at dawn and dusk, but in contrast with the two bird
350 species, it had a larger proportion of its detections during the day. The two frog species had very
351 contrasting daily patterns of vocalization (Fig. 4 d-e). The peak in activity of *Diaspora diastema*
352 occurred during the night with a peak of activity at 3:00 and small peak at 18:00, but there was
353 also a low level of activity throughout the day. In contrast, the majority of vocal activity of
354 *Oophaga pumilio* occurred during the day, with a peak (>28% of detections) at 7 am. The model
355 for insect #2 showed virtually no activity during the day and a peak in vocalization around 22:00.

357 DISCUSSION

359 How detailed, long-term acoustical data can be collected and managed

360 Here we have demonstrated how frequent (sub hourly) data collection over long time
361 periods (years) can be carried out, and how the data can be managed, archived, and analyzed
362 virtually in real-time. By recording one minute of audio, every 10 minutes, we were able to
363 achieve fine temporal resolution, covering 24 hours a day, seven days of the week over a five
364 year period in Puerto Rico. This fine-scale and long-term temporal sampling, now needs to be
365 matched spatially with many sensors across the landscape.

366 The detailed and long-term temporal sampling of these sites could not have been
367 accomplished without automating data acquisition, processing, and management. The
368 automation of data collection also provided additional benefits. First, recordings can be
369 inspected visually and aurally in real-time. Recordings from the Sabana Seca station took less
370 than 1 minute to be sent from the field, to the base station, and on to the project server where it
371 was processed, stored, and incorporated into the project's open-access web site. This real-time
372 monitoring can help researchers and managers respond rapidly to important events, particularly
373 when a model that identifies a focal species has been incorporated into the data processing
374 scripts. Another benefit of the real time processing is that we can easily detect any malfunction
375 of the hardware or software by inspecting the recordings, and then respond quickly to limit data
376 loss. The Sabana Seca system collected recordings between 60-70% of the time. The major
377 causes of data loss were: 1) loss of power due to extended cloud cover or vegetation growing
378 over the solar panel, 2) loss of power at the base station, and 3) network problems at the base
379 station. Nevertheless, the real cause of missing data was a slow response by our staff to solve
380 these problems. To accelerate the response time, we have developed an application that
381 continuously collects information from each station and generates an alert in the form of an
382 email to the project owner when the station is malfunctioning.

383 Other benefits of automating data collection include: 1) reduced observer bias and 2)
384 each recording is a verifiable permanent record, equivalent to a museum specimen. Even if
385 observers could stay in the field 24 hr/d throughout the year, there would still be a problem of
386 observer bias (Cerqueira et al., in press). This is a major limitation especially when it is
387 necessary to sample many sites simultaneously or when data are collected over many years by
388 many different observers. The ability to detect and identify an animal vocalization correctly may
389 require years of experience. But, there can also be high levels of variation among "experts" due
390 to differences in the habitat being sampled, hearing ability, or biases toward certain species
391 (Sauer et al., 1994). Another benefit is that each recording is a permanent record, which allows
392 multiple users to review them, leading to more accurate identifications and consequently more
393 accurate estimates of population parameters. All recordings archived in ARBIMON
394 (arbimon.net) are open access, and thus it is the equivalent of an acoustic museum, presently
395 with >1.3 million 1-minute recordings.

396 Our approach is very different in comparison with most other collections of animal
397 vocalizations. For example, the recordings from the Macaulay Library of the Cornell Lab of
398 Ornithology, Xeno-canto, and the Internet Bird Collection are important collections of animal
399 vocalizations and photographs, but their focus is species specific. Furthermore, many species are
400 represented by one or a few recordings. In contrast, our approach is to record the environment
401 (i.e. soundscape), frequently and over the long-term. This allows multiple users to take
402 advantage of the recordings. For example, while the initial objective of a project may be to study
403 a specific bird species, the vocalizations of many other species (e.g. insects, frogs, birds and
404 mammals) are likely to be present. In addition, a soundscape index, an integrated measure of the
405 acoustic environment, can be calculated and measured across time to estimate changes in
406 biodiversity or other factors affecting the acoustic environment (Sueur et al., 2008; Pijanowski et
407 al., 2011). Moreover, given that all recordings will be permanently archived, future users, with
408 new tools and questions will be able to reanalyze these recordings in the future.

