

Influences of heel height on human postural stability and functional mobility between inexperienced and experienced high heel shoe wearers

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Background. High heel shoes (HHS) can affect human postural control because elevated heel height (HH) may result in plantar flexed foot and limit ankle joint range of motion during walking. Effects of HH and HHS wearing experience on postural stability during self-initiated and externally triggered perturbations are less examined in the literature. Hence, the objective of the present study is to investigate the influences of HH on human postural stability during dynamic perturbations, perceived stability, and functional mobility between inexperienced and experienced HHS wearers. **Methods.** A total of 41 female participants are recruited (21 inexperienced HHS wearers and 20 experienced HHS wearers). Sensory organization test (SOT), motor control test (MCT), and limits of stability (LOS) were conducted to measure participant's postural stability by using computerized dynamic posturography. Functional reach test, timed up and go tests, and a visual analog scale were performed to measure functional mobility and perceived stability. Four pairs of shoes with different HH (i.e., 0.8, 3.9, 7.0, and 10.1 cm) were applied to participants randomly. Repeated measures analysis of variance was conducted to detect the effects of HH and HHS wearing experience on each variable. **Results.** During self-initiated perturbations, equilibrium score remarkably decreased when wearing 10.1 cm compared with flat shoes and 3.7 cm HHS. The vision system had higher weight in 10.1 cm HHS than in flat shoes. The use of ankle strategy worsened when HH increased to 7 cm. Similarly, the directional control of the center of gravity (COG) decreased for 7 cm HHS in LOS. Experienced wearers showed significantly better ankle strategy and COG directional control than novices. Under externally triggered perturbations, postural stability was substantially decreased when HH reached 3.9 cm in MCT. No significant difference was found in experienced wearers compared with novices in MCT. Experienced wearers exhibited considerably better functional mobility and perceived stability with increased HH. **Conclusions.** The use of HHS may worsen dynamic postural control and functional mobility when HH increases to

3.9 cm. Although experienced HHS wearers exhibit better postural strategy and directional control, the experience may not influence overall human postural control.

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13 **Abstract**

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20 experienced HHS wearers.

21 **Methods.** A total of 41 female participants are recruited (21 inexperienced HHS wearers and 20
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24 computerized dynamic posturography. Functional reach test, timed up and go tests, and a visual
25 analog scale were performed to measure functional mobility and perceived stability. Four pairs
26 of shoes with different HH (i.e., 0.8, 3.9, 7.0, and 10.1 cm) were applied to participants randomly.
27 Repeated measures analysis of variance was conducted to detect the effects of HH and HHS
28 wearing experience on each variable.

29 **Results.** During self-initiated perturbations, equilibrium score remarkably decreased when
30 wearing 10.1 cm compared with flat shoes and 3.7 cm HHS. The vision system had higher
31 weight in 10.1 cm HHS than in flat shoes. The use of ankle strategy worsened when HH
32 increased to 7 cm. Similarly, the directional control of the center of gravity (COG) decreased for
33 7 cm HHS in LOS. Experienced wearers showed significantly better ankle strategy and COG
34 directional control than novices. Under externally triggered perturbations, postural stability was
35 substantially decreased when HH reached 3.9 cm in MCT. No significant difference was found
36 in experienced wearers compared with novices in MCT. Experienced wearers exhibited
37 considerably better functional mobility and perceived stability with increased HH.

38 **Conclusions.** The use of HHS may worsen dynamic postural control and functional mobility
39 when HH increases to 3.9 cm. Although experienced HHS wearers exhibit better postural

40 strategy and directional control, the experience may not influence overall human postural control.

41 **Keywords.** high heel shoes; heel height; wearing experience; postural stability; functional

42 mobility

43

44 **1. Introduction**

45 High heel shoes (HHS) have been widely used among women in several centuries; 37% to
46 69% of women wear HHS daily (American Podiatric Medical Association, 2003). HHS are
47 featured with heel elevation, rigid heel cap, and curved plantar region, all of which interfere
48 with natural foot motion (Cronin, 2014). A more plantar flexed and supinated foot position can
49 alter the distribution of plantar pressure, affect muscle activities around ankle joints, and limit the
50 range of motion (ROM) of the ankle during standing and walking (Ko et al., 2009; Luximon et
51 al., 2015; Simonsen et al., 2012). A number of studies have documented that the effects of HHS
52 are not localized to the ankle; instead, a “chain reaction” of kinematic effects travels up the lower
53 limb and disturbs the displacement of the center of mass (COM; Chien et al., 2013; Cronin, 2014;
54 Schroeder & Hollander, 2018). These biomechanical alterations can decrease perceived stability,
55 impair postural control, and increase the risks of falling among HHS wearers (Luximon et al.,
56 2015; Wan et al., 2019). High heels-related injuries increased from 7.1% to 14.1% during the 11-
57 year period from 2002 to 2012, where most injuries occurred on foot and ankle as sprains and
58 strains (Barnish & Barnish, 2009; Moore et al., 2015).

59 One of the risk factors on high heels-related injuries is decreased postural stability among
60 HHS wearers (Wan et al., 2019). Postural control is the ability to stabilize and restore the body’s
61 COM relative to the base of support (BOS) during self-initiated and externally triggered
62 perturbations (Horak, 2006; Winter, 1995). To maintain postural stability, a complex motor skill
63 based on the interaction of proprioceptive, visual, and vestibular system is utilized in this process
64 (Mancini & Horak, 2010). Wearing HHS can cause biomechanical constrains and disturb human
65 movement strategies through reduced BOS and elevated heel height (HH; Chien et al., 2013).
66 The HHS wearers tend to apply different movement strategies (e.g., ankle and hip strategy) to

67 maintain the stability of the body's equilibrium with regard to elevated HH during standing,
68 walking, and dynamic perturbations.

69 A number of studies found that different HH can influence postural stability through
70 interfering with the stabilization of COM with respect to the BOS. Different sensory and
71 movement strategies are also involved in the process of postural control in HHS wearers. Recent
72 studies have examined that HHS wearers had significantly worse standing balance starting at 7
73 cm HH by analyzing the center of pressure (COP) magnitude in quiet stance and limits of
74 stability test (LOS; Choi & Cho, 2006; Gerber et al., 2012; Mika et al., 2016). During extrinsic
75 perturbations, previous studies demonstrated that HHS can impair human balance (e.g.,
76 sinusoidal oscillations and waist pulling; Choi & Cho, 2006; Sun et al., 2017). When HH
77 increased to 10 cm, increased use of ankle strategy, slow center of gravity (COG) movement
78 velocity, and decreased body equilibrium were observed with increased HH (Hapsari & Xiong,
79 2016; Truszczyńska et al., 2019). However, no difference in the interaction of sensory systems
80 was found in postural control among HHS wearers with increased HH (Hapsari & Xiong, 2016).
81 It will be worthwhile to detect how sensory systems interact during postural control, to what
82 extend HH can affect movement strategy and influence human overall postural control
83 accordingly.