409 Although there are many benefits of a permanent station, the user must consider the costs
410 and other limitations. The initial cost of establishing a permanent recording stations will vary
411 depending on the site and logistics, and could range from approximately US\$ 10,000 to \$20,000.

412 Another important costs is the processing and long-term storage of the audio files. We have
413 estimated the cost at US\$0.15 per 1-minute recording. Other limitations associated with any
414 monitoring program that depends on audio recordings include: 1) poor or no detection of species
415 or individuals that rarely use acoustic signals for communication (e.g. females and juvenile), 2) a
416 single permanent or fixed station will only record biotic activity in a limited radius around the
417 station and this distance will vary among species depending on the sound pressure generated by
418 the calling individual (Llusia et al., 2011), and 3) using models to identify species-specific
419 vocalizations in recordings with varying degrees of intense background noise (e.g. other species,
420 rain, wind, automobile traffic) could result in misidentifications.

421 422 **Species-specific identification models and daily and long-term activity** 423 **patterns**

424 For many studies, presence/absence data or an index of relative abundance can be very
425 useful, but it is not easy to extract this information from thousands of recordings. While some
426 researchers have the programming skills to manage and analyze their recordings, most do not.
427 Typically, researchers resort to listening to a subset of their recordings, which can be very time
428 consuming and leads to a considerable loss of data. In contrast, the ARBIMON-acoustic
429 software allows the user to reduce the time analyzing recordings, while taking advantage of the
430 complete data set. To do this the user must only inspect a subset of the recordings to provide
431 examples of the species-specific vocalization (i.e. training data) and create the validation data
432 set, which is needed for training the initial model and to evaluate the accuracy and precision of
433 each model, respectively. Our results illustrate that the species-specific identification models
434 created using the ARBIMON-acoustic system worked well for birds, mammals, amphibians and
435 insects, and the models had high levels of accuracy and precision. These models allowed us to
436 process 100,000s of recordings to generate detailed information on daily and monthly
437 vocalization patterns for these species. Another important feature is that these models can be
438 used in other projects, allowing new users to dedicate their time to producing new models of
439 other vocalizations made by the same species or of other species. Most importantly, these
440 web-based tools greatly simplify the process of extracting useful results for researchers and
441 managers from the raw data (i.e. recordings), which should help the users to improve and expand
442 their ecological monitoring programs.

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563 **Figure legends**

564

565 Figure 1. Workflow of data acquisition, processing, and management.

566

567 Figure 2. The ARBIMON-acoustic web-based tools for creating, testing, and applying the
568 species-specific identification models.

569

570 Figure 3. Daily (a-c) and monthly (d-f) vocal activity of three species from Sabana Seca, Puerto
571 Rico. The number in parenthesis is the number of recordings where the species was detected by
572 the model. The detection frequency was calculated as the number of recordings with a positive
573 detection divided by the total number of recordings during the time period.

574

575 Figure 4. Daily vocal activity of six species from La Selva Biological Station, Costa Rica. The
576 number in parenthesis is the number of recordings where the species was detected by the model.
577 The detection frequency was calculated as the number of recordings with a positive detection
578 divided by the total number of recordings during the time period.

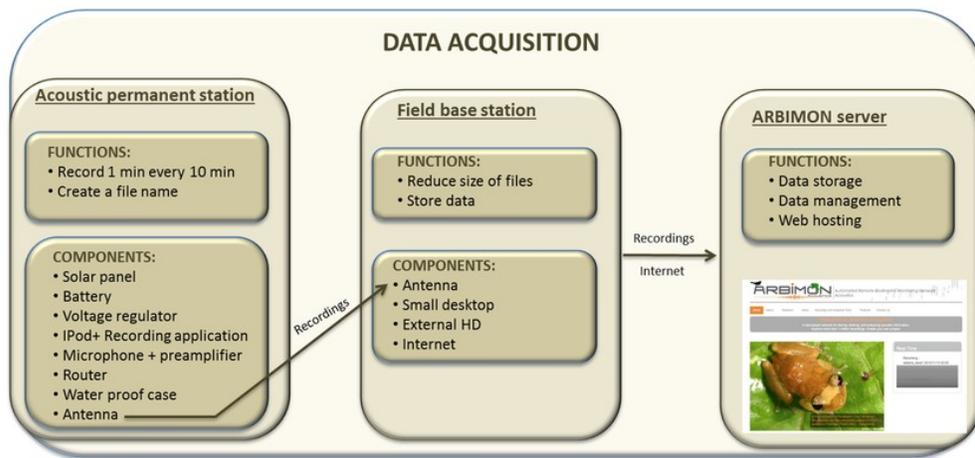
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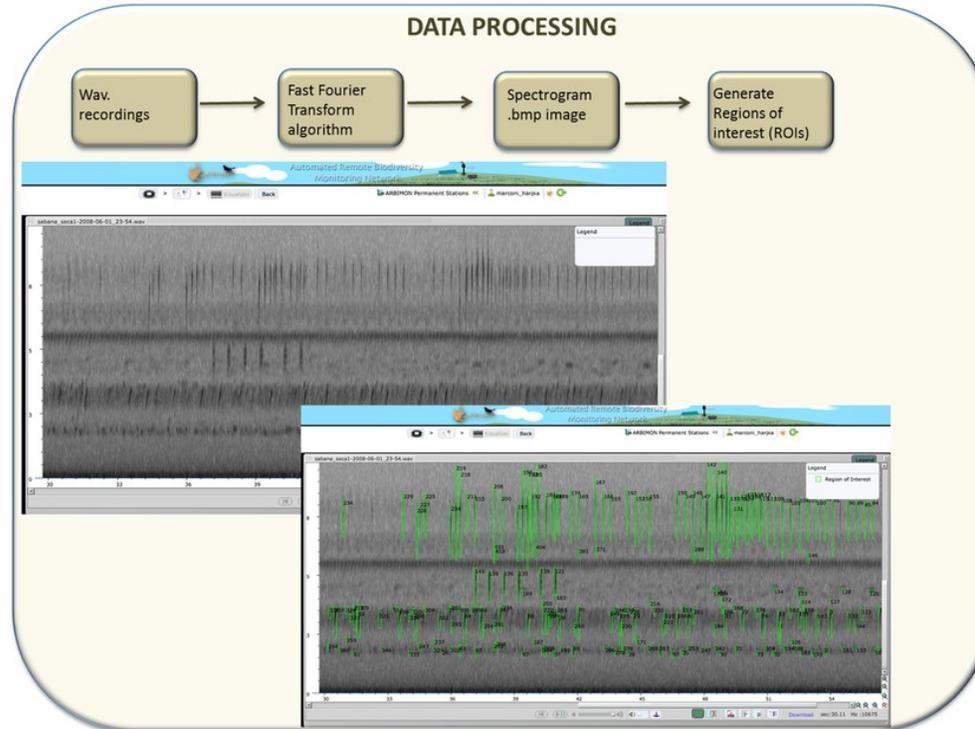
Figure 1

Workflow of data acquisition, processing, and management.