84 HHS experience might be another vital factor that can influence HHS wearers' postural
85 stability as well. Previous research have shown significant muscular alterations, such as
86 overwork muscle activities in medial gastrocnemius and peroneus longus, shortened calf muscles,
87 and increased Achilles tendon stiffness after long-term use of HHS (Cronin et al., 2012; Csapo et
88 al., 2010; Kermani et al., 2018). These accommodations can affect the efficient use of ankle
89 strategies on maintaining postural stability, thereby resulting in deficiencies during standing and
90 walking (Chien et al., 2014; Rahimi et al., 2017; Wan et al., 2019). However, Xiong and Hapsari
91 found no significant difference in self-initiated standing balance and functional mobility between
92 experienced HHS wearers and inexperienced HHS wearers, although the experienced group
93 showed better directional control of COG in LOS (Hapsari & Xiong, 2016). Therefore, whether

94 HHS wearing experience can influence human postural stability and functional mobility remains
95 unclear.

96 Hence, the current study aims to investigate the effects of HH (i.e., 0.8, 3.9, 7.0, and 10.1 cm)
97 and HHS experience on postural stability during dynamic perturbations, perceived stability, and
98 functional mobility in women. We hypothesized that human postural stability could decrease
99 with increasing HH, and HHS experience could improve performance in postural control and
100 functional mobility test.

101 **2. Materials & Methods**

102 **2.1 Participants**

103 A total of 41 female participants were recruited from the local university and communities
104 (21 inexperienced HHS wearers and 20 experienced HHS wearers). All participants had a shoe
105 size of EU 36–39 and self-reported to be free from lower limb injuries for a minimum of six
106 months prior to the study. Participants with any history of musculoskeletal, cardiovascular,
107 neurological, and VEST abnormalities were excluded from the experiment. Experienced HHS
108 wearers were those who had worn narrow-heeled shoes with a minimum HH of 4 cm two or
109 more times per week and at least eight hours per day for one year. Inexperienced HHS wearers
110 were participants wearing HHS less than once per week (Hapsari & Xiong, 2016). The study was
111 approved by the ethics committee of Shanghai University of Sport (Number: 2018074), and all
112 subjects were provided written consents prior to the experiment.

113 **2.2 Experimental shoes**

114 Experimental shoes with HH of 0.8, 3.9, 7.0, and 10.1 cm were used in the study (Figure 1).
115 All the experimental shoes were manufactured by the same manufacturer. The shoe style and
116 materials were maintained the same to minimize confounding variance. Except for the 0.8 cm
117 HHS as the baseline condition, the three other types of HHS were featured with narrow-heeled
118 shoes (12.5 mm*12.0 mm). Participants were allowed to familiarize themselves with the most
119 suitable experimental shoes with shoe size ranging from EU 36–39 prior to the experiment. The
120 four HHS testing conditions were assessed in random order in the study.

121 *Insert Figure 1 here*

122 **2.3 Data collection**

123 **2.3.1 Postural control**

124 NeuroCom Balance Manager System (Version 9.3, Natus Medical Incorporated, USA)
125 SMART EquiTest was used to assess postural stability by measuring the participants' COG
126 alignment at a sampling frequency of 100 Hz after they were familiar with the experimental HHS
127 (Chander et al., 2016; Hapsari & Xiong, 2016). Computerized dynamic posturography has been
128 proven to be a "gold standard" for assessing postural stability with high reliability and validity
129 (Harro & Garascia, 2019). Prior to the test, participants were secured with a protective vest from
130 falling off the instrumentation. They were instructed to stand on the two force plates (23 cm*46
131 cm) with feet aligned with the platform axis as the initial position. SOT and LOS were used to
132 test the participants' standing balance during self-initiated perturbations, and postural stability
133 during externally triggered perturbations was tested by motor control test (MCT). Participants
134 were requested to stand still with their feet fixed in the initial position. Five-minute rest was
135 allowed between each postural control test to prevent fatigue.

136 **2.3.1.1 Sensory organization test (SOT)**

137 SOT utilizes the sway-referencing capabilities of the visual and the support surface to
138 evaluate the integration of the sensory systems in postural control by selectively disrupting
139 somatosensory and/or visual information. The six testing conditions in SOT are described in
140 Table 1 (Yin & Wang, 2020). Each testing condition was repeated three times. All the testing
141 orders were randomly assigned to the participants. The equilibrium and composite scores (0–100)
142 represent the ability of the participants to maintain postural stability in each condition and overall
143 postural control, respectively. The strategy scores (0–100) quantify the relative amount of
144 movement about the ankle and hip strategies that participants used in maintaining postural
145 stability. A strategy score approaching 100 indicates that ankle strategy is more dominant in
146 maintaining balance, whereas a score closest to 0 suggests that the participant uses hip strategy
147 dominantly to stabilize her body under each trial. Somatosensory, vestibular, and visual scores

148 (0–100) in sensory analysis quantify the participants' ability to integrate proprioception,
149 vestibulum, and vision information that contribute to balance, respectively.

150 *Insert Table 1 here*

151 **2.3.1.2 Motor control test (MCT)**

152 Postural stability under support surface perturbations was assessed by MCT. The two force
153 plates with translation capabilities in backward and forward directions can create six perturbing
154 conditions, which are small backward translation (SBT), medium backward translation (MBT),
155 large backward translation (LBT), small forward translation (SFT), medium forward translation
156 (MFT), and large forward translation (LFT). The amplitude was scaled to the participants' body
157 weight and height. Each testing condition was repeated three times. The six testing conditions
158 were assigned in random order. The outcome measures were composite latency and amplitude
159 scaling. Composite latency measures the reaction time from the translation of the platform to the
160 displacement of COG in milliseconds. Amplitude scaling quantifies the force generated from the
161 lower limb in response to the external perturbations.

162 **2.3.1.3 Limits of stability test (LOS)**

163 LOS quantifies the ability of participants to intentionally displace their COG within the BOS.
164 In LOS, a computerized screen was placed in front of the participants. They were instructed to
165 lean their body on the sagittal plane in each direction to reach to the target location displayed on
166 the screen as far as possible upon hearing an auditory cue. Then, they were required to remain in
167 that position for 10 s. The outcome measures were COG movement velocity and directional
168 control (DCL). COG movement velocity in degree per second ($^{\circ}/s$) represents the average COG
169 movement speed from the initial place to the target position. Directional control was calculated
170 as the amount of the COG movement toward the intended direction minus the amount of off-axis
171 movement (Yin & Wang, 2020).