DATA ACQUISITION



DATA PROCESSING



DATA MANAGEMENT

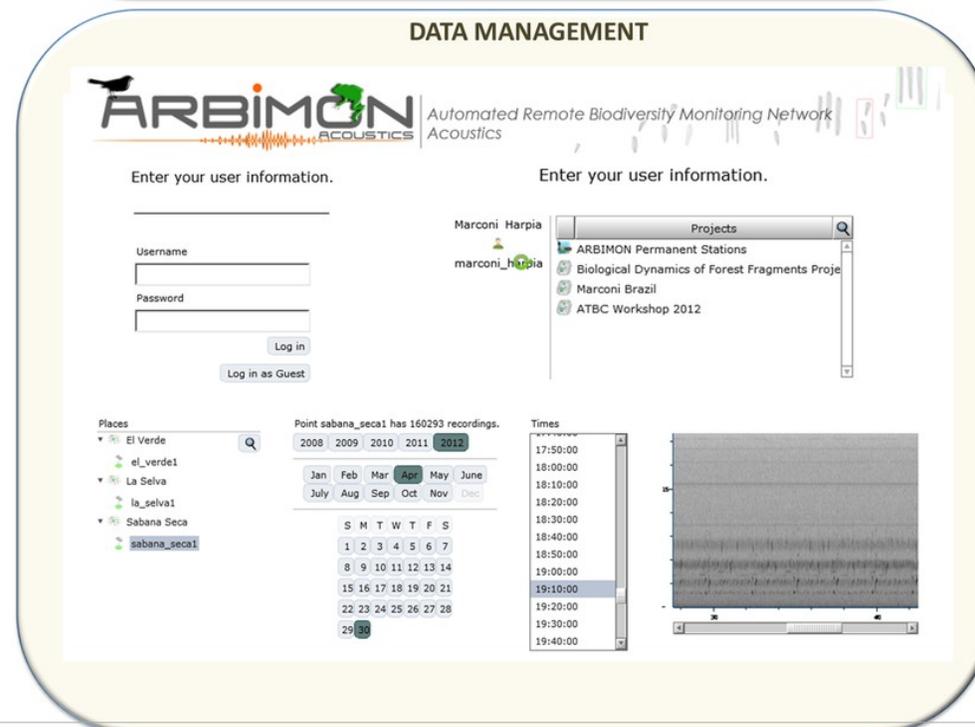


Figure 2

The ARBIMON-acoustic web-based tools for creating, testing, and applying the species-specific identification models.

1) Species validation

Validated Species

Project Species	Present	NOT Present
Eleutherodactylus jananari Common Song	<input checked="" type="checkbox"/> Has ROIs	
Eleutherodactylus brittoni Common Song		
Eleutherodactylus equi Common Song		
Eleutherodactylus hedricki Common Song		
Eleutherodactylus portoricensis Common Song		
Leptodactylus ablabris Common Song		
Rhinella marina Common Song		
Amazilia autumnalis Common Song		
Rana grylio Common Song		<input checked="" type="checkbox"/>

2) Training data

Song Classifier

Specie :
Eleutherodactylus jananari
Common Song

Add to Training Set

Submit Classification

Index	T1(s)	T2(s)	minFreq(Hz)	maxFreq(Hz)	syllable type
94	43.3972	43.4495	5943.16	9646.88	1
93	43.6585	43.7282	5770.9	9991.41	1

3) Create and training model

Model

2012-10-19 16:43:04
Eleutherodactylus jananari
Common Song
1 tones, 3 boxes
0 Data Points.

Training Set

2012-10-19 16:38:31
1 Data Point.

Create New Model

Choose Model

Train Model

Review Training Data

Publish Training Set

Choose Training Set

Clear Training Set

4) Model validation

Model Validation

2012-11-12 13:42:50

Total Recordings : 231
Recordings Searched : 231
Validation has finished.

View Validation Data

Export Validation Data

Run Another Validation

Compare Validations

Run

Error Matrix :

	Detected	Not Detected	Total
Present Marked	108 47%	17 7%	125 54%
Present Unmarked	1 0%	11 5%	12 5%
Not Present	6 3%	88 38%	94 41%
Total	115 50%	116 50%	231 100%

Error Matrix :

	Detected	Not Detected
Present	109 (TP = 80%)	28 (FN = 20%)
Not Present	6 (FP = 6%)	88 (TN = 94%)

Accuracy : 85%
Precision : 95%
Kappa : 71%

5) Compare validation

Compare Validations

Sort by : Date Ascending

Validation Date	Error Matrix :		Factors :						
	Detected	Not Detected	#	Max Freq	Min Freq	Duration	Bandwidth	Silence	
2012-10-19 16:43:04	6 (FP = 7%)	76 (TN = 93%)	1	7000	1175	5250 - 8000	0.03 - 0.17	2500 - 6500	0.10 - 4.00
2012-10-21 14:01:42	91 (TP = 81%)	21 (FN = 19%)	1	7000	1175	5250 - 8000	0.03 - 0.17	2500 - 6500	0.08 - 4.00
2012-10-21 14:03:05	11 (FP = 13%)	71 (TN = 87%)	1	7000	1175	5250 - 8000	0.03 - 0.17	2500 - 6500	0.08 - 4.00
2012-10-21 14:05:40	89 (TP = 79%)	23 (FN = 21%)	1	7000	1175	5250 - 8000	0.03 - 0.17	2500 - 6500	0.20 - 4.00
2012-10-21 14:06:18	88 (TP = 79%)	24 (FN = 21%)	1	7000	1175	5250 - 8000	0.03 - 0.17	2500 - 6500	0.30 - 4.00

6) Run Model over all data

Model Run

2012-10-21 14:10:32

Recordings
Total : 156615
Searched : 156615
Detected : 32052
Model run has finished.

Export Run Data

Run Model Again

Run

Syllable # 1

Duration : 0.030 s - 0.170 s

Frequency
- Max : 7000 Hz - 11750 Hz
- Min : 5250 Hz - 8000 Hz

Bandwidth : 2500 Hz - 6500 Hz

Silence : 0.100 s - 1.000 s

Threshold : 0 1 0.1

Figure 3

Vocal activity in Sabana Seca

Daily (a-c) and monthly (d-f) vocal activity of three species from Sabana Seca, Puerto Rico. The number in parenthesis is the number of recordings where the species was detected by the model. The detection frequency was calculated as the number of recordings with a positive detection divided by the total number of recordings during the time period.