172 **2.3.2 Functional mobility test**

173 After postural control tests, functional reach test (FRT) and timed up and go test (TUGT)
174 were performed to measure functional mobility. FR measures the maximum forward reach of the

175 participants. Participants were instructed to lean their body forward as far as possible without
176 stepping and reaching for assistance. Three trials were conducted for data normalization. TUGT
177 measures the complete time of a 3 m walking trial. Participants were requested to walk on their
178 own speed. The fastest among the three testing trials was used for data analysis.

179 **2.3.3 Perceived stability**

180 Thereafter, the participants were instructed to quantify their perceived stability in FRT on a
181 visual analog scale (VAS). The scores range from 0–100. The VAS score of 0 indicates that the
182 participants were perceived as unstable, whereas a score of 100 suggests the most stable situation
183 that can be perceived.

184 **2.4 Statistical analysis**

185 All data were presented as mean \pm standard deviation (SD). The normal distribution of data
186 was examined by the Shapiro–Wilk test. Repeated measurement of ANOVA (HH * HHS
187 wearing experience) was conducted to detect the effects of HH and HHS wearing experience on
188 each variable. Simple main effect analysis was used for *post hoc* comparisons. Significance was
189 set at an alpha level of $p < 0.05$. Partial eta-squared (η^2) effect size, 95% confidence interval (CI),
190 and F-statistic were reported. Statistical analysis was performed using SPSS 22.0 statistical
191 software package (SPSS Inc., Chicago, USA).

192 **3. Results**

193 **3.1 Demographic characteristics of the participants**

194 Table 2 illustrates the characteristics of the participants. No significant differences were
195 observed in age, height, weight, and body mass index (BMI) between the two groups. The
196 experienced group showed significantly higher HHS wearing frequency than the inexperienced
197 group ($p < 0.001$).

198 *Insert Table 2 here*

199 **3.2 SOT**

200 The descriptive data of SOT are shown in Table 3. No statistically significant interaction
201 was found between the HH and HHS wearing experience on the outcome measures of SOT
202 (Table 3). The main effect of HH was significant for the equilibrium score in C1 ($F(3,38)=8.342$,

203 $p < 0.001$, $\eta^2=0.202$), C2 ($F(3,38)=14.498$, $p < 0.001$, $\eta^2=0.202$), C3 ($F(3,38)=10.428$, $p < 0.001$,
204 $\eta^2=0.202$), and C5 ($F(3,38)=10.920$, $p < 0.001$, $\eta^2=0.202$). No significant effect of HHS wearing
205 experience was found on the equilibrium score. Post hoc analysis revealed significantly lower
206 equilibrium score in 10.1 cm than 7 cm HHS among experienced HHS wearers in C2 ($p=0.035$,
207 95% CI=0.143–5.590).

208 The main effect of HH was significant for the strategy score in six conditions
209 ($F(3,38)=12.234$, $p < 0.001$, $\eta^2=0.176$; $F(3,38)=29.763$, $p < 0.001$, $\eta^2=0.271$; $F(3,38)=21.591$, $p <$
210 0.001 , $\eta^2=0.356$; $F(3,38)=3.125$, $p=0.036$, $\eta^2=0.074$; $F(3,38)=10.598$, $p < 0.001$, $\eta^2=0.214$;
211 $F(3,38)=5.601$, $p=0.002$, $\eta^2=0.126$). The main effect of wearing experience was also significant
212 in C3 ($F(1,40)=10.841$, $p=0.002$, $\eta^2=0.218$), C5 ($F(1,40)=4.977$, $p=0.032$, $\eta^2=0.022$), and C6
213 ($F(1,40)=5.857$, $p=0.020$, $\eta^2=0.132$). The strategy score decreased significantly when HH
214 increased to 7 cm compared with flat shoes among experienced HHS wearers in C5 ($p=0.001$,
215 95% CI=0.997–4.036). In C3, the experienced HHS wearers demonstrated significantly higher
216 strategy score than inexperienced HHS wearers in flat shoes ($t=-2.231$, $p=0.033$), 3.9 cm
217 ($t=-2.404$, $p=0.023$), and 10.1 cm HHS ($t=-3.327$, $p=0.002$; Table 3).

218 Table 3 illustrates that the main effect of HH was significant for sensory analysis score in
219 SOM ($F(3,38)=3.059$, $p=0.031$, $\eta^2=0.099$) and VIS ($F(3,38)=4.270$, $p=0.010$, $\eta^2=0.099$), but the
220 main effect of wearing experience was undetected. *Post hoc* analysis showed that the sensory
221 analysis score declined significantly in VIS when wearing 10.1 cm HHS compared with flat
222 shoes in inexperienced wearers ($p=0.008$, 95% CI=1.470–12.244).

223 *Insert Table 3 here*

224 3.3 MCT

225 No significant interaction between the HH and wearing experience was detected on outcome
226 measures of MCT. As shown in Table 4, the main effect of HH was significant for the composite
227 latency ($F(3,38)=3.121$, $p=0.044$, $\eta^2=0.080$), whereas no significant difference was detected in
228 the pairwise comparison. The HH revealed a significant main effect on amplitude scaling in SBT
229 ($F(3,38)=7.004$, $p < 0.001$, $\eta^2=0.163$), MBT ($F(3,38)=3.630$, $p=0.015$, $\eta^2=0.092$), SFT
230 ($F(3,38)=15.604$, $p < 0.001$, $\eta^2=0.302$), MFT ($F(3,38)=24.919$, $p < 0.001$, $\eta^2=0.409$), and LFT

231 ($F(3,38)=9.522, p < 0.001, \eta^2=0.209$). No significant main effect was investigated for HHS
232 wearing experience on amplitude scaling in six perturbing conditions. In MFT, the amplitude
233 scaling was significantly higher when HH increased to 7 cm compared with flat shoes among
234 experienced wearers ($p=0.013, 95\% \text{ CI}=-2.193-0.207$).

235 *Insert Table 4 here*

236 **3.4 LOS**

237 No statistically significant interaction was found between the HH and HHS wearing
238 experience on COG movement velocity, whereas the two-way interaction was significant on
239 directional control ($F(3,38)=7.790, p < 0.001, \eta^2=0.166$). The main effect of HH was significant
240 for COG movement velocity ($F(3,38)=20.770, p < 0.001, \eta^2=0.347$) and directional control
241 ($F(3,38)=75.478, p < 0.001, \eta^2=0.659$). The significant main effect of wearing experience was
242 also determined for directional control ($F(1,40)=5.114, p=0.029, \eta^2=0.116$). The results of *post*
243 *hoc* analysis are shown in Figure 2. COG movement velocity decreased significantly when
244 wearing 3.9 cm HHS compared with 10.1 cm HHS among experienced wearers ($p=0.001, 95\%$
245 $\text{CI}=0.310^\circ/\text{s}-1.480^\circ/\text{s}$). Experienced HHS wearers exhibited significantly better COG directional
246 control than inexperienced wearers when wearing 10.1 cm HHS ($t=-3.391, p=0.002$).