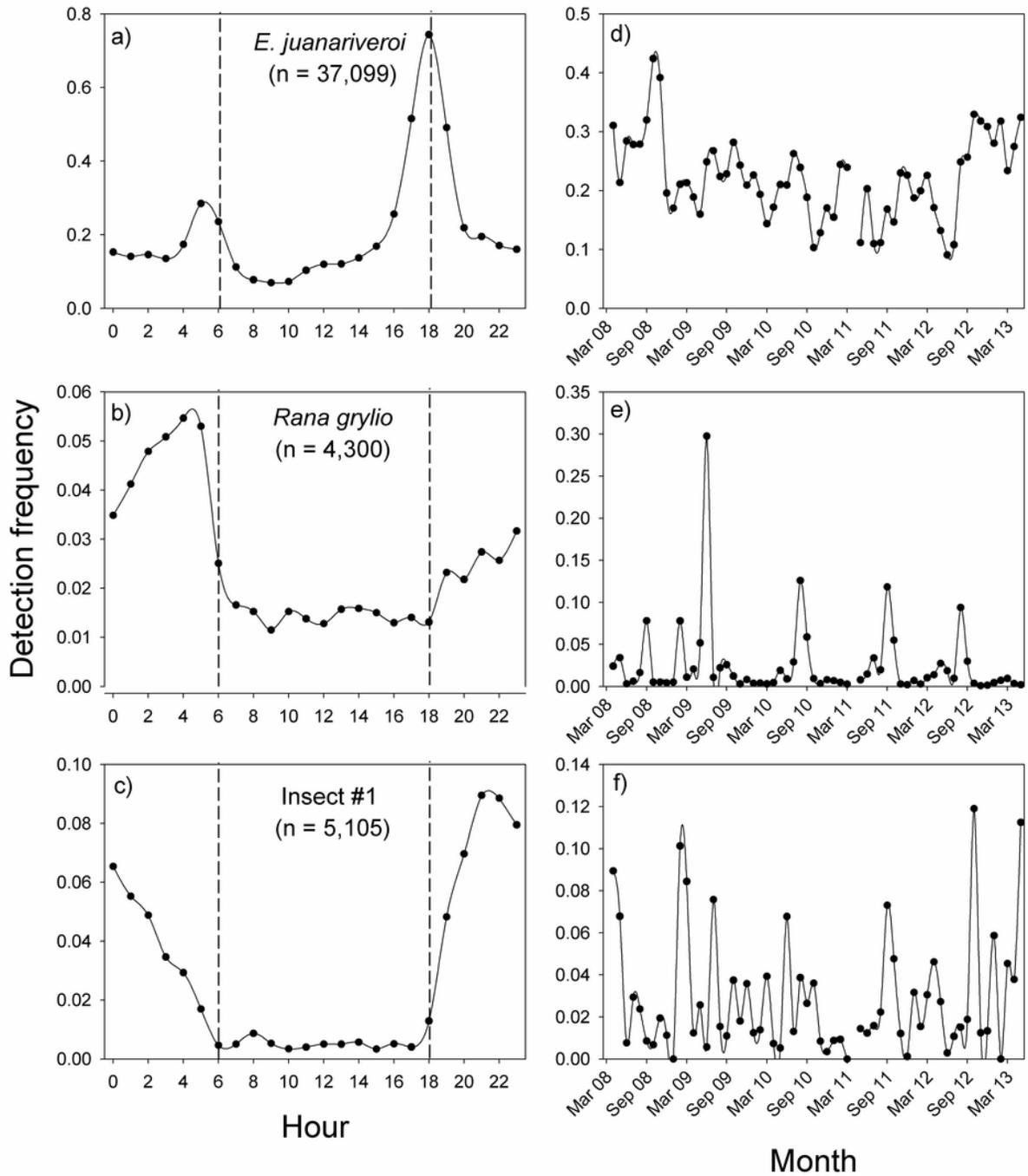


Figure 4

Vocal activity in La Selva

Daily vocal activity of six species from La Selva Biological Station, Costa Rica. The number in parenthesis is the number of recordings where the species was detected by the model. The detection frequency was calculated as the number of recordings with a positive detection divided by the total number of recordings during the time period.