247 *Insert Figure 2 here*

248 **3.5 Functional mobility**

249 The two-way interaction (HH * wearing experience) was significant for FRT distance
250 ($F(3,38)=3.858, p=0.016, \eta^2=0.090$) and TUGT time ($F(3,38)=9.883, p < 0.001, \eta^2=0.202$). The
251 main effect of HH was significant for FRT distance ($F(3,38)=94.859, p < 0.001, \eta^2=0.709$) and
252 TUGT time ($F(3,38)=127.372, p < 0.001, \eta^2=0.766$). Significant main effect of wearing
253 experience was also determined for FRT distance ($F(1,40)=10.840, p=0.002, \eta^2=0.217$) and
254 TUGT time ($F(1,40)=10.639, p=0.0021, \eta^2=0.214$). The results of the pairwise comparison are
255 illustrated in Figure 3. Generally, functional mobility decreased as HH increased. FRT distance
256 was significantly shorter in 10.1 HHS than in flat shoes ($p < 0.001, 95\% \text{ CI}=3.170-8.973 \text{ cm}$),
257 3.9 cm ($p < 0.001, 95\% \text{ CI}=4.254-8.146 \text{ cm}$), and 7 cm HHS ($p < 0.001, 95\% \text{ CI}=2.675-6.225$
258 cm) among experienced wearers. TUGT time showed a significant difference when wearing

259 different HHS in experienced and inexperienced wearers. Experienced wearers performed longer
260 FRT distance than inexperienced wearers in 3.9 cm ($t=-2.714, p=0.010$), 7 cm ($t=-2.805,$
261 $p=0.003$) and 10.1 cm HHS ($t=-4.524, p < 0.001$). Similarly, TUGT time in experienced wearers
262 was significantly shorter than inexperienced HHS wearers in 3.9 cm ($t=3.528, p=0.010$), 7 cm
263 ($t=3.117, p=0.003$), and 10.1 cm HHS ($t=3.698, p=0.001$).

264 *Insert Figure 3 here*

265 **3.6 Perceived stability**

266 The main effect of HH ($F(3,38)=26.911, p < 0.001, \eta^2=0.415$) and wearing experience
267 ($F(1,40)=11.517, p=0.001, \eta^2=0.027$) was significant for perceived stability. No significant two-
268 way interaction was detected on perceived stability. The perceived stability was decreased with
269 increased HH. Specifically, the perceived stability reduced significantly in 7 cm HHS relative to
270 flat shoes ($p=0.001, 95\% \text{ CI}=5.530-26.049$) and 3.9 cm HHS ($p=0.029, 95\% \text{ CI}=0.940-23.060$)
271 among experienced wearers. The inexperienced wearers also perceived significantly decreased
272 stability with increased HH similar to the experienced wearers (Figure 4). The experienced
273 wearers perceived significantly higher stability than inexperienced wearers in 3.9 cm ($t=-3.538,$
274 $p=0.002$), 7 cm ($t=-3.719, p=0.001$), and 10.1 cm HHS ($t=-2.656, p=0.011$).

275 *Insert Figure 4 here*

276 **4. Discussion**

277 The main purpose of the study is to evaluate the effects of HH and HHS wearing experience
278 on human postural stability under dynamic perturbations. During self-initiated standing
279 perturbations, HHS wearers exhibited decreased equilibrium and strategy scores in 10.1 cm HHS,
280 compared with flat shoes and 3.9 and 7 cm HHS. Vision played a vital role in the integration of
281 the sensory systems in the postural control process with elevated HH. With respect to the control
282 of the COG movement, the COG movement velocity and directional control declined in 10.1 cm
283 HHS compared with flat shoes and 3.9 cm HHS. During external support surface perturbations,
284 the postural latencies tended to delay with elevated HH. Amplitude scaling increased when HH
285 increased to 3.9 cm compared with flat shoes. Similarly, impaired functional mobility can be

286 detected in 3.9 cm HHS contrary to flat shoes. However, experienced HHS wearers did not show
287 better overall postural control in SOT than inexperienced wearers. Experienced wearers utilized
288 better ankle strategy and control of COG in maintaining postural stability. They perceived higher
289 stability and performed better functional mobility than inexperienced HHS wearers.

290 In SOT, decreased equilibrium and strategy scores were found in 10.1 cm HHS, compared
291 with flat shoes and 3.9 and 7 cm shoes. The ability to integrate the sensory systems to maintain
292 the stability of the body's equilibrium was impaired in 10.1 HHS. HHS wearers intended to use a
293 larger portion of vision than proprioception in the postural control process when wearing 10.1
294 cm HHS. However, the anticipatory postural reactions from proprioceptive receptors played a
295 vital role in maintaining balance, especially in the absence of vision (Mika et al., 2016). In SOT,
296 the elevated HH may simulate an unstable condition. The sensory condition is more challenged
297 because the support surface and vision are sway referenced. Humans can increase sensory
298 weighting to vestibular and vision information for postural orientation when surrounded by these
299 sway-referenced vision and unstable surfaces (Horak, 2006). Our study demonstrated that hip
300 strategy was adopted more than ankle strategy by HHS wearers with increased HH under
301 interfered conditions. The ankle strategy is the first postural control strategy adopted by humans
302 to counteract small perturbations of the COG. With the increase in HH, the distance of the ankle
303 and knee joints from the line of gravity is reduced (Stefanyshyn et al., 2000). The hip strategy is
304 used because the evaluated HH can restrict the ROM of ankle joints. HHS wearers cannot exert
305 torque at the ankles to rapidly move the body's COM (Horak & Kuo, 2000; Wan et al., 2019).
306 The results are in line with Xiong's study, in which the hip strategy was used because the ankle
307 strategy failed to maintain balance when wearing HHS (Hapsari & Xiong, 2016). Our study
308 showed that the HHS wearing experience had no significant effect on the overall human postural
309 control. Human postural control is considered a complex motor skill with respect to the support
310 surface, visual environment, and cognitive process (Shumway-Cook & Horak, 1986).
311 Experienced wearers were found to adapt to walking regularity more flexibly under cognitive
312 load than HHS novices (Schaefer & Lindenberger, 2013). Significant different muscle efforts

313 were exerted in HHS experts compared with novices (Stefanyshyn et al., 2000). Generally, HHS
314 experience might further influence cognitive processing and muscle activities. However, the
315 ability to integrate the sensory systems in postural control was not altered; this finding is
316 supported by Xiong's study (Hapsari & Xiong, 2016).

317 With regard to MCT, the amplitude scaling increased significantly when HH reach 3.9 cm.
318 Although the composite latency was 4.06% lower in 10.1 HH than in 3.9 cm HH, no
319 significantly delayed postural latency in response to external perturbations was found in our
320 study. Similarly, previous studies have shown no significant difference in postural reaction time
321 when wearing flip-flops, clog style Crocs, and Vibram Five-Fingers (Chander et al., 2016).
322 Footwear design characteristics may influence human postural reaction because elevated HH can
323 disturb the ROM of ankle joints and affect human postural control in response to forward
324 translations accordingly. When HH reached 3.9 cm, the increased amplitude scaling suggested
325 that HHS wearers may alter motor output strategies to maintain postural stability under
326 perturbations. In the motor output process, the gastrocnemius medialis (GM), gastrocnemius
327 lateralis (GL), tibialis anterior (TA), and vastus lateralis (VL) were found to exert more effort
328 when wearing 7 cm HHS compared to flat shoes (Hapsari & Xiong, 2016). The threshold of
329 afferent discharge of muscle spindle was raised. The HHS wearers' postural control can be
330 affected for the somatosensory alternation around the ankle and foot (Gefen et al., 2002).
331 However, no adverse effect on postural reaction was found even in 10.1 cm HHS. This finding
332 suggested that the delay of latency was often associated with neurological disorders and
333 anatomical constraints, other than the footwear design (Redfern et al., 2001). Previous studies
334 demonstrated that HHS can impair human balance during other extrinsic perturbations (e.g.,
335 sinusoidal oscillations and waist pulling; Choi & Cho, 2006; Sun et al., 2017). Sun et al. found
336 that the COP displacement increased, and the COP trajectory transferred to the medial foot
337 significantly during AP and ML perturbations when wearing 6.6 cm compared with 0.8 cm HH.
338 However, the study did not control the shoe design and applied three types of HHS in the
339 experiment (Sun et al., 2017). Choi and Cho compared human balance control of HHS wearers in

340 barefoot and high-heeled posture when experiencing a waist-pull perturbation by quantifying the
341 displacement and velocity of the COP. Results suggested that human balance control was
342 approximately twice worse in HHS than barefoot, and the perturbation amplitude was not
343 attributed to the participants' body weight and height (Choi & Cho, 2006). Experienced HHS
344 wearers exhibited no improvement in postural control under dynamic perturbations. They applied
345 different muscle activation patterns compared with inexperienced wearers. Experienced wearers
346 exerted significantly more muscle activities on GM and less muscular effort on VL, TA, and
347 erector spinae than novices in SOT (Hapsari & Xiong, 2016). During HHS walking, substantial
348 increases in muscle fascicle strains and muscle activation were found in experienced HHS
349 wearers compared with barefoot walking during the stance phase (Cronin et al., 2012).
350 Experienced wearers may regulate the flexibility of the neuromuscular system to adapt to
351 possible perturbations (e.g., walking and external perturbations) and can vary according to
352 different HHs (Alkjær et al., 2012).

353 Our study investigated that the COG movement velocity and directional control in LOS
354 significantly decreased in 10.1 cm compared with that in 3.9 cm HHS. Consistent with the
355 previous study, when HH increased to 10 cm, slower COG movement velocity was observed in
356 10 cm than in 4cm HH in LOS (Mika et al., 2016). The increased HH may induce the fear of
357 falling in HHS wearers. The HHS wearers manifested slow COG movement velocity, declined
358 COG excursions, and worst directional control, particularly in the forward and backward
359 directions (Hapsari & Xiong, 2016). The experienced HHS wearers showed better directional
360 control in 10.1 cm HHS. Better directional control may be due to the motor learning effects in
361 the experienced wearer, resulting in superior ankle strategy in maintaining postural stability
362 (Schaefer & Lindenberger, 2013). Nonetheless, another study suggested that the increased
363 muscular coactivation around the ankle joint could enhance joint stiffness during HHS walking.
364 The walking balance may be improved through altered muscle activation patterns (Alkjær et al.,
365 2012; Nielsen & Kagamihara, 1993). The effects of muscle activation patterns on the postural
366 control process in LOS among HHS wearers remain unclear.

367 The functional mobility was impaired when HH reached 3.9 cm. A number of studies have
368 shown that walking in HHS may affect neuromechanics and kinematics of the lower limbs when
369 HH increased to 4 cm HH (Naik et al., 2017). When walking in 4 and 10 cm HHS compared with
370 flat shoes, the postural stability may be decreased on the account of high joint stiffness evaluated
371 by muscle pair synchronization around the knee joint (Pratihast et al., 2018). Accordingly, the
372 TUGT completion time was longer for impaired postural stability and reduced perceived stability,
373 consistent with previous findings (Arnadottir & Mercer, 2000). Our study found that the
374 experienced HHS wearers had significantly shorter TUGT completion time and FRT distance
375 than the novices. Long-time use of HHS has been suggested to shorten the gastrocnemius muscle
376 fascicles and increase the Achilles tendon stiffness, thereby contributing to a restricted ankle
377 ROM and reduced functional reach mobility (Csapo et al., 2010). Cronin et al. suggested that
378 experienced HHS wearers may have increased muscle fascicle strains and lower limb muscle
379 activation than inexperienced wearers during HHS walking. This finding indicates chronic
380 adaptations in muscle–tendon structure related to HHS (Cronin et al., 2012). The experienced
381 wearers could apply altered movement strategies to increase effort on muscular control around
382 the knee and ankle joints, so as to obtain postural stability during HHS walking. However, high
383 muscle activities may contribute to muscle inefficiency and raised energy cost during walking,
384 thereby leading to muscle strains, muscle fatigue, and pain (Cronin, 2014; Csapo et al., 2010;
385 Ebbeling et al., 1994).

386 Although we found better functional mobility and higher perceived stability in experienced
387 HHS wearer, no significant increase in overall postural control was detected in long-time HHS
388 users in SOT. In functional tests, important resources, such as biomechanical constraints (e.g.,
389 strength and limits of stability), cognitive processing (e.g., learning and attention), movement
390 strategies (e.g., anticipatory and voluntary), and sensory strategies (e.g., sensory integration and
391 reweighting), are required for postural control. Thus, the loss of somatosensory in the foot and
392 higher sensory weighting in vision cannot completely predict the deficiencies in functional
393 mobility because the function depends on the aforementioned resources likewise (Horak, 2006;

394 Horak and Kuo, 2000). In terms of HH, we assume that the decreased perceived comfort and loss
395 of joint position may lead to low perceived stability, compromising functional mobility
396 accordingly (Hong et al., 2005; Lee & Hong, 2005).