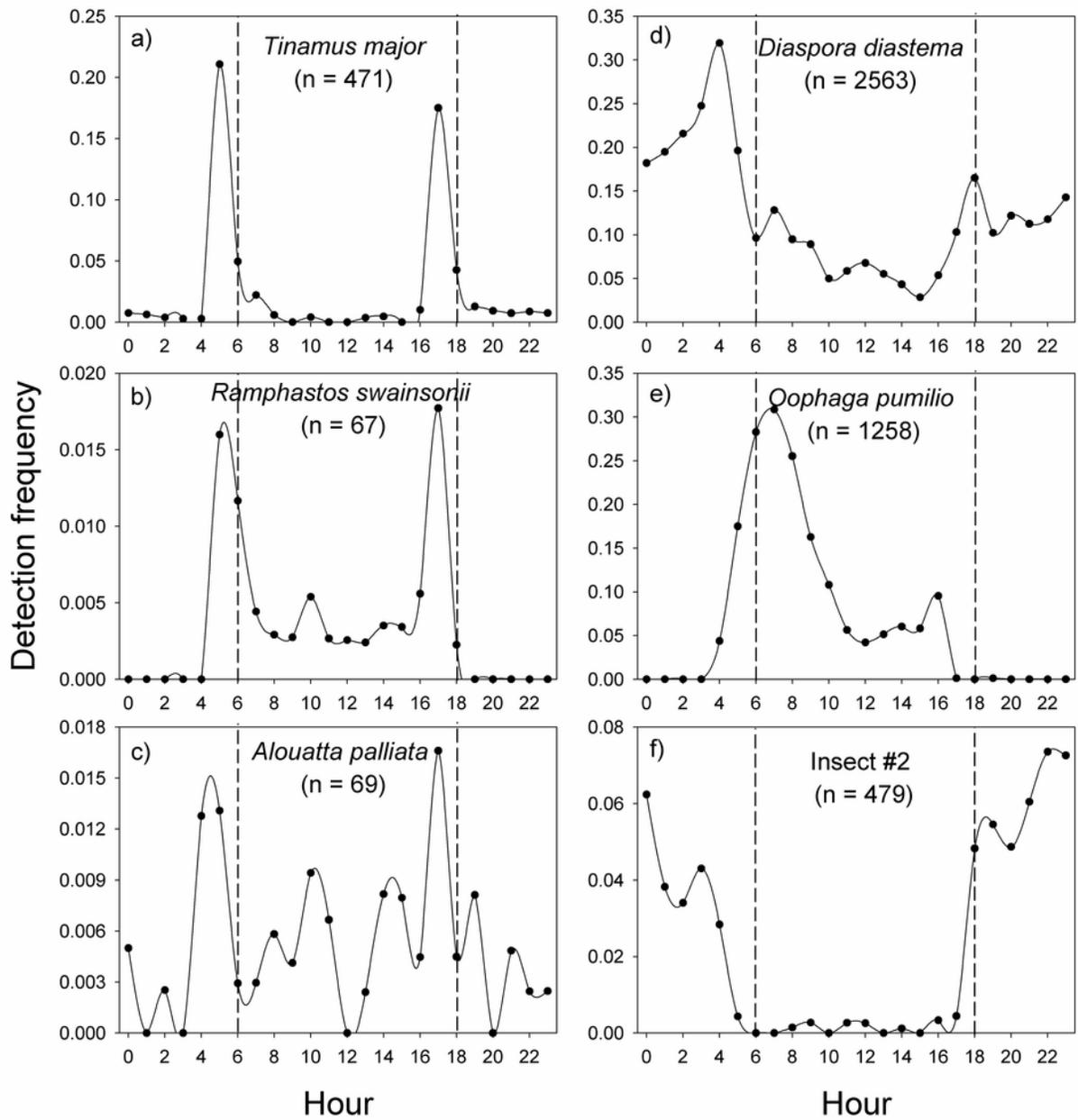


Table 1(on next page)

Confusion matrix of the species-specific models.

The confusion matrix results based on a comparison of the validation training set for each of the nine species with the model results. LSBS – La Selva Biological Station, Costa Rica; SS – Sabana Seca, Puerto Rico.

Table 1. The confusion matrix results based on a comparison of the validation training set for each of the nine species with the model results. LSBS – La Selva Biological Station, Costa Rica; SS – Sabana Seca, Puerto Rico.

Species	Site	Validation data (n)	True positives	False positives	True negatives	False negatives	Accuracy	Precision
<i>Oophaga pumilio</i>	LSBS	183	31	0	150	2	99	100
<i>Ramphastos swainsonii</i>	LSBS	395	24	5	348	18	94	83
<i>Alouatta palliata</i>	LSBS	342	35	11	288	8	94	76
<i>Tinamus major</i>	LSBS	407	67	1	298	41	90	99
<i>Rana grylio</i>	SS	127	37	6	76	8	89	86
<i>Eleutherodactylus juanariveroi</i>	SS	231	109	6	88	28	85	95
Insect 01	SS	130	50	7	61	12	85	88
<i>Diaspora diastema</i>	LSBS	190	54	4	101	31	82	93
Insect 02	LSBS	163	53	1	75	34	79	98