397 The limitation of the study is that the results may not be extrapolated to all HHS populations
398 from different ages and health statuses, considering that we only recruited healthy young females
399 in our study. Furthermore, the neuromuscular mechanism of postural control in HHS wearers is
400 still unknown. The effects of HH and long-term use of HHS on lower limb muscle activities,
401 muscle coordination, and Hoffmann reflex need to be further studied to elucidate how CNS
402 controls motor output in the postural control process.

403 **5. Conclusions**

404 Perceived stability and functional mobility decreased when wearing HHS. The vision system
405 had high weight in maintaining postural stability when HH increased to 10.1 cm. During
406 dynamic perturbations, high percentage of ankle strategies and motor control strategies was
407 exhibited when wearing 3.9 cm HHS compared with flat shoes. In terms of HHS experience,
408 experienced HHS wearers used better ankle strategy and COG directional control in postural
409 control than novices. In addition, experienced wearers perceived better postural stability and
410 showed better functional mobility. Our study suggests that women should choose low-heeled
411 shoes to prevent the risk of falls and HHS-related injuries.

412

413 *Acknowledgment*

414 Yiyang Chen contributed to conceptualization, methodology, formal analysis, investigation, and
415 writing - Original Draft. Lin Wang contributed to conceptualization, methodology, and
416 supervision. Jing Xian Li participated in conceptualization and writing - Review & Editing.
417 The authors appreciate the kind participation of all the subjects.

418

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Table 1 (on next page)

Six testing conditions of SOT

1 **Table 1:**

2 **Six testing conditions of SOT.**

Condition	Eyes	Support Surface	Vision	Anticipated Sensory Systems
1	Open	Fixed	Fixed	Somatosensory
2	Closed	Fixed	Fixed	Somatosensory
3	Open	Fixed	Sway referenced	Somatosensory
4	Open	Sway referenced	Fixed	Vision and vestibular
5	Closed	Sway referenced	Fixed	Vestibular
6	Open	Sway referenced	Sway referenced	Vestibular

3

Table 2 (on next page)

Demographic data of the participants

BMI, Body Mass Index; *, inexperienced vs. experienced HHS wearers, $p < 0.05$.

1 **Table 2:**2 **Demographic data of the participants.**

	Inexperienced HHS wearers (N=21)	Experienced HHS wearers (N=20)
Age (years)	25.1±1.6	23.1±2.2
Height (cm)	1.6±0.1	1.6±0.1
Weight (Kg)	57.5±7.9	56.3±6.9
BMI (Kg/m ²)	21.6±2.4	21.1±2.6
HHS wearing frequency (hours/week)	2.2±4.6	28.3±10.1*

3 Note: BMI, Body Mass Index; *, inexperienced vs. experienced HHS wearers, $p < 0.05$.

Table 3(on next page)

Comparison of outcome measures (means \pm SD) in SOT for four HHS in inexperienced and experienced groups

SOM, somatosensory score; VIS, visual score; VEST, vestibular score; *, Inexperienced vs. experienced HHS wearers, $p < 0.05$.

1 **Table 3:**2 **Comparison of outcome measures (means \pm SD) in SOT for four HHS in inexperienced and experienced groups.**

	Inexperienced HHS wearers (N=21)				Experienced HHS wearers (N=20)				<i>p</i> values		
	0.8 cm	3.9 cm	7 cm	10.1 cm	0.8 cm	3.9 cm	7 cm	10.1 cm	Within groups	Between groups	Two-way interaction
Equilibrium score											
C1	93.02 \pm 3.72	93.40 \pm 2.82	92.46 \pm 3.36	91.52 \pm 2.40	93.58 \pm 2.54	93.57 \pm 2.03	92.80 \pm 2.61	91.37 \pm 2.39	<0.001	0.735	0.877
C2	90.76 \pm 2.58	91.20 \pm 4.21	89.44 \pm 4.24	87.86 \pm 4.25	91.37 \pm 2.76	91.55 \pm 2.59	90.83 \pm 1.71	87.97 \pm 4.65	<0.001	0.473	0.672
C3	89.89 \pm 4.42	89.91 \pm 3.99	88.86 \pm 4.59	86.52 \pm 4.34	91.25 \pm 3.21	91.08 \pm 2.76	89.57 \pm 4.01	87.95 \pm 4.61	<0.001	0.226	0.921
C4	85.35 \pm 10.46	88.19 \pm 9.99	87.78 \pm 7.44	89.95 \pm 3.40	88.93 \pm 8.69	89.62 \pm 6.08	90.00 \pm 4.83	89.55 \pm 4.78	0.187	0.340	0.425
C5	80.11 \pm 10.37	79.56 \pm 9.39	81.14 \pm 6.44	80.56 \pm 4.78	81.82 \pm 7.81	79.62 \pm 9.01	80.78 \pm 5.45	81.42 \pm 6.27	0.563	0.763	0.799
C6	72.97 \pm 10.87	76.81 \pm 9.46	77.25 \pm 9.37	80.90 \pm 5.23	76.70 \pm 12.27	75.65 \pm 9.80	79.10 \pm 11.12	85.01 \pm 4.80	<0.001	0.358	0.292
COMP	83.52 \pm 7.35	84.86 \pm 5.94	84.86 \pm 5.70	84.52 \pm 3.16	85.85 \pm 6.33	85.20 \pm 4.70	85.95 \pm 4.84	85.15 \pm 5.09	0.776	0.463	0.533
Strategy score											
C1	95.06 \pm 2.47	84.86 \pm 5.94	84.86 \pm 5.70	84.52 \pm 3.16	95.58 \pm 1.34	95.90 \pm 1.18	94.98 \pm 1.73	94.13 \pm 1.82	<0.001	0.318	0.900
C2	93.90 \pm 2.34	93.40 \pm 2.82	92.46 \pm 3.36	91.52 \pm 2.40	94.78 \pm 1.64	94.92 \pm 1.57	93.92 \pm 1.39	90.98 \pm 3.55	<0.001	0.145	0.701
C3	94.17 \pm 2.01	91.20 \pm 4.21	89.44 \pm 4.24	87.86 \pm 4.25	95.30 \pm 1.11*	95.37 \pm 1.11*	94.22 \pm 2.03	93.17 \pm 1.91*	<0.001	0.002	0.278
C4	89.24 \pm 3.40	89.91 \pm 3.99	88.86 \pm 4.59	86.52 \pm 4.34	90.58 \pm 2.44	90.70 \pm 2.78	90.03 \pm 2.30	89.73 \pm 2.73	0.036	0.104	0.837
C5	85.05 \pm 4.37	88.19 \pm 9.99	87.78 \pm 7.44	89.95 \pm 3.40	87.22 \pm 2.76	85.50 \pm 5.02	84.70 \pm 3.42	84.68 \pm 2.18*	<0.001	0.032	0.061
C6	84.44 \pm 4.33	79.56 \pm 9.39	81.14 \pm 6.44	80.56 \pm 4.78	86.87 \pm 3.55	87.10 \pm 2.54*	85.27 \pm 5.16	85.02 \pm 4.80*	0.002	0.020	0.235
Sensory analysis score											
SOM	97.86 \pm 3.14	97.62 \pm 3.32	96.81 \pm 3.09	96.19 \pm 3.93	97.90 \pm 2.29	98.05 \pm 1.82	98.05 \pm 2.39	96.40 \pm 3.95	0.031	0.450	0.756
VIS	91.71 \pm 9.56	94.48 \pm 9.42	94.90 \pm 6.06	98.57 \pm 3.60	95.20 \pm 9.05	95.95 \pm 6.08	97.10 \pm 4.12	97.95 \pm 4.37	0.010	0.247	0.484
VEST	86.10 \pm 10.24	85.10 \pm 9.08	87.62 \pm 5.95	88.24 \pm 4.89	87.45 \pm 7.57	85.10 \pm 9.57	87.15 \pm 4.98	89.20 \pm 6.70	0.097	0.781	0.872

3 Note: SOM, somatosensory score; VIS, visual score; VEST, vestibular score; *, Inexperienced vs. experienced HHS wearers, $p < 0.05$.

4

Table 4(on next page)

Comparison of outcome measures (means \pm SD) in MCT for four HHS in inexperienced and experienced groups

COMP, composite score; B, backward; F, forward; S, small; M, medium; L, large; *, inexperienced vs. experienced HHS wearers, $p < 0.05$.

1 **Table 4:**2 **Comparison of outcome measures (means \pm SD) in MCT for four HHS in inexperienced and experienced groups.**

		Inexperienced HHS wearers (N=21)				Experienced HHS wearers (N=20)				<i>p</i> values		
		0.8 cm	3.9 cm	7 cm	10.1 cm	0.8 cm	3.9 cm	7 cm	10.1 cm	Within groups	Between groups	Two-way interaction
Latency COMP (milliseconds)												
		128.39 \pm 8.27	128.39 \pm 7.82	126.50 \pm 5.29	126.39 \pm 4.98	131.90 \pm 11.14	134.25 \pm 15.11	129.20 \pm 9.02	128.80 \pm 7.30	0.044	0.146	0.576
Amplitude scaling												
B	S	1.72 \pm 1.02	2.28 \pm 1.49	2.44 \pm 1.46	2.83 \pm 1.15	1.80 \pm 1.47	1.75 \pm 1.12	2.35 \pm 1.63	3.00 \pm 1.56	<0.001	0.759	0.579
	M	4.06 \pm 2.24	4.61 \pm 2.89	5.06 \pm 2.36	4.61 \pm 1.88	3.20 \pm 1.94	4.10 \pm 2.29	4.40 \pm 2.09	4.45 \pm 2.24	0.015	0.359	0.798
	L	6.33 \pm 2.95	6.78 \pm 3.34	6.67 \pm 3.12	6.78 \pm 2.44	4.90 \pm 2.77	5.65 \pm 3.00	5.65 \pm 2.41	6.50 \pm 2.31	0.082	0.359	0.798
F	S	2.28 \pm 1.71	2.78 \pm 1.52	3.28 \pm 1.74	3.89 \pm 1.32	2.05 \pm 1.15	1.90 \pm 1.02	2.25 \pm 1.41	3.45 \pm 1.64	<0.001	0.089	0.314
	M	4.39 \pm 1.97	5.44 \pm 1.85	5.78 \pm 1.80	6.94 \pm 1.86	3.70 \pm 1.81	4.90 \pm 2.29	5.15 \pm 2.41	6.55 \pm 2.80	<0.001	0.337	0.970
	L	6.83 \pm 2.33	7.44 \pm 2.59	7.78 \pm 0.56	8.44 \pm 2.18	5.65 \pm 2.76	7.10 \pm 2.69	8.15 \pm 3.10	8.20 \pm 3.02	<0.001	0.622	0.328

3 Note: COMP, composite score; B, backward; F, forward; S, small; M, medium; L, large; *, inexperienced vs. experienced HHS
 4 wearers, $p < 0.05$.

Figure 1

(A) Size of the heel base; (B) experimental shoes with different HH

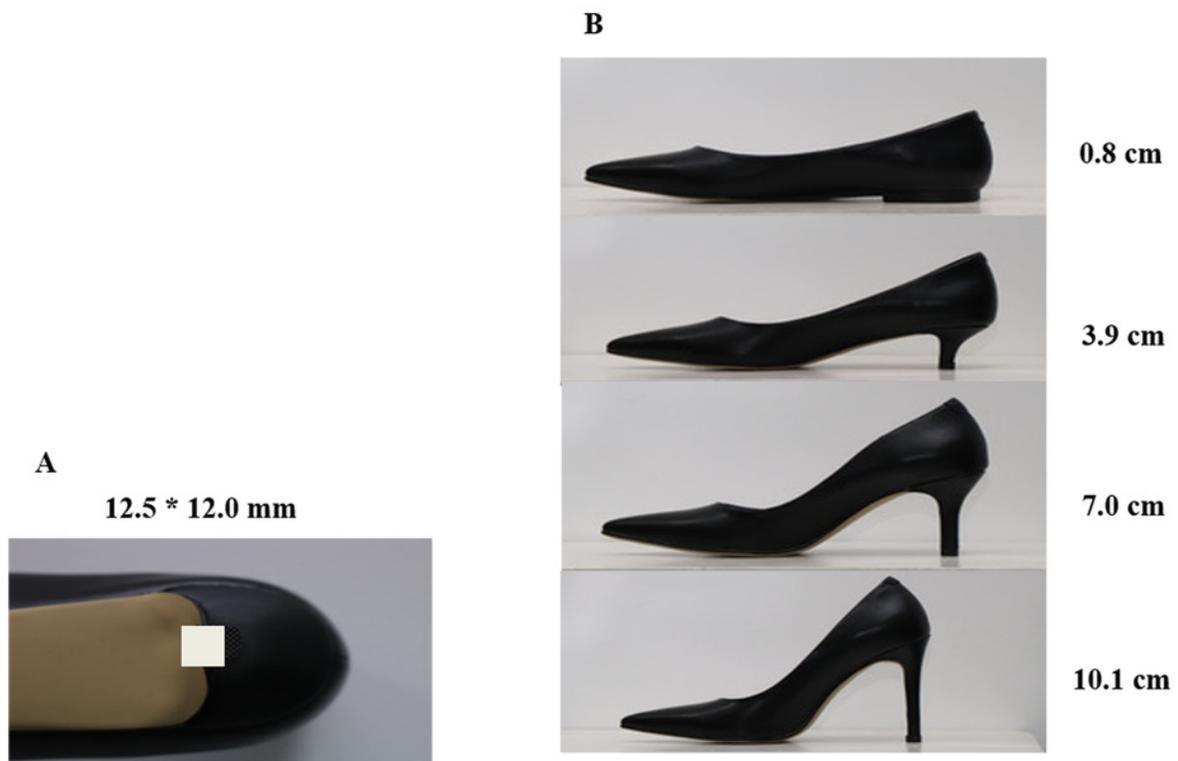


Figure 2

(A) COG movement velocity of experienced and inexperienced HHS wearers in four HHs;
 (B) directional control of experienced and inexperienced HHS wearers in four HHs.

b, 7 cm vs. 0.8 cm, $p < 0.05$; c, 10.1 cm vs. 0.8 cm, $p < 0.05$; d, 7 cm vs. 3.9 cm, $p < 0.05$; e, 10.1 cm vs. 3.9 cm, $p < 0.05$; f, 10.1 cm vs. 7 cm, $p < 0.05$; *, inexperienced vs. experienced HHS wearers, $p < 0.05$; COG, center of gravity; HHS, high heel shoes; HH, heel height.

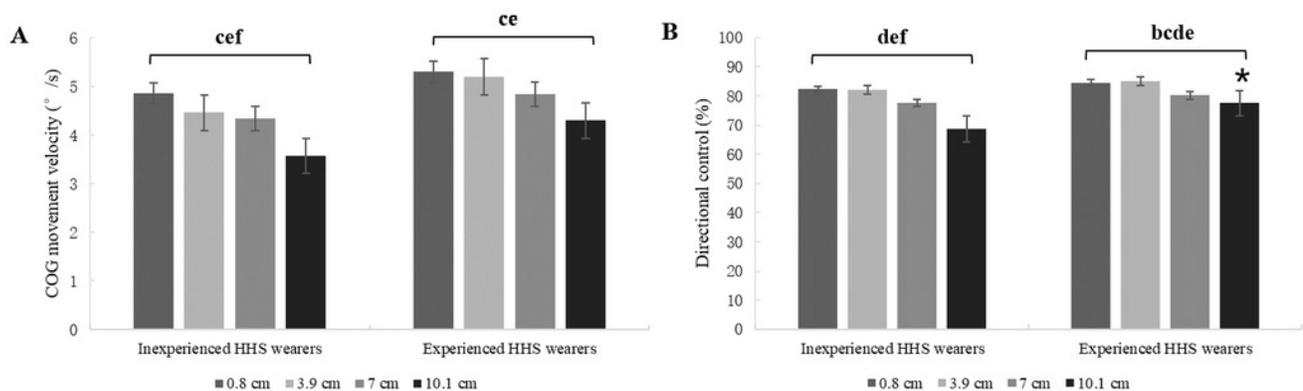


Figure 3

(A) Completion time of TUGT in experienced and inexperienced HHS wearers in four HHs; (B) distance of FRT in experienced and inexperienced HHS wearers in four HHs

a, 3.9 cm vs. 0.8 cm, $p < 0.05$; b, 7 cm vs. 0.8 cm, $p < 0.05$; c, 10.1 cm vs. 0.8 cm, $p < 0.05$;
 d, 7 cm vs. 3.9 cm, $p < 0.05$; e, 10.1 cm vs. 3.9 cm, $p < 0.05$; f, 10.1 cm vs. 7 cm, $p < 0.05$;
 *, inexperienced vs. experienced HHS wearers, $p < 0.05$; TUGT, timed up and go test; FRT, functional reach test; HHS, high heel shoes; HH, heel height.

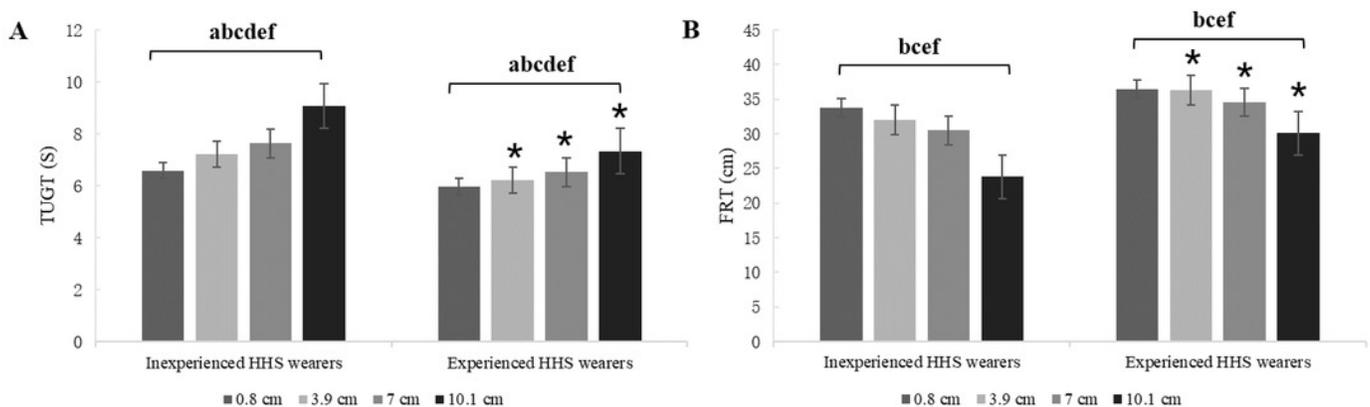


Figure 4

Visual analog scaling of perceived stability among experienced and inexperienced HHS wearers in four HHs

b, 7 cm vs. 0.8 cm, $p < 0.05$; c, 10.1 cm vs. 0.8 cm, $p < 0.05$; d, 7 cm vs. 3.9 cm, $p < 0.05$; e, 10.1 cm vs. 3.9 cm, $p < 0.05$; f, 10.1 cm vs. 7 cm, $p < 0.05$; *, inexperienced vs. experienced HHS wearers, $p < 0.05$; HHS, high heel shoes; HH, heel height.